

## 4-CHANNEL MOTOR DRIVER WITH POWER CONTROLLER

AM5901A

### General Description

The AM5901A is a 4-channel motor driver with power controller that includes the reset, battery charge and reduced voltage detection circuits required for portable CD/MP3/VCD players on a single chip.

This kind of IC is provided with lower startup voltage and power consumption than similar products, its driver block power supply uses on-chip switching regulator, making this component an ideal choice for low-power sets. It is used in mini portable compact disc players (CDP), portable mini disc players (MD), disc-man or other portable compact disc media.

The AM5901A is available in PQFP-44 and LQFP-44 packages.

### Features

- 4-channel H-bridge Driver
- Built-in DC/DC Converter Control Circuit
- Built-in Reset Circuit
- Built-in Reduced Voltage Detection Circuit
- Built-in Battery Charging Circuit
- Built-in General-purpose Operational Amplifier
- Built-in Thermal Shutdown Circuit
- Low Power Consumption

### Applications

- Portable Compact Disc Player (CDP)
- Portable Mini Disc Player
- Portable Disc-man
- Portable CD/MP3/VCD
- Other Portable Compact Disc Media

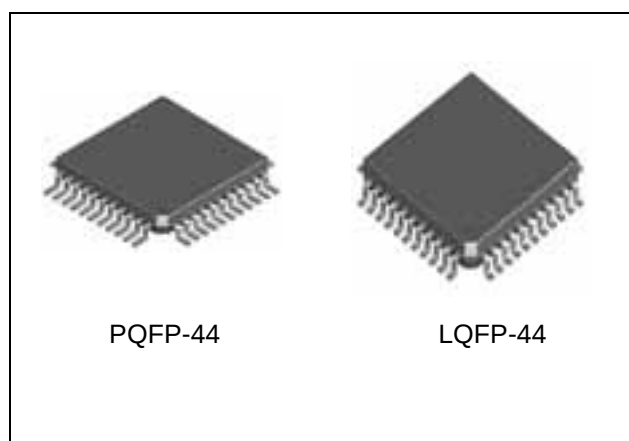


Figure 1. Package Types of AM5901A

# 4-CHANNEL MOTOR DRIVER WITH POWER CONTROLLER

AM5901A

## Pin Configuration

F44 Package  
(PQFP-44)

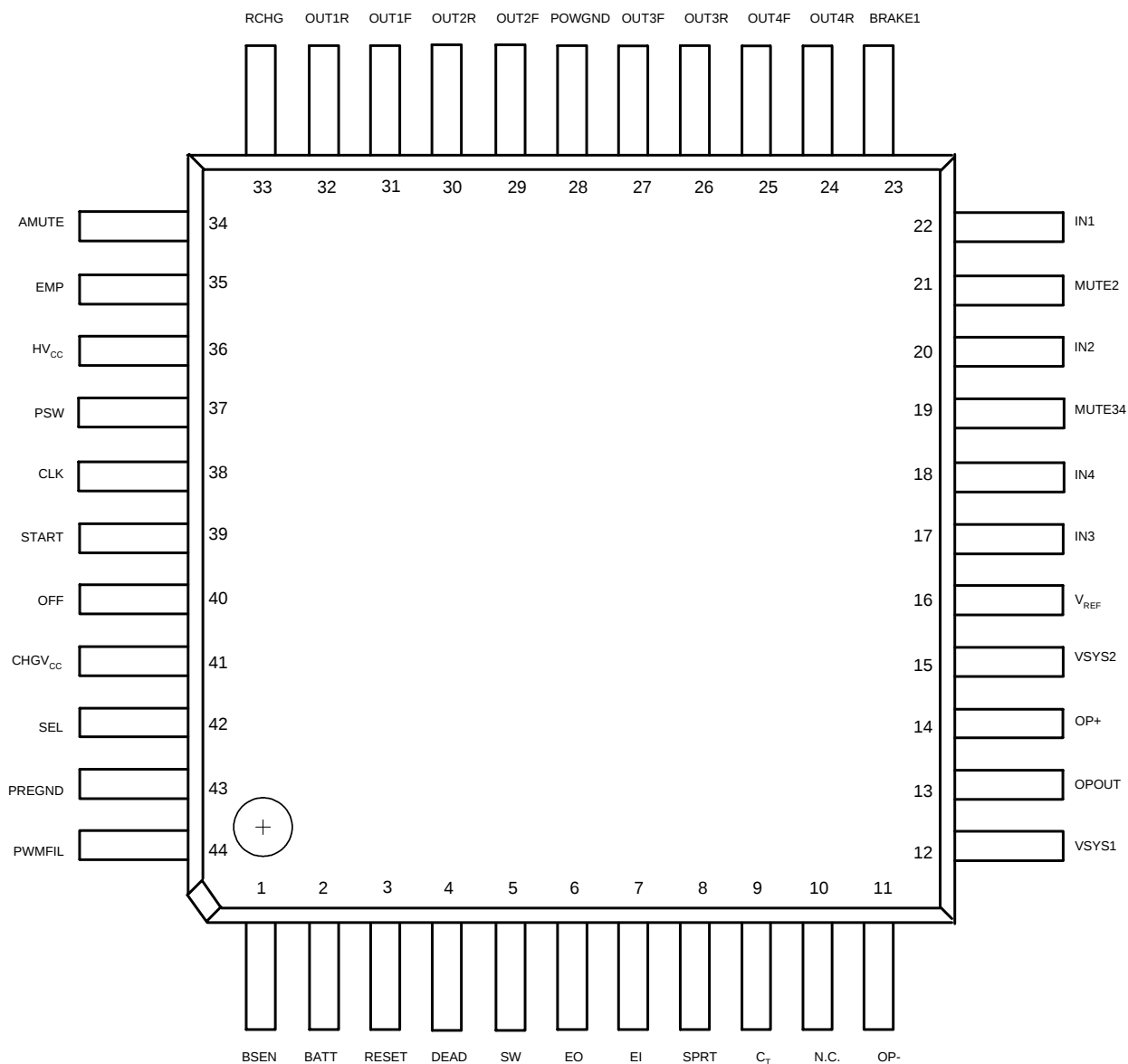


Figure 2. Pin Configuration of AM5901A (Top View)

# 4-CHANNEL MOTOR DRIVER WITH POWER CONTROLLER

AM5901A

## Pin Configuration (Continued)

LF44 Packages  
(LQFP-44)

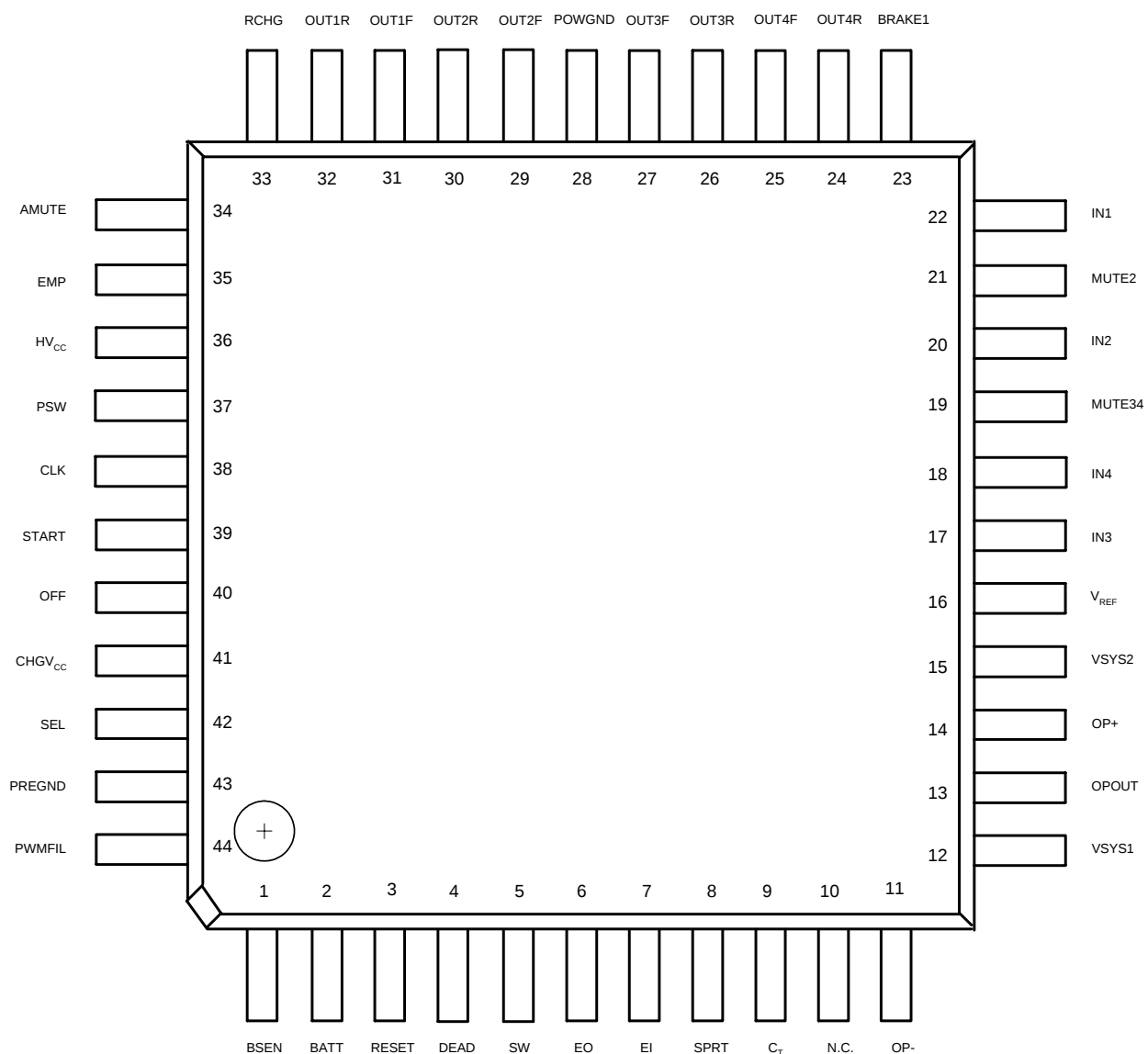


Figure 3. Pin Configuration of AM5901A (Top View)

**4-CHANNEL MOTOR DRIVER WITH POWER CONTROLLER****AM5901A****Pin Description**

| Pin Number | Pin Name           | Function                             |
|------------|--------------------|--------------------------------------|
| 1          | BSEN               | Battery voltage monitor              |
| 2          | BATT               | Battery power supply input           |
| 3          | RESET              | Reset detection output               |
| 4          | DEAD               | Dead-time setting                    |
| 5          | SW                 | Booster transistor drive             |
| 6          | EO                 | Error amplifier output               |
| 7          | EI                 | Error amplifier input                |
| 8          | SPRT               | Short-circuit protection setting     |
| 9          | C <sub>T</sub>     | Triangular wave output               |
| 10         | N.C.               | Nothing connected                    |
| 11         | OP-                | Operational amplifier negative input |
| 12         | VSYS1              | Control circuit power supply input   |
| 13         | OPOUT              | Operational amplifier output         |
| 14         | OP+                | Operational amplifier positive input |
| 15         | VSYS2              | Pre-driver power supply input        |
| 16         | V <sub>REF</sub>   | Reference power supply input         |
| 17         | IN3                | CH3 control signal input             |
| 18         | IN4                | CH4 control signal input             |
| 19         | MUTE34             | CH3/CH4 mute                         |
| 20         | IN2                | CH2 control signal input             |
| 21         | MUTE2              | CH2 mute                             |
| 22         | IN1                | CH1 control signal input             |
| 23         | BRAKE1             | CH1 brake                            |
| 24         | OUT4R              | CH4 negative output                  |
| 25         | OUT4F              | CH4 positive output                  |
| 26         | OUT3R              | CH3 negative output                  |
| 27         | OUT3F              | CH3 positive output                  |
| 28         | POWGND             | Power unit power ground              |
| 29         | OUT2F              | CH2 positive output                  |
| 30         | OUT2R              | CH2 negative output                  |
| 31         | OUT1F              | CH1 positive output                  |
| 32         | OUT1R              | CH1 negative output                  |
| 33         | RCHG               | Charging current setting             |
| 34         | AMUTE              | Reset inversion output               |
| 35         | EMP                | "Empty" detection output             |
| 36         | HV <sub>CC</sub>   | H-bridge power supply input          |
| 37         | PSW                | PWM transistor drive                 |
| 38         | CLK                | External clock synchronization input |
| 39         | START              | Boost DC/DC converter starting       |
| 40         | OFF                | Boost DC/DC converter OFF            |
| 41         | CHGV <sub>cc</sub> | Charging circuit power supply input  |
| 42         | SEL                | "Empty" detection level switching    |
| 43         | PREGND             | Pre-unit power supply ground         |
| 44         | PWMFIL             | PWM phase compensation               |



# 4-CHANNEL MOTOR DRIVER WITH POWER CONTROLLER

AM5901A

## Functional Block Diagram

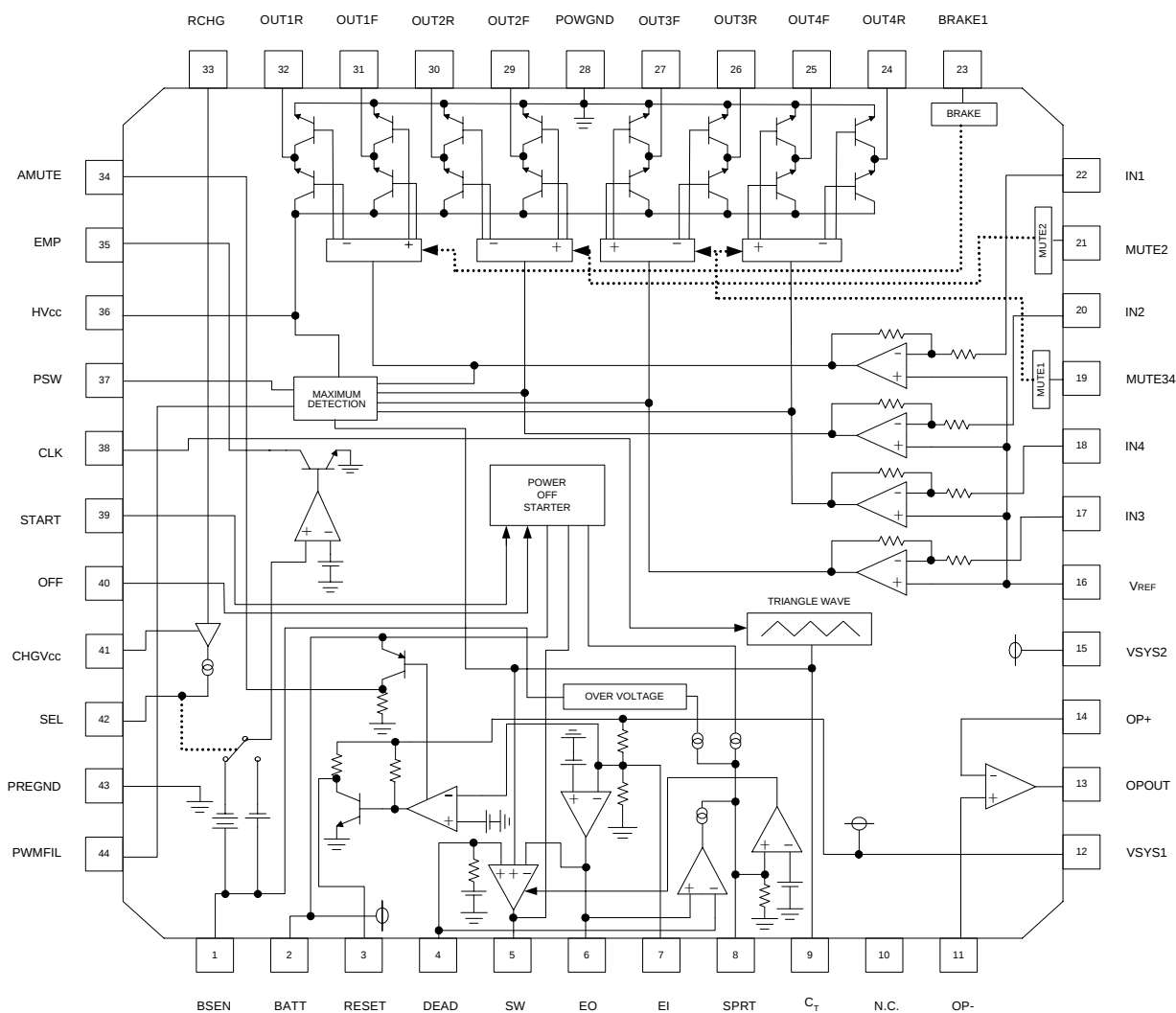
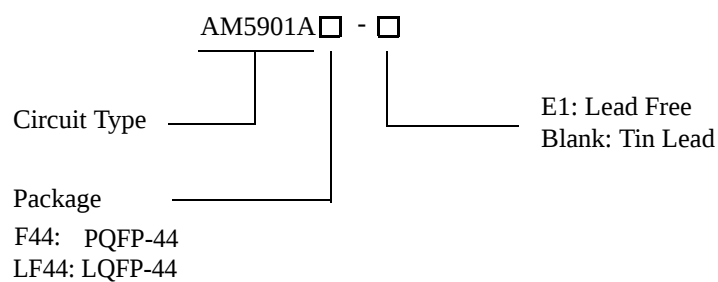


Figure 4. Functional Block Diagram of AM5901A

## 4-CHANNEL MOTOR DRIVER WITH POWER CONTROLLER

AM5901A

### Ordering Information



| Package | Temperature Range | Part Number |                | Marking ID  |                | Packing Type |
|---------|-------------------|-------------|----------------|-------------|----------------|--------------|
|         |                   | Tin Lead    | Lead Free      | Tin Lead    | Lead Free      |              |
| PQFP-44 | 0 to 70°C         | AM5901AF44  | AM5901AF44-E1  | AM5901AF44  | AM5901AF44-E1  | Tray         |
| LQFP-44 | 0 to 70°C         | AM5901ALF44 | AM5901ALF44-E1 | AM5901ALF44 | AM5901ALF44-E1 | Tray         |

BCD Semiconductor's Pb-free products, as designated with "E1" suffix in the part number, are RoHS compliant.

## 4-CHANNEL MOTOR DRIVER WITH POWER CONTROLLER

AM5901A

### Absolute Maximum Ratings (Note 1)

| Parameter                      | Symbol    | Value        | Unit |
|--------------------------------|-----------|--------------|------|
| Supply Voltage                 | $V_{CC}$  | 13.5         | V    |
| Driver Output Current          | $I_O$     | 500          | mA   |
| Power Dissipation              | $P_D$     | 625 (Note 2) | mW   |
| Operating Junction Temperature | $T_J$     | 150          | °C   |
| Storage Temperature            | $T_{STG}$ | -55 to 150   | °C   |

Note 1: Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "Recommended Operating Conditions" is not implied. Exposure to "Absolute Maximum Ratings" for extended periods may affect device reliability.

Note 2: Power dissipation is reduced by 5mW for each increase in  $T_A$  of 1°C over 25°C.

### Recommended Operating Conditions

| Parameter                             | Symbol               | Min | Typ | Max  | Unit |
|---------------------------------------|----------------------|-----|-----|------|------|
| Control Circuit Power Supply Voltage  | VSYS1                | 2.7 | 3.2 | 5.5  | V    |
| Pre-driver Power Supply Voltage       | VSYS2                | 2.7 | 3.2 | 5.5  | V    |
| H-bridge Power Supply Voltage         | $HV_{CC}$            |     | PWM | BATT | V    |
| Power Unit Power Supply Voltage       | BATT<br>( $V_{CC}$ ) | 1.6 | 2.4 | 8    | V    |
| Charging Circuit Power Supply Voltage | CHGV $_{CC}$         | 3.0 | 4.5 | 8    | V    |
| Operating Temperature                 | $T_A$                | 0   | 25  | 70   | °C   |

## 4-CHANNEL MOTOR DRIVER WITH POWER CONTROLLER

AM5901A

### Electrical Characteristics

(Typicals and limits apply for  $T_A=25^\circ\text{C}$ ,  $BATT=2.4\text{V}$ ,  $VSYS1=VSYS2=3.2\text{V}$ ,  $V_{REF}=1.6\text{V}$ ,  $CHGV_{CC}=0$ ,  $CLK=88.2\text{kHz}$ , unless otherwise specified.)

| Parameter                                    | Symbol          | Conditions                                                         | Min  | Typ  | Max  | Unit             |
|----------------------------------------------|-----------------|--------------------------------------------------------------------|------|------|------|------------------|
| <b>Common Section</b>                        |                 |                                                                    |      |      |      |                  |
| BATT Standby Current                         | $I_{ST}$        | $BATT=9\text{V}$ , $VSYS1=VSYS2=V_{REF}=0\text{V}$                 |      | 0    | 5    | $\mu\text{A}$    |
| BATT Supply Current at No Load               | $I_{BAT}$       | $HV_{CC}=0.45\text{V}$ , $MUTE34=3.2\text{V}$                      |      | 2.5  | 4    | $\text{mA}$      |
| VSYS1 Supply Current at No Load              | $I_{SYS1}$      | $HV_{CC}=0.45\text{V}$ , $MUTE34=3.2\text{V}$ , $EI=0\text{V}$     |      | 4.7  | 6.4  | $\text{mA}$      |
| VSYS2 Supply Current at No Load              | $I_{SYS2}$      | $HV_{CC}=0.45\text{V}$ , $MUTE34=3.2\text{V}$                      |      | 4.1  | 5.5  | $\text{mA}$      |
| CHGV <sub>CC</sub> Supply Current at No Load | $I_{CHGVCC}$    | $CHGV_{CC}=4.5\text{V}$ , $R_{OUT}=OPEN$                           |      | 0.65 | 2    | $\text{mA}$      |
| <b>H-bridge Driver Section</b>               |                 |                                                                    |      |      |      |                  |
| Voltage Gain (CH1,3,4)                       | $G_{VC134}$     |                                                                    | 12   | 14   | 16   | $\text{dB}$      |
| Voltage Gain (CH2)                           | $G_{VC2}$       |                                                                    | 21.5 | 23.5 | 25.5 | $\text{dB}$      |
| Gain Error by Polarity                       | $\Delta G_{VC}$ |                                                                    | -2   | 0    | 2    | $\text{dB}$      |
| IN Pin Input Resistance (CH1,3,4)            | $R_{IN134}$     | $IN=1.7$ and $1.8\text{V}$                                         | 9.6  | 11   | 14.4 | $\text{k}\Omega$ |
| IN Pin Input Resistance (CH2)                | $R_{IN2}$       | $IN=1.7$ and $1.8\text{V}$                                         | 6.6  | 7.5  | 9.9  | $\text{k}\Omega$ |
| Maximum Output Voltage                       | $V_{OUT}$       | $R_L=8\Omega$ , $HV_{CC}=BATT=4\text{V}$ , $IN=0$ to $3.2\text{V}$ | 1.9  | 2.1  |      | $\text{V}$       |
| Lower Transistor Saturated Voltage           | $V_{SATL}$      | $I_O=-300\text{mA}$ , $IN=0$ and $3.2\text{V}$                     |      | 240  | 400  | $\text{mV}$      |
| Upper Transistor Saturated Voltage           | $V_{SATU}$      | $I_O=300\text{mA}$ , $IN=0$ and $3.2\text{V}$                      |      | 240  | 400  | $\text{mV}$      |
| Input Offset Voltage                         | $V_{IO}$        |                                                                    | -8   |      | 8    | $\text{mV}$      |
| Output Offset Voltage (CH1,3,4)              | $V_{OO134}$     | $V_{REF}=IN=1.6\text{V}$                                           | -54  | 0    | 54   | $\text{mV}$      |
| Output Offset Voltage (CH2)                  | $V_{OO2}$       | $V_{REF}=IN=1.6\text{V}$                                           | -134 | 0    | 134  | $\text{mV}$      |
| Dead Zone                                    | $V_{DB}$        |                                                                    | -15  | 0    | 15   | $\text{mV}$      |
| BRAKE1 ON Threshold Voltage                  | $V_{BRON}$      | $IN1=1.8\text{V}$                                                  | 2    |      |      | $\text{V}$       |
| BRAKE1 OFF Threshold Voltage                 | $V_{BROFF}$     | $IN1=1.8\text{V}$                                                  |      |      | 0.8  | $\text{V}$       |
| MUTE2 ON Threshold Voltage                   | $V_{M2ON}$      | $IN2=1.8\text{V}$                                                  | 2    |      |      | $\text{V}$       |
| MUTE2 OFF Threshold Voltage                  | $V_{M2OFF}$     | $IN2=1.8\text{V}$                                                  |      |      | 0.8  | $\text{V}$       |



# 4-CHANNEL MOTOR DRIVER WITH POWER CONTROLLER

AM5901A

## Electrical Characteristics (Continued)

| Parameter                               | Symbol       | Conditions                                                                                           | Min  | Typ  | Max  | Unit |
|-----------------------------------------|--------------|------------------------------------------------------------------------------------------------------|------|------|------|------|
| MUTE34 ON Threshold Voltage             | $V_{M34ON}$  | IN3=IN4=1.8V                                                                                         |      |      | 0.8  | V    |
| MUTE34 OFF Threshold Voltage            | $V_{M34OFF}$ | IN3=IN4=1.8V                                                                                         | 2.0  |      |      | V    |
| $V_{REF}$ ON Threshold Voltage          | $V_{REFON}$  | IN1=IN2=IN3=IN4=1.8V                                                                                 | 1.2  |      |      | V    |
| $V_{REF}$ OFF Threshold Voltage         | $V_{REFOFF}$ | IN1=IN2=IN3=IN4=1.8V                                                                                 |      |      | 0.8  | V    |
| BRAKE 1 Brake Current                   | $I_{BRAKE1}$ | Current difference between BRAKE1 pin "H" and "L"                                                    | 4    | 7    | 10   | mA   |
| <b>PWM Power Supply Driving Section</b> |              |                                                                                                      |      |      |      |      |
| PWM Sink Current                        | $I_{PSW}$    | IN1=2.1V                                                                                             | 7.9  | 13   | 17.5 | mA   |
| HV <sub>CC</sub> Level Shift Voltage    | $V_{SHIF}$   | IN1=1.8V, HV <sub>CC</sub> -OUT1F                                                                    | 0.25 | 0.45 | 0.55 | V    |
| HV <sub>CC</sub> Leak Current           | $I_{HLK}$    | HV <sub>CC</sub> =9V,<br>V <sub>SY1</sub> =V <sub>SY2</sub> =BATT=0V                                 |      | 0    | 11   | μA   |
| PWM Amplifier Transfer Gain             | $G_{PWM}$    | IN1=1.8V, HV <sub>CC</sub> =1.2 to 1.4V                                                              | 1/60 | 1/50 | 1/40 | 1/kΩ |
| <b>DC/DC Converter Section</b>          |              |                                                                                                      |      |      |      |      |
| <b>(Error Amplifier Section)</b>        |              |                                                                                                      |      |      |      |      |
| V <sub>SY1</sub> Pin Threshold Voltage  | $V_{SITH}$   |                                                                                                      | 3.05 | 3.2  | 3.35 | V    |
| EO Pin Output Voltage H                 | $V_{EOH}$    | EI=0.7V, I <sub>O</sub> =-80μA                                                                       | 1.4  | 1.6  |      | V    |
| EO Pin Output Voltage L                 | $V_{EOL}$    | EI=1.3V, I <sub>O</sub> =80μA                                                                        |      |      | 0.3  | V    |
| <b>(Short-circuit Protection)</b>       |              |                                                                                                      |      |      |      |      |
| SPRT Pin Voltage (Normal)               | $V_{SPR}$    | EI=1.3V                                                                                              |      | 0    | 0.1  | V    |
| SPRT Pin Current 1 EO=H                 | $I_{SPR1}$   | EI=0.7V                                                                                              | 6    | 10   | 16   | μA   |
| SPRT Pin Current 2 EO=L                 | $I_{SPR2}$   | EI=1.3V, OFF=0V                                                                                      | 12   | 20   | 32   | μA   |
| SPRT Pin Current 3 (Over-voltage)       | $I_{SPR3}$   | EI=1.3V, BATT=9.5V                                                                                   | 12   | 20   | 32   | μA   |
| SPRT Pin Impedance                      | $R_{SPR}$    |                                                                                                      | 175  | 220  | 265  | kΩ   |
| SPRT Pin Threshold Voltage              | $V_{SPTH}$   | EI=0.7, C <sub>T</sub> =0V                                                                           | 1.1  | 1.2  | 1.3  | V    |
| Over-voltage Protection Detect          | $V_{HVPR}$   | BSEN Pin Voltage,<br>pin 7=1.3V, pin 12=3.2V                                                         | 8    | 8.6  | 9    | V    |
| <b>(Transistor Driving Section)</b>     |              |                                                                                                      |      |      |      |      |
| SW Pin Output Voltage 1 H               | $V_{SW1H}$   | BATT=C <sub>T</sub> =1.5V, I <sub>O</sub> =-2mA,<br>V <sub>SY1</sub> =V <sub>SY2</sub> =0V, at start | 0.78 | 0.98 | 1.13 | V    |
| SW Pin Output Voltage 2 H               | $V_{SW2H}$   | C <sub>T</sub> =0V, I <sub>O</sub> =-10mA, EI=0.7V,<br>SPRT=0V                                       | 1    | 1.5  |      | V    |
| SW Pin Output Voltage 2 L               | $V_{SW2L}$   | C <sub>T</sub> =2V, I <sub>O</sub> =10mA                                                             |      | 0.3  | 0.45 | V    |
| SW Pin Oscillating Frequency 1          | $f_{SW1}$    | C <sub>T</sub> =470pF, V <sub>SY1</sub> =V <sub>SY2</sub> =0, at start                               | 65   | 80   | 95   | kHz  |
| SW Pin Oscillating Frequency 2          | $f_{SW2}$    | C <sub>T</sub> =470pF, CLK=0V                                                                        | 60   | 70   | 82   | kHz  |

# 4-CHANNEL MOTOR DRIVER WITH POWER CONTROLLER

AM5901A

## Electrical Characteristics (Continued)

| Parameter                             | Symbol       | Conditions                                                               | Min      | Typ  | Max          | Unit      |
|---------------------------------------|--------------|--------------------------------------------------------------------------|----------|------|--------------|-----------|
| SW Pin Oscillating Frequency 3        | $f_{SW3}$    | $C_T=470pF$                                                              |          | 88.2 |              | kHz       |
| SW Pin Minimum Pulse Width            | $T_{SWMIN}$  | $C_T=470pF$ , $EO=0.5\sim 0.7V$ Sweep                                    | 0.01     |      | 0.6          | $\mu s$   |
| Pulse Duty at Start                   | $D_{SW1}$    | $C_T=470pF$ , $V_{SYS1}=V_{SYS2}=0V$                                     | 40       | 50   | 60           | %         |
| Max Pulse Duty at Self-Running        | $D_{SW2}$    | $EI=0.7V$ , $C_T=470pF$ , $CLK=0V$ , $SPRT=1.1V$ , $START$ not connected | 70       | 80   | 90           | %         |
| Max Pulse Duty at CLK Synchronization | $D_{SW3}$    | $EI=0.7V$ , $C_T=470pF$ , $SPRT=1.1V$ , $START$ not connected            | 65       | 75   | 85           | %         |
| <b>(Dead Time Section)</b>            |              |                                                                          |          |      |              |           |
| DEAD Pin Impedance                    | $R_{DEAD}$   |                                                                          | 20       | 25   | 30           | $k\Omega$ |
| DEAD Pin Output Voltage               | $V_{DEAD}$   |                                                                          | 0.78     | 0.88 | 0.98         | V         |
| <b>(Interface Section)</b>            |              |                                                                          |          |      |              |           |
| OFF Pin Threshold Voltage             | $V_{OFTH}$   | $EI=1.3V$                                                                |          |      | $V_{SYS1-2}$ | V         |
| OFF Pin Bias Current                  | $I_{OFF}$    | $OFF=0V$                                                                 | 75       | 95   | 115          | $\mu A$   |
| START Pin ON Threshold Voltage        | $V_{STATH1}$ | $V_{SYS1}=V_{SYS2}=0V$ , $C_T=2V$                                        |          |      | BATT-1       | V         |
| START Pin OFF Threshold Voltage       | $V_{STATH2}$ | $V_{SYS1}=V_{SYS2}=0V$ , $C_T=2V$                                        | BATT-0.3 |      |              | V         |
| START Pin Bias Current                | $I_{START}$  | $START=0V$                                                               | 10       | 16   | 19           | $\mu A$   |
| CLK Pin Threshold Voltage H           | $V_{CLKTHH}$ |                                                                          | 2        |      |              | V         |
| CLK Pin Threshold Voltage L           | $V_{CLKTHL}$ |                                                                          |          |      | 0.8          | V         |
| CLK Pin Bias Current                  | $I_{CLK}$    | $CLK=3.2V$                                                               |          |      | 10           | $\mu A$   |
| <b>(Started Circuit Section)</b>      |              |                                                                          |          |      |              |           |
| Starter Switching Voltage             | $V_{STMM}$   | $V_{SYS1}=V_{SYS2}=0V$ to $3.2V$<br>$START=0V$                           | 2.3      | 2.5  | 2.7          | V         |
| Starter Switching Hysteresis Width    | $V_{SNHS}$   | $START=0V$                                                               | 18       | 200  | 300          | mV        |
| Discharge Release Voltage             | $V_{DIS}$    |                                                                          | 1.63     | 1.83 | 2.03         | V         |
| <b>(Empty Detection Section)</b>      |              |                                                                          |          |      |              |           |
| Empty Detection Voltage 1             | $V_{EMPT1}$  | $V_{SEL}=0V$                                                             | 2.1      | 2.2  | 2.35         | V         |
| Empty Detection Voltage 2             | $V_{EMPT2}$  | $I_{SEL}=-2\mu A$                                                        | 1.7      | 1.8  | 1.945        | V         |
| Empty Detection Hysteresis Width1     | $V_{EMHS1}$  | $V_{SEL}=0V$                                                             | 8        | 50   | 100          | mV        |
| Empty Detection Hysteresis Width2     | $V_{EMHS2}$  | $I_{SEL}=-2\mu A$                                                        | 8        | 50   | 100          | mV        |
| EMP Pin Output Voltage                | $V_{EMP}$    | $I_O=1mA$ , $BSEN=1V$                                                    |          |      | 0.5          | V         |
| EMP Pin Output Leak Current           | $I_{EMPL}$   | $BSEN=2.4V$                                                              |          |      | 1            | $\mu A$   |
| BSEN Pin Input Resistance             | $R_{BSEN}$   | $V_{SEL}=0V$                                                             | 17       | 23   | 27           | $k\Omega$ |



# 4-CHANNEL MOTOR DRIVER WITH POWER CONTROLLER

AM5901A

## Electrical Characteristics (Continued)

| Parameter                              | Symbol       | Conditions                                                            | Min      | Typ  | Max   | Unit       |
|----------------------------------------|--------------|-----------------------------------------------------------------------|----------|------|-------|------------|
| BSEN Pin Leak Current                  | $I_{BSNL}$   | VSYS1=VSYS2=0V, BSEN=4.5V                                             |          |      | 1     | $\mu A$    |
| SEL Pin Detection Voltage              | $V_{SELTH}$  | $V_{SELTH}=BATT-SEL$ , BSEN=2V                                        | 1.35     |      |       | V          |
| SEL Pin Detection Current              | $I_{SELT}$   |                                                                       | -15      |      |       | $\mu A$    |
| <b>(Reset Section)</b>                 |              |                                                                       |          |      |       |            |
| VSYS1 Reset Threshold Voltage Ratio    | $H_{SRT}$    | Ratio of VSYS1 voltage and error-amp threshold voltage                | 82.98    | 90   | 97.2  | %          |
| RESET Detection Hysteresis Width       | $V_{RSTHS}$  |                                                                       | 10       | 50   | 100   | mV         |
| RESET Pin Output Voltage               | $V_{RST}$    | $I_O=1mA$ , VSYS1=VSYS2=2.8V                                          |          |      | 0.5   | V          |
| RESET Pin Pull-up Resistance           | $R_{RST}$    |                                                                       | 72       | 90   | 108   | $k\Omega$  |
| AMUTE Pin Output Voltage 1             | $V_{AMT1}$   | $I_O=-1mA$ , VSYS1=VSYS2=2.8V                                         | BATT-0.4 |      | BATT  | V          |
| AMUTE Pin Output Voltage 2             | $V_{AMT2}$   | $I_O=-1mA$ , START=0V, VSYS1=VSYS2=0V                                 | BATT-0.4 |      | BATT  | V          |
| AMUTE Pin Pull Down Resistance         | $R_{AMT}$    |                                                                       | 77       | 95   | 113   | $k\Omega$  |
| <b>(Operational Amplifier Section)</b> |              |                                                                       |          |      |       |            |
| Input Bias Current                     | $I_{BIAS}$   | OP+=1.6V                                                              |          |      | 300   | nA         |
| Input Offset Voltage                   | $V_{IOOP}$   |                                                                       | -5.5     | 0    | 5.5   | mV         |
| High Level Output Voltage              | $V_{OHOP}$   | $R_L=OPEN$                                                            | 2.8      |      |       | V          |
| Low Level Output Voltage               | $V_{OLOP}$   | $R_L=OPEN$                                                            |          |      | 0.2   | V          |
| Output Driver Current (Source)         | $I_{SOU}$    | Output shorted to GND By 50 $\Omega$                                  |          | -6.5 | -3    | mA         |
| Output Driver Current (Sink)           | $I_{SIN}$    | Output shorted to VSYS By 50 $\Omega$                                 | 0.3      | 0.7  | 2.2   | mA         |
| Open Loop Voltage GAIN                 | $G_{VO}$     | $V_{IN}=-75dBV$ , f=1kHz                                              |          | 70   |       | dB         |
| Slew Rate                              | SR           |                                                                       |          | 0.5  |       | V/ $\mu s$ |
| <b>(Charging Circuit Section)</b>      |              |                                                                       |          |      |       |            |
| SEL Pin Charging Current               | $I_{SEL}$    | CHGV <sub>CC</sub> =4.5V, RCHG=1.8k $\Omega$ , V <sub>SEL</sub> =4.5V | 80       | 150  | 250   | mA         |
| RCHG Pin Bias Voltage                  | $V_{RCHG}$   | CHGV <sub>CC</sub> =4.5V, RCHG=1.8k $\Omega$                          | 0.745    | 0.81 | 0.960 | V          |
| RCHG Pin Output Resistance             | $R_{RCHG}$   | CHGV <sub>CC</sub> =4.5V, RCHG=0.5 and 0.6V                           | 0.75     | 0.95 | 1.2   | $k\Omega$  |
| SEL Pin Leak Current 1                 | $I_{SELLK1}$ | CHGV <sub>CC</sub> =4.5V, RCHG=OPEN BATT=4.5V                         |          |      | 1.2   | $\mu A$    |
| SEL Pin Leak Current 2                 | $I_{SELLK2}$ | CHGV <sub>CC</sub> =0.6V, RCHG=1.8k $\Omega$ BATT=4.5V                |          |      | 1.2   | $\mu A$    |
| SEL Pin Saturation Voltage             | $V_{SELCG}$  | CHGV <sub>CC</sub> =4.5V, $I_O=300mA$ , RCHG=0 $\Omega$               |          | 0.45 | 1     | V          |

## Typical Performance Characteristics

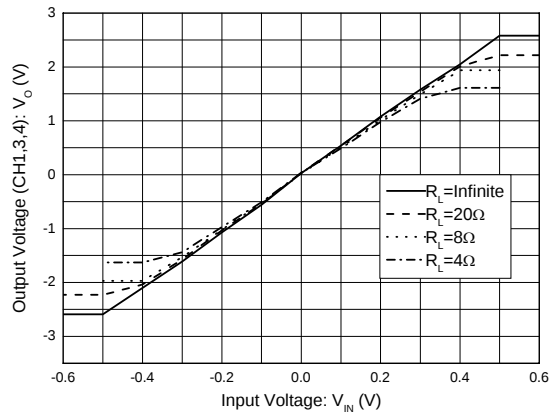


Figure 5. Input Load Fluctuation (CH1, 3, 4, Note 3)

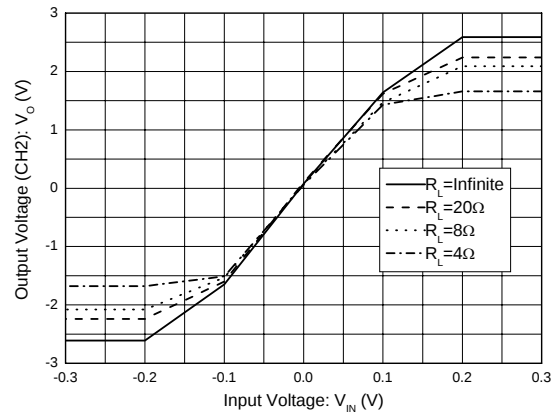


Figure 6. Input Load Fluctuation (CH2, Note 3))

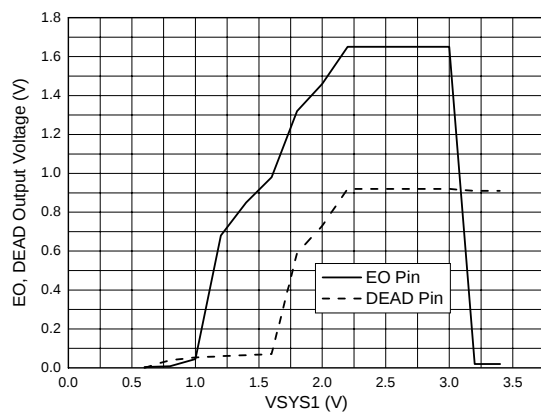


Figure 7. Error Amplifier Output Voltage

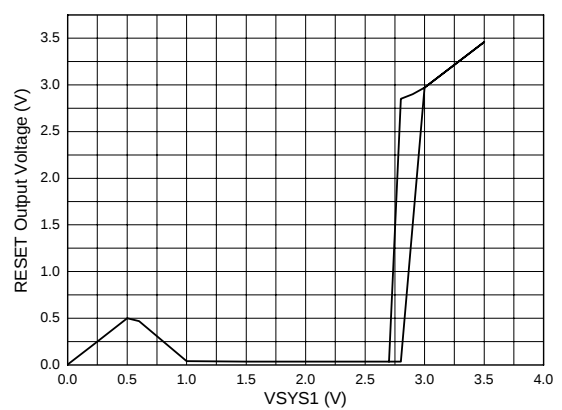


Figure 8. RESET Pin Voltage

Note 3: Input voltage herein is referenced to Bias pin voltage.



Mar. 2007 Rev. 1.3

## 4-CHANNEL MOTOR DRIVER WITH POWER CONTROLLER

AM5901A

### Application Information

#### H-Bridge Driver

##### 1. Mute Function

Brake function is assigned to CH1, mute function is assigned to other 3 channels.

(1) CH1 is in normal operation when the BRAKE pin is low (high when CH1 mute on), and enters a brake mode.

(2) CH2 is in normal operation when the MUTE2 pin is low (high when CH2 mute on).

(3) CH3,4 are in normal operation when the MUTE34 pin is high (low when CH3,4 mute on).

##### 2. $V_{REF}$ Drop Mute

When the voltage impressed to  $V_{REF}$  terminal is 1.0V (Typ.) or less, impedance of driver output becomes "high".

##### 3. Thermal Shutdown

If the chip temperature rises above 140 °C, then the thermal shutdown (TSD) circuit is activated and the output current is cut. When the chip temperature has dropped to 100°C, then output current begins to flow.

##### 4. Driver Gain

Driver input resistance is 11k $\Omega$  (CH1, CH3, CH4) and 7.5k $\Omega$  (CH2). Driver gain can be calculated by the expression.

$$\text{CH1,3,4} \quad G_V = 20 \log |55k/(R+11k)|$$

$$\text{CH2} \quad G_V = 20 \log |110k/(R+7.5k)|$$

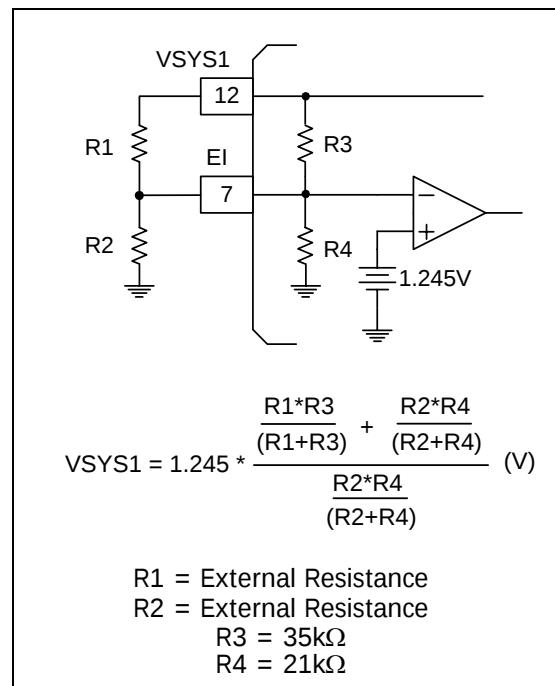
R is an external resistance

The power supply of driver output stage is  $HV_{CC}$  terminal and that of pre-driver circuit is  $VSYS2$  terminal. Attach a by-pass capacitor (approximately 0.1 $\mu$ F) between the power supplies as near as possible to this chip.

#### DC/DC Converter Control Circuit

##### 1. Output Voltage

Booster circuit of voltage ( $VSYS1$ ) can be configured with external component. The voltage is defined as follows.



##### 2. Short-Circuit Protection Function

When the output of error amplifier is "H", if the voltage of SPRT terminal has reached 1.245V (Typ.) upon charging the terminal, switching of SW terminal is disabled. Time to disable switching depends on the capacitor of SPRT terminal and it can be calculated by the expression:

$$t = C_{SPRT} * V_{TH} / I_{SPRT} \text{ (sec)}$$

( $V_{TH}$ =1.245V,  $I_{SPRT}$ =10 $\mu$ A)

## 4-CHANNEL MOTOR DRIVER WITH POWER CONTROLLER

AM5901A

### Application Information (Continued)

#### 3. Soft-Start Function

The soft-start is functioned by putting a capacitor between DEAD terminal and GND, the maximum duty can be changed by attaching a resistance to pin 4.

$$t = C_{\text{DEAD}} * R \text{ (sec)}$$

(R=65kΩ)

#### 4. Power-Off Operation

SPRT terminal is charged by setting OFF terminal to "L". Then, switching of SW terminal is terminated when the voltage of the SPRT terminal has reached 1.245V (Typ.). Time to disable switching depends on a capacitor of the SPRT terminal and it can be calculated by the expression:

$$t = C_{\text{SPRT}} * V_{\text{TH}} / I_{\text{OFF}} \text{ (sec)}$$

( $V_{\text{TH}} = 1.245\text{V}$ ,  $I_{\text{HV}} = 20\mu\text{A}$ )

#### 5. Over-Voltage Protection Operation

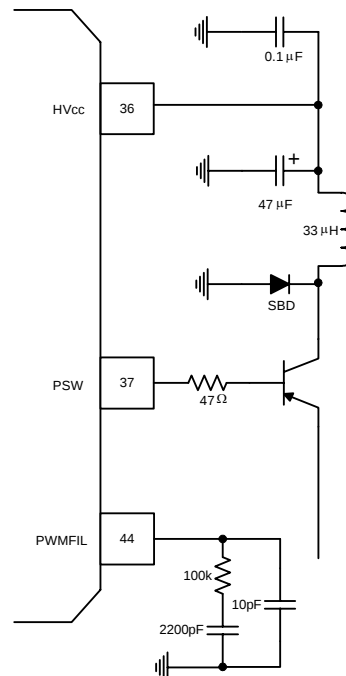
When the voltage applied to BSEN terminal has been 8.4V (Typ.), SPRT terminal is charged. Then, switching of SW terminal is terminated when the voltage of the SPRT terminal has reached 1.245V (Typ.). Time to disable switching depends on a capacitor of SPRT terminal and it can be calculated by the expression:

$$t = C_{\text{SPRT}} * V_{\text{TH}} / I_{\text{HV}} \text{ (sec)}$$

( $V_{\text{TH}} = 1.245\text{V}$ ,  $I_{\text{HV}} = 20\mu\text{A}$ )

#### PWM Power Supply Driver Circuit

This circuit detects a maximum output level of drivers of four channels and performs the PWM supply of load drive power supply. This circuit uses PNP transistor, Schottky Diode and capacitor as external component.



#### "Empty" Detector Unit

When the voltage applied to BSEN terminal has reached the detecting voltage or less. EMP terminal varies from "H" to "L" (open collector output). Hysteresis of 50mV (Typ.) is set to the detecting voltage to prevent the output chattering. The detecting voltage varies depending on SEL terminal as follows:

| SEL Pin | Detecting Voltage | Return Voltage |
|---------|-------------------|----------------|
| L       | 2.2V (Typ.)       | 2.25V (Typ.)   |
| High-Z  | 1.8V (Typ.)       | 1.85V (Typ.)   |

**4-CHANNEL MOTOR DRIVER WITH POWER CONTROLLER****AM5901A****Application Information (Continued)****Reset Circuit**

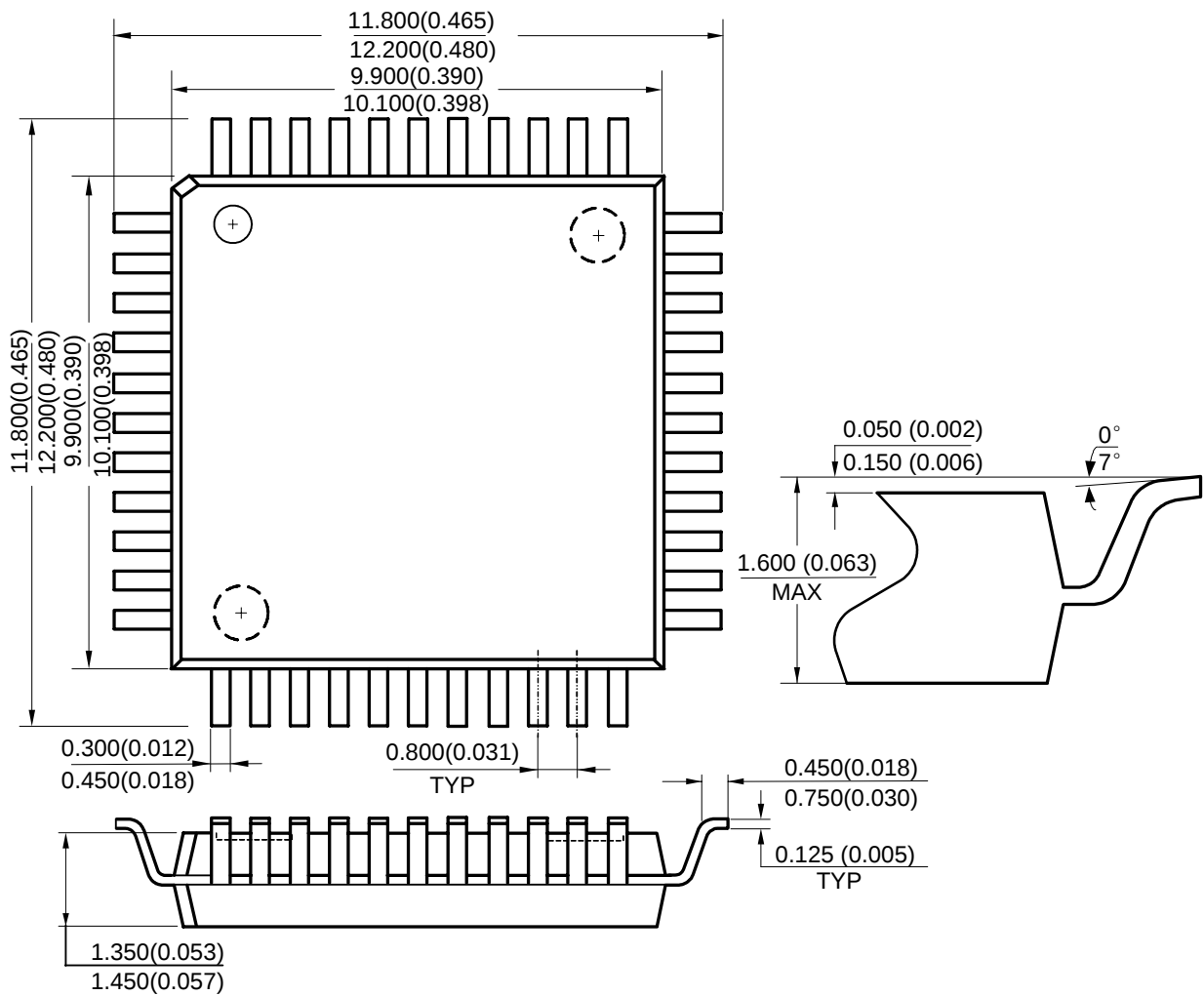
Upon 90% of DC/DC converter output voltage, RESET terminal varies from "L" to "H" and AMUTE terminal changes from "H" to "L". Hysteresis of 50mV (Typ.) is set to the reset voltage to prevent the output chattering.

**Charging Circuit**

The power supply of the charging unit is from CHGV<sub>CC</sub> terminal and it is independent of any

other circuits. Charging current is set by the resistance between RCHG terminal and GND. The charging current takes constant current through SEL terminal.

This circuit has a private thermal shutdown circuit. When the chip temperature has risen to 140°C, the charging current is cut off. When the chip temperature has dropped to 100°C, the charging current begins to flow.

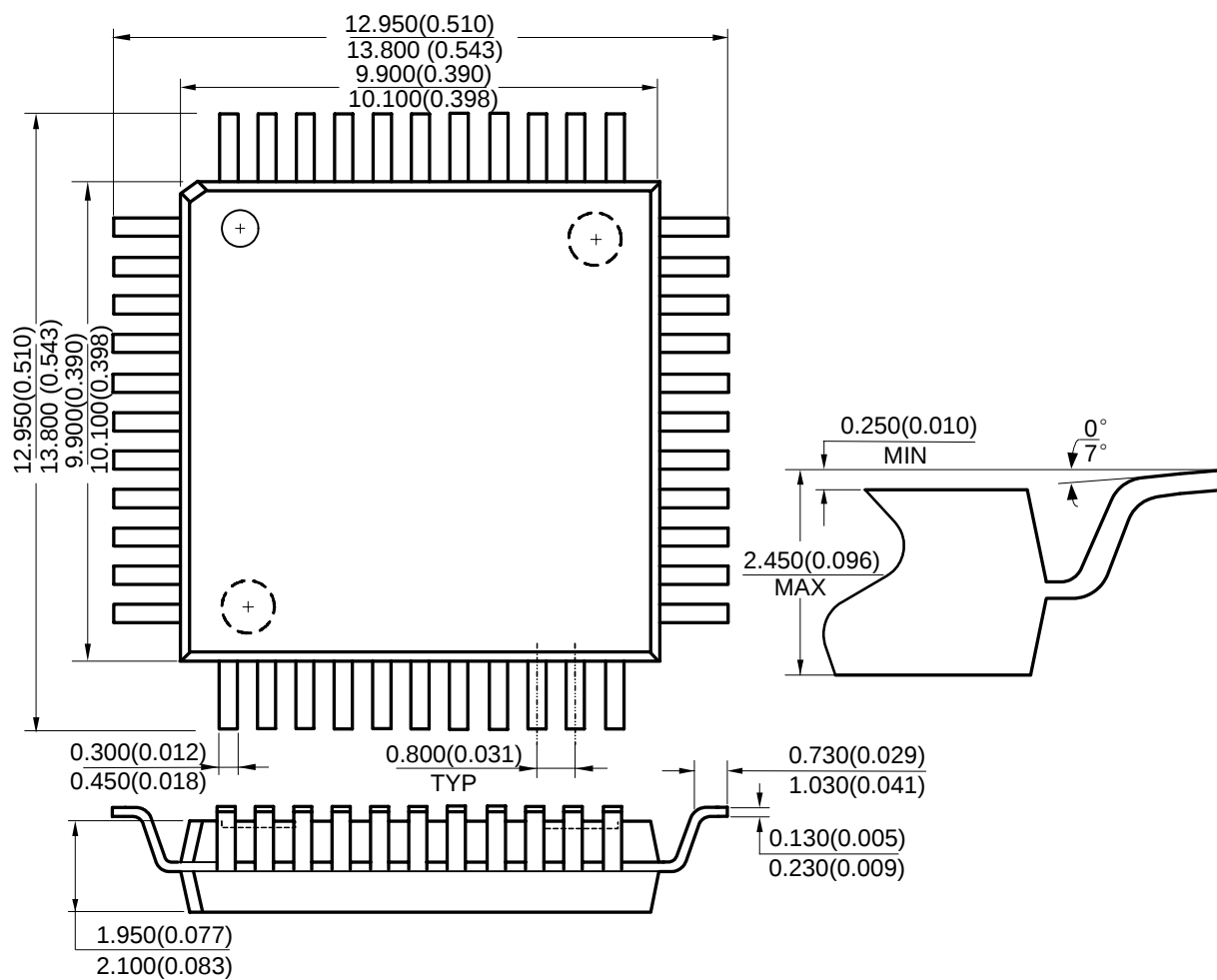
**4-CHANNEL MOTOR DRIVER WITH POWER CONTROLLER****AM5901A****Mechanical Dimensions****LQFP-44****Unit: mm(inch)**



### Mechanical Dimensions (Continued)

**PQFP-44**

Unit: mm(inch)





BCD Semiconductor Manufacturing Limited

<http://www.bcdsemi.com>

#### IMPORTANT NOTICE

BCD Semiconductor Manufacturing Limited reserves the right to make changes without further notice to any products or specifications herein. BCD Semiconductor Manufacturing Limited does not assume any responsibility for use of any its products for any particular purpose, nor does BCD Semiconductor Manufacturing Limited assume any liability arising out of the application or use of any its products or circuits. BCD Semiconductor Manufacturing Limited does not convey any license under its patent rights or other rights nor the rights of others.

---

#### MAIN SITE

**BCD Semiconductor Manufacturing Limited**  
- Wafer Fab  
**Shanghai SIM-BCD Semiconductor Manufacturing Limited**  
800, Yi Shan Road, Shanghai 200233, China  
Tel: +86-21-6485 1491, Fax: +86-21-5450 0008

**BCD Semiconductor Manufacturing Limited**  
- IC Design Group  
**Advanced Analog Circuits (Shanghai) Corporation**  
8F, Zone B, 900, Yi Shan Road, Shanghai 200233, China  
Tel: +86-21-6495 9539, Fax: +86-21-6485 9673

#### REGIONAL SALES OFFICE

**Shenzhen Office**  
**Shanghai SIM-BCD Semiconductor Manufacturing Co., Ltd. Shenzhen Office**  
**Advanced Analog Circuits (Shanghai) Corporation Shenzhen Office**  
Room E, 5F, Noble Center, No.1006, 3rd Fuzhong Road, Futian District, Shenzhen 518026, China  
Tel: +86-755-8826 7951  
Fax: +86-755-8826 7865

**Taiwan Office**  
**BCD Semiconductor (Taiwan) Company Limited**  
4F, 298-1, Rui Guang Road, Nei-Hu District, Taipei, Taiwan  
Tel: +886-2-2656 2808  
Fax: +886-2-2656 2806

**USA Office**  
**BCD Semiconductor Corporation**  
30920 Huntwood Ave. Hayward, CA 94544, U.S.A  
Tel : +1-510-324-2988  
Fax: +1-510-324-2788