

PIM400 Series; ATCA Board Power Input Modules

-36 to -75 Vdc; 400W/10A



Applications

- ATCA Front Board / Blade
- Central Office Telecom equipment
- High availability server and storage applications

Options

- Choice of short pin lengths
- I²C Digital Interface

Description

The PIM400 series of Power Input Modules are designed to greatly simplify the task of implementing dual redundant, hot swap – 48Vdc power distribution with EMI filtering on an ATCA or other telecom boards. The PIM400 with optional I²C digital interface capability, when used with a variety of GE's series of Bus converters (Barracuda™ Series) /POLs (DLynx™ Series) provides for a quick, simple and elegant power solution to a wide variety of demanding & intelligent power system architectures.

Features

- -48V/10A Dual redundant input power distribution
- 3.3Vdc/3.6A & 5.0Vdc/150mA of isolated Management Power for IPM or other housekeeping functions
- Independent holdup capacitor charging voltage; trimmable from 50 to 95Vdc for optimal real estate
- OR'ing functionality, Inrush protection & hot swap capability
- Integral EMI filter designed for the ATCA board to meet CISPR Class B with minimal external filtering
- Protection: Reverse polarity, under voltage, input transient over voltage/current and temperature
- I²C digital interface options
- Isolated A/B Feed Loss /Open Fuse Alarm
- High efficiency : 98%
- -40 to 85°C ambient temperature operation
- Industry Standard Quarter brick size: 58.4 mm x 36.8 mm x 13.7 mm (2.3 in x 1.45 in x 0.54 in)
- MTBF : 2,308,563 hours per TELCORDIA
- ISO** 9001 & ISO 14001 certified manufacturing facilities
- Compliant to RoHS II EU "Directive 2011/65/EU"
- UL* 60950-1, 2nd Ed. Recognized, CSA† C22.2 No. 60950 1-07 Certified, and VDE‡ (EN60950-1, 2nd Ed.) Licensed
- Meets the voltage and current requirements for ETSI 300-132-2 and complies with and licensed for Basic insulation rating per EN60950-1
- 2250 Vdc Isolation tested in compliance with IEEE 802.3[¶] PoE standards
- ISO**9001 and ISO 14001 certified manufacturing facilities

* UL is a registered trademark of Underwriters Laboratories, Inc.

† CSA is a registered trademark of Canadian Standards Association.

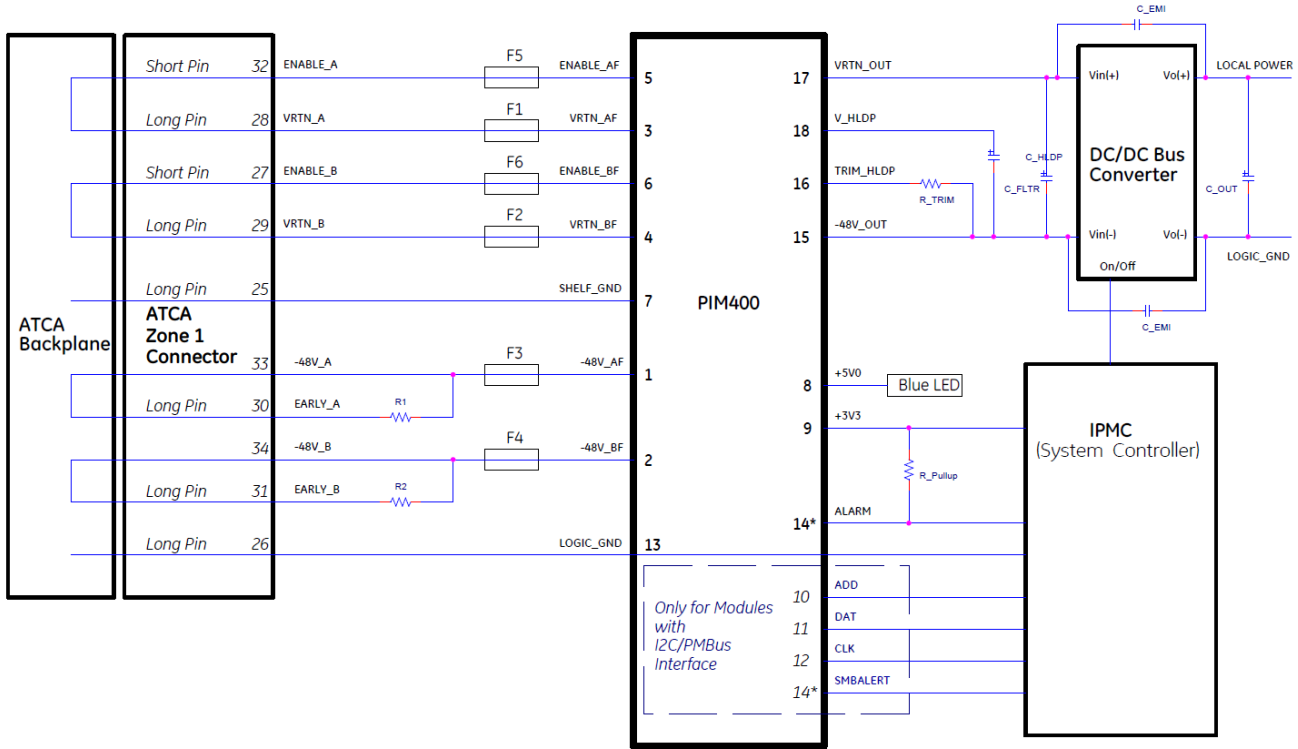
‡ VDE is a trademark of Verband Deutscher Elektrotechniker e.V.

** ISO is a registered trademark of the International Organization of Standards

¶ IEEE and 802 are registered trademarks of the Institute of Electrical and Electronics Engineers, Incorporated.

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ATCA Board Typical Application



| External Holdup Capacitor Selection | External Holdup Trim Resistor Selection |
|--|--|
| $C_{HLDP} = \frac{2T_{HU}P_{HU}}{V_{HLDP}^2 - V_{UV}^2}$ | $R_{TRIM}(\Omega) = \left(\frac{500,000}{V_{HLDP} - 50.0} - 10,000 \right)$ |

Suggested Bill of Materials

(Note: Customer is ultimately responsible for the final selection and verification of the suggested parts for the end application).

| Ref Des | Description (Values) | Comments |
|----------|--------------------------------|--|
| F1-F4 | Fuses (15A) | Max fuse rating not to exceed 20A, fast acting |
| F5,F6 | Fuses (15A) | 0.5 to 1A rated |
| R1,R2 | Pre-charge Resistors (15 Ohms) | High Surge Power Type e.g. KOA P/N SG73 |
| R_TRIM | Resistor | See Design Consideration section for details |
| R_PULLUP | Resistor (3.3 kOhms) | Alarm pull-up resistor |
| C_FLTR | Capacitor(s) (100µF) | 270 µF (max) |
| C_HLDP | Capacitor(s) | 3300µF (max); see Design Consideration section for details |
| C_OUT | Capacitor(s) | Consult data sheet for the applicable DC/DC Bus Converter |
| C_EMI | Capacitors | See Design Consideration section for details |

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Absolute Maximum Ratings

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

| Parameter | Device | Symbol | Min | Typ | Max | Unit |
|---|--------|------------|------|-----|------|-----------------|
| Input Voltage | | | | | | |
| Continuous | All | V_I | -0.5 | | -75 | V _{dc} |
| Transient (Pulse duration = 1ms, square wave) | All | V_{tr} | | | -100 | V _{dc} |
| Additionally: Transient Input Undervoltage, Overvoltage and Impulse per ANSI T1.315-2001(R2006) | All | | | | | |
| Reverse Polarity Protection | | | | | +75V | V _{dc} |
| Holdup Capacitor Voltage | | | | | | |
| Voltage (with respect to -48V_OUT) | All | V_{HLDP} | | | 100 | V _{dc} |
| Capacitance | All | C_{HLDP} | | | 3300 | μF |
| Temperature | | | | | | |
| Normal Operating Ambient Temperature (See Thermal Considerations section) | All | T_A | -40 | | 85 | °C |
| Storage Temperature | All | T_{stg} | -55 | | 125 | °C |
| Isolation Voltage | | | | | | |
| Input to MGMT_PWR Output Voltage & Alarm | All | | | | 2250 | Vdc |
| Input to SHELF_GND Voltage | All | | | | 2250 | Vdc |
| Input to LOGIC_GND Voltage | All | | | | 2250 | Vdc |

CAUTION: This power module is not internally fused. Both A & B feeds and their corresponding returns must be individually fused.

To preserve maximum flexibility, internal fusing is not included. However, to achieve maximum safety and system protection, the safety agencies require a fast-acting fuse with a maximum rating of 20 Amps and Voltage Rating $\geq 75V_{dc}$ for the -48AF, -48BF VRTN_AF & VRTN_BF feeds. Consult Fusing and fault protection Section of PICMG 3.0 ATCA specifications for additional information. Based on the information provided in this data sheet on inrush current and maximum dc input current, the same type of fuse with a lower rating can be used. Refer to the fuse manufacturer's data sheet for further information.

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Electrical Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

| Parameter | Device | Symbol | Min | Typ | Max | Unit | |
|--|--------|------------------|-------|-------|----------|------------|------|
| -48V Dual Feed Inputs (-48_AF,-48_BF,VRTN_AF,VRTN_BF) | | | | | | | |
| Input Voltage Range | All | V_i | -36 | -48 | -75 | Vdc | |
| Output Current With the following maximum power limits 400W @ 40Vin, 480W @ 48Vin, 540W @ 54Vin | All | I_o | | | 10 | Adc | |
| Disabled input current drain if input voltage falls below V_{UVLO} for > 2 seconds. | All | I_{UVLO} | | 10 | | mA | |
| Enabled No-load input current | All | I_{stdby} | | 40 | 70 | mA | |
| Inrush Transient (@ -48 V, $C_{FLTR} = 200\mu F$ & EARLY_A, EARLY_B Pre-charge resistors 15 ohms per leg as recommended in the " ATCA Board Typical Application" figure, p=2) | All | | | | | | |
| Duration: 0.1ms to 0.9ms | | I_{pk} | | | 40 | Adc | |
| Duration: 0.9ms to 3 ms (Logarithmically declining) | | I_{pk} | | | 40 to 18 | Adc | |
| ENABLE A/B Signal Inputs (ENABLE_A, ENABLE_B) | | | | | | | |
| Input Voltage Threshold (On/Off); Default Setting | All | V_{UVHI} (On) | -33.5 | -35.3 | -36.0 | Vdc | |
| | | V_{UVLO} (Off) | -32.4 | -33.7 | -34.1 | | |
| Enable A / B Signals current drain ($V_{in} = -48Vdc$) | All | | | 380 | | μA dc | |
| Main Output (-48V_OUT, VRTN_OUT) | | | | | | | |
| Efficiency ($V_{in} = -48V$; 3.3V/5.0V @ no load) | | | | | | | |
| 400W Output Power | All | η | | 98.2 | | % | |
| 300W Output Power | All | η | | 98.5 | | % | |
| Output Voltage Delay | All | T_{delay} | | 100 | | ms | |
| Input Current Limit | All | I_{limit} | 11 | 13 | 15 | A | |
| External Output Filter Capacitance (C_{FLTR}) | All | C_{FLTR} | 80 | 100 | 270 | μF | |
| Holdup Capacitor Output Voltage (V_{HLDP}) | | | | | | | |
| Holdup Capacitor Voltage Trim Range | All | V_{HLDP} | 50 | 90 | 95 | V | |
| Holdup Capacitor Output Voltage Tolerance @ $V_{HLDP} = 90Vdc$ | | | +6 | | -6 | % | |
| -48V_OUT Threshold | | | | | | | |
| To charge external holdup capacitors (C_{HLDP}) | | | | | 40.0 | | |
| To discharge external holdup capacitors (C_{HLDP}) | | | | -34.5 | -36.0 | -37.5 | |
| dV/dt on Hold-up Connect | | | | | 80 | | V/ms |
| Switching Frequency | | f | | 330 | | kHz | |
| A/B Feed Loss / Fuse Alarm Output (ALARM) | | | | | | | |
| ALARM ON Input Voltage Threshold | All | | -36.4 | -37.2 | -40.4 | Vdc | |
| ALARM OFF Input Voltage Threshold | | | | -40.5 | | Vdc | |
| External Pull-up Voltage | | | | | 5.0 | Vdc | |

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Electrical Specifications (continued):

| Parameter | Output Voltage | Symbol | Min | Typ | Max | Unit |
|--|----------------|-------------------|-------|----------------|-------|--------------------------------|
| +3.3V Isolated Management Power Output (+3V3) | | | | | | |
| Input Under-Voltage Lockout Turn-On Voltage Threshold | All | | -32.4 | -33.7 -34.5 | -34.1 | V V |
| Total Output Voltage Range (Over all operating input voltage, resistive Load and temperature conditions until end of life). | All | +3V3 | 3.170 | 3.350 | 3.430 | V |
| Output Current | All | I_o | 0 | — | 3.6 | A _{dc} |
| Output Ripple and Noise Measured across 10 μ F ceramic capacitor $V_I = V_{I,nom}$ $T_A = 25^\circ\text{C}$, $I_o = I_{o,max}$ RMS (500 MHz bandwidth) | All | | — | 16 | 30 | mV _{rms} |
| Peak-to-peak (500MHz bandwidth) | | | — | 75 | 100 | mV _{p-p} |
| Output Current- Limit Inception | All | $I_{o,lim}$ | — | 4 | 6 | A _{rms} |
| Output Short-circuit Current | All | $I_{o,sc}$ | — | 3 | — | A _{rms} |
| External Load Capacitance | All | $C_{O,max}$ | 0 | — | 1000 | μ F |
| Switching Frequency | All | f | | 330 | | kHz |
| Dynamic Response ($di/dt = 0.1\text{A}/\mu\text{s}$, $V_{in} = V_{in,nom}$, $T_A = 25^\circ\text{C}$) Load change from $I_o = 50\%$ to 75% of $I_{o,max}$, | All | | | | | |
| Peak Deviation Settling Time ($V_O < 10\%$ of peak deviation) | | V_{pk} t_s | | 7 800 | | % $V_{O,set}$ μs |
| Turn-On Delay ($I_o = 80\%$ of $I_{o,max}$, $T_A = 25^\circ\text{C}$) | All | T_{delay} | | 50 | | ms |
| Output voltage overshoot ($I_o = 80\%$ of $I_{o,max}$, $V_I = 48\text{Vdc}$ $T_A = 25^\circ\text{C}$) | All | | | | 3% | % $V_{O,set}$ |
| Output Over Voltage Protection | All | $V_{o,limit}$ | 3.7 | | 5.4 | V |
| +5.0V Isolated Management Power Output (+5V0) | | | | | | |
| Total Output Voltage Range (Over all operating input voltage, resistive Load and temperature conditions until end of life). | All | +5V0 | 4.80 | 5.00 | 5.20 | V |
| Output Current | All | I_o | 0 | — | 150 | mA _{dc} |
| Output Current-Limit Inception | All | $I_{o,lim}$ | — | 250 | — | mA |
| Output Short-circuit Current | All | $I_{o,sc}$ | — | 150 | — | mA _{RMS} |
| External Load Capacitance | All | $C_{O,max}$ | 0 | — | 1000 | μ F |
| Switching Frequency | All | f | — | 330 | — | kHz |

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Digital Interface Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

| Parameter | Conditions | Symbol | Min | Typ | Max | Unit |
|---|------------------|-----------|-----|------|-----|------|
| Digital Signal Interface Characteristics | | | | | | |
| Clock frequency range | | f_{CLK} | | 100 | 400 | kHz |
| Measurement Tolerance | | | | | | |
| Feed Voltage A/B (-48V_AF & -48V_BF) | | | | +/-3 | | % |
| Holdup Voltage (V_HLDP) | | | | +/-3 | | % |
| -48V_OUT current (-48V_IOUT) | % of $I_{o,max}$ | | | +/-3 | | % |
| Module Temperature (TEMP) | | | | +/-3 | | °C |

General Specifications

| Parameter | Device | Min | Typ | Max | Unit |
|---|--------|-----|------------|-----|---------|
| Calculated MTBF ($P_O=0.8P_{O,RATED}$, $48V_{IN}$, $T_A=40^{\circ}C$, Airflow=300LFM) Telecordia Issue 2 Method 1 Case 3 | All | | 2,308,563 | | Hours |
| Weight | | — | 28.3 (1.0) | — | g (oz.) |

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Characteristic Curves

The following figures provide typical characteristics for the PIM400X modules at 25°C.

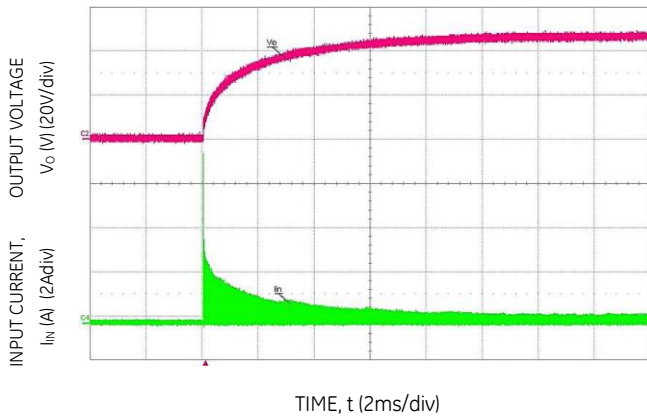


Figure 1. Inrush Current
 CH2: VRTN_OUT wrt -48Vout (Vo)
 CH4: Input current (I_{IN})

Test Conditions:
 48V_{in}, 400W, C_{FLTR} = 100μF

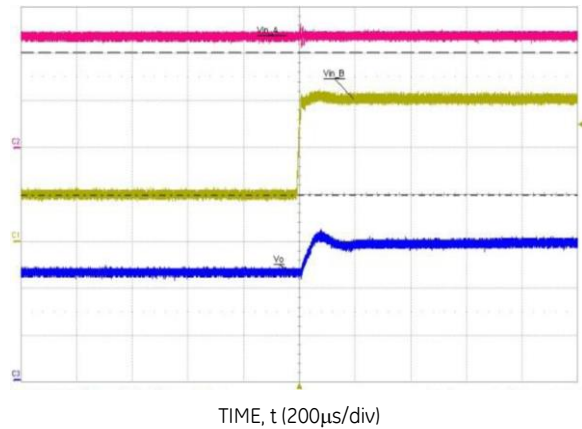


Fig 2: Input Transient on one feed
 CH1: Feed B step to 60V (20V/Div)
 CH2: Feed A at 48V (20V/Div)
 CH3: VRTN_OUT (20V/Div)
 Test Conditions:
 Full load

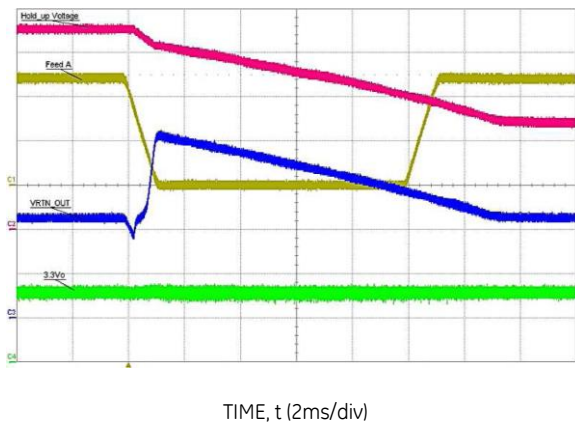


Fig 3: Hold-up Event vs 3.3Vout
 CH1: Feed A (20V/Div)
 CH2: Hold-up Voltage (20V/Div)
 CH3: VRTN_OUT (20V/Div)
 CH4: 3.3Vout (2V/Div)

Test Conditions:

1. Payload Bus Converter: QBVW033A0B
2. Load: 12.0V Bus Converter Output @ 33A; 3.3V@3.6A
3. C_{Hold-up} = 2200 μF
4. C_{FLTR}=220μF
5. V_{HLDP}=90V

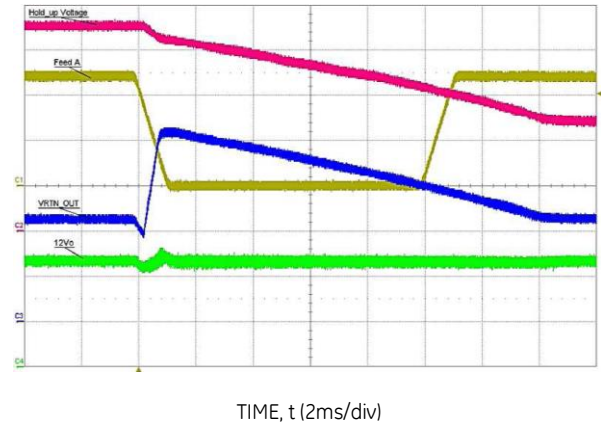


Fig 4: Hold-up Event vs 12.0Vout
 CH1: Feed A (20V/Div)
 CH2: Hold-up Voltage (20V/Div)
 CH3: VRTN_OUT (20V/Div)
 CH4: 12.0 Vout (5V/Div)

Test Conditions:

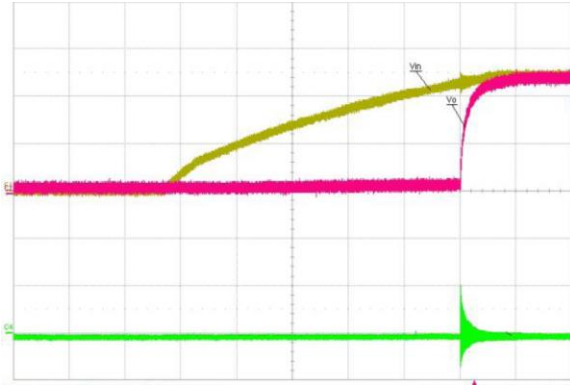
1. Payload Bus Converter: QBVW033A0B
2. Load: 12.0V Bus Converter Output @ 33A; 3.3V@3.6A
3. C_{Hold-up} = 2200 μF
4. C_{FLTR}=220μF
5. V_{HLDP}=90V

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Characteristic Curves (continued)

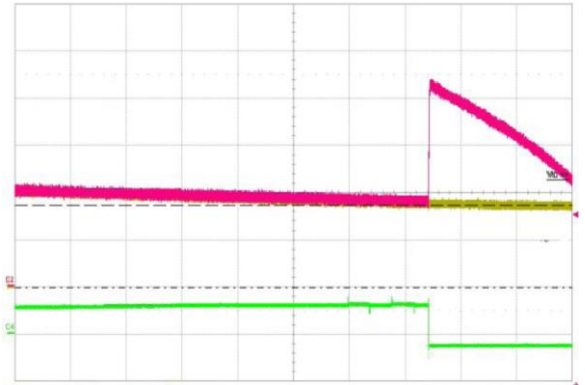
The following figures provide typical characteristics for the PIM400X modules at 25°C.



TIME, t (20ms/div)

Fig 5: Turn-ON Threshold

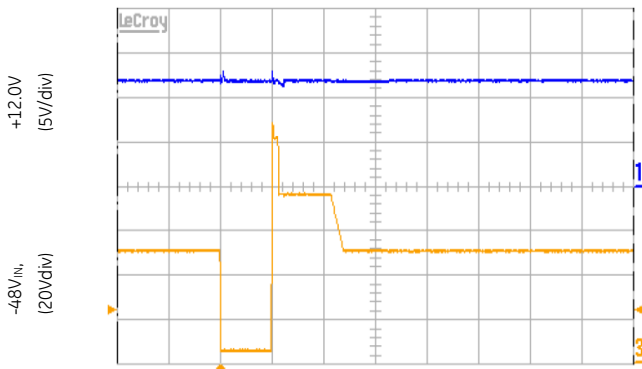
CH1: Input Voltage (20V/Div)
 CH2: VRTN_OUT voltage (20V/Div)
 CH4: Input Current (5A/Div)



TIME, t (10ms/div)

Fig 6: Turn-OFF Threshold

CH1: Input Voltage (20V/Div)
 CH2: VRTN_OUT voltage (20V/Div)
 CH4: Input Current (2A/Div)



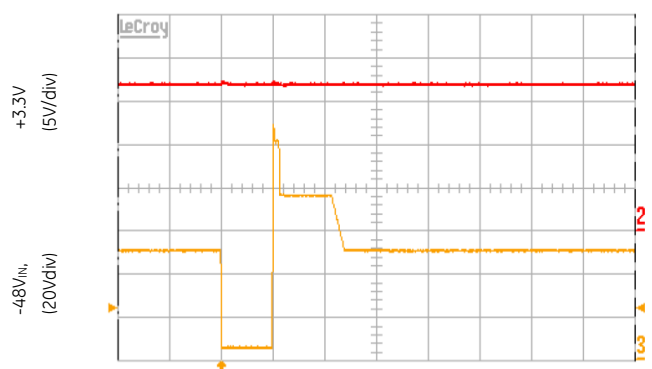
TIME, t (10ms/div)

Fig 7a: Line Transient performance per ANSI T1.315-2001 standard vs +12.0V output

CH1: +12Voutput voltage (5V/Div)
 CH3: -48V input Voltage (20V/Div)

Test Conditions:

1. PIM400 + QBDW033A0 (12V Bus Converter)
2. Load: +12Vout @ 30A; 3.3V @ 3.0A
3. C_HLDP = 2200 μ F
4. C_FLTR = 220 μ F



TIME, t (10ms/div)

Fig 7b: Line Transient performance per ANSI T1.315-2001 standard vs 3.3V output

CH2: +3V3 Output Voltage (1V/Div)
 CH3: -48V input Voltage (20V/Div)

Test Conditions:

5. PIM400 + QBDW033A0 (12V Bus Converter)
6. Load: +12Vout @ 30A; 3.3V @ 3.0A
7. C_HLDP = 2200 μ F
8. C_FLTR = 220 μ F

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Characteristic Curves (continued)

The following figures provide typical characteristics for the PIM400X modules at 25°C.

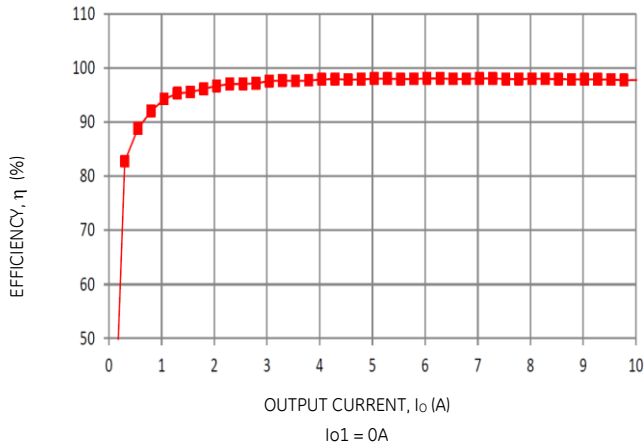


Fig8a: Efficiency vs Output Current

Test Conditions:

No load on 3.3V output

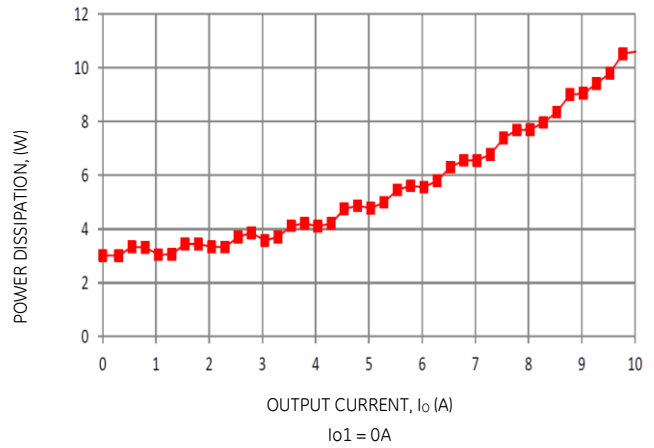


Fig 8b: Power Dissipation vs Output Current

Test Conditions:

No load on 3.3V output

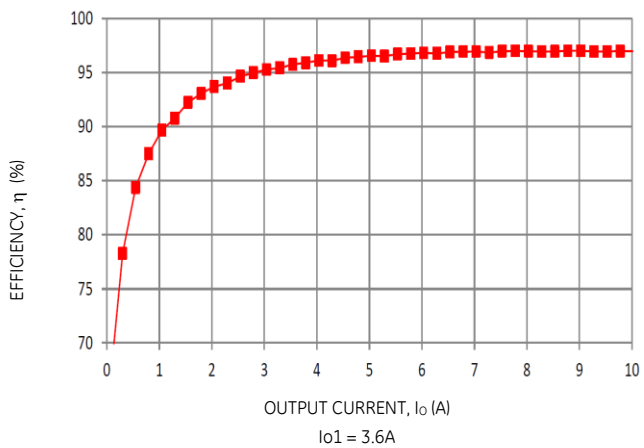


Fig 9a: Efficiency

Test Conditions:

Full load on 3.3V output

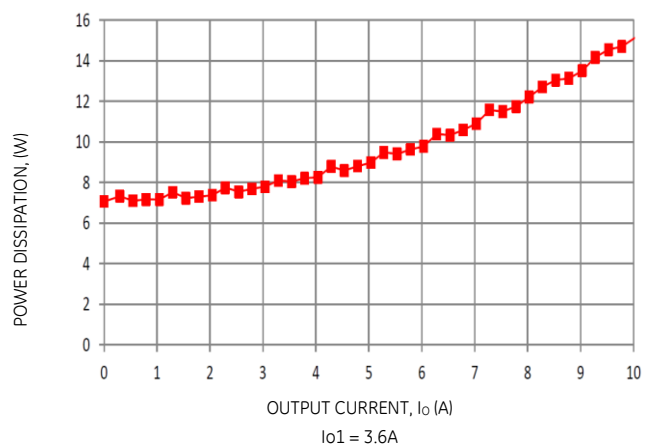


Fig 9b: Power Dissipation

Test Conditions:

Full load on 3.3V output

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Characteristic Curves (continued)

The following figures provide typical characteristics for the PIM400X modules at 25°C.

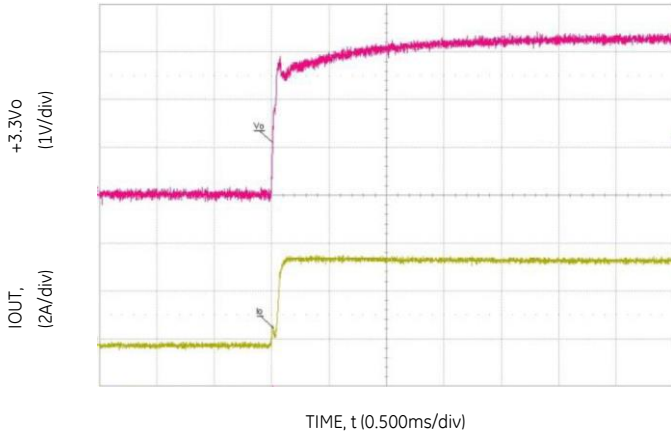


Fig 10: 3.3V Turn-On

Test Conditions:
 Cout=10μF ceramic

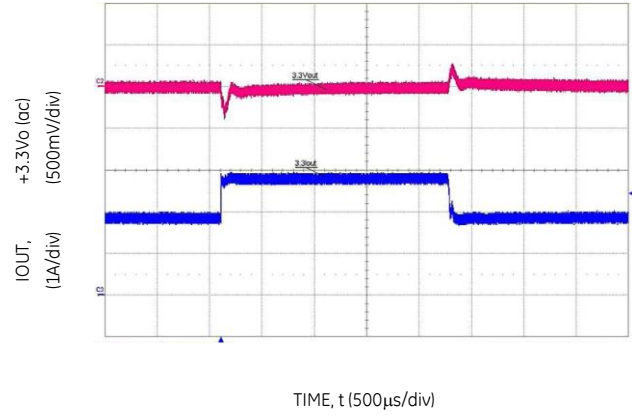


Fig 11: 3.3V Load Transient

Test Conditions:
 Cout = 10μF ceramic
 Step Load Change = 50%-75%-50% of Iout,max
 Slew Rate = 1 A/μs

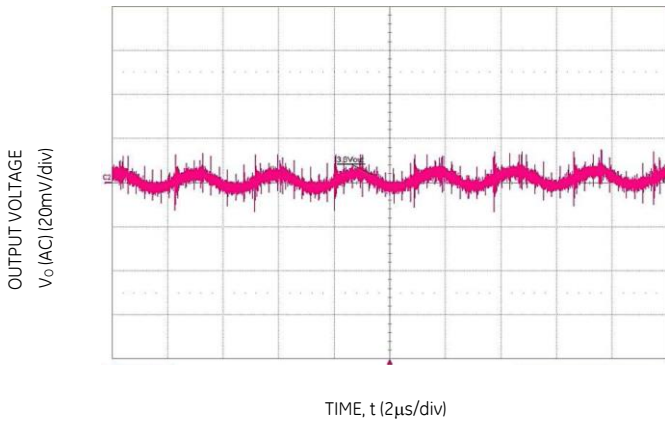


Fig 12: 3.3V Ripple

Test Conditions:
 Cout=10μF ceramic
 Iout=3.6A

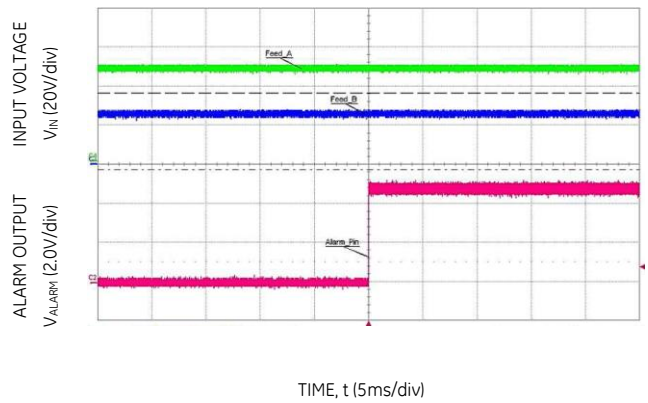
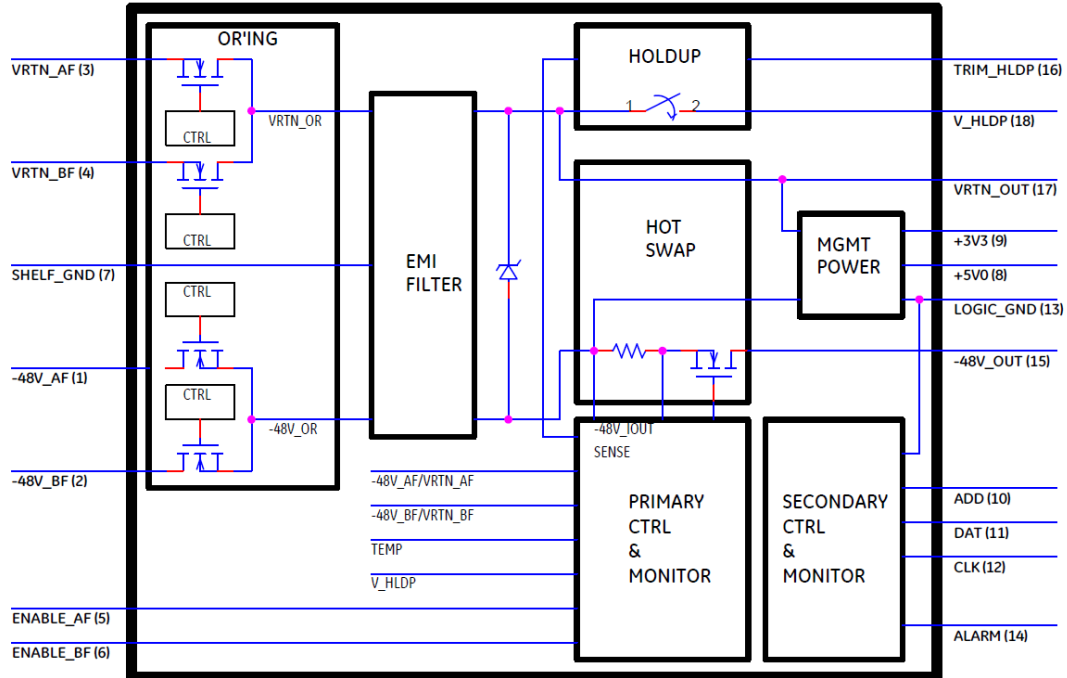


Fig 13: ALARM Output change of state with input voltage dropout

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PIM400 Internal Block Diagram



PIN FUNCTIONS

| Pin No. | Signal Name | Description |
|---------|-------------|--|
| 1 | -48V_AF | -48V_A Feed (Externally Fused) |
| 2 | -48V_BF | -48V_B Feed (Externally Fused) |
| 3 | VRTN_AF | VRTN_A Feed (Externally Fused) |
| 4 | VRTN_BF | VRTN_B Feed (Externally Fused) |
| 5 | ENABLE_AF | ENABLE_A Feed (Externally Fused) (Short Pin, connected to VRTN_A on the back plane) |
| 6 | ENABLE_BF | ENABLE_B Feed (Externally Fused) (Short Pin, connected to VRTN_B on the back plane) |
| 7 | SHELF_GND | Shelf / Chassis / Safety Ground |
| 8 | +5V0 | Isolated 5.0Vdc (Blue LED Power) w.r.t. LOGIC_GND |
| 9 | +3V3 | Isolated 3.3Vdc (Management Power) w.r.t. LOGIC_GND |
| 10* | ADD | I2C Address w.r.t. LOGIC_GND |
| 11* | DAT | I2C Data w.r.t. LOGIC_GND |
| 12* | CLK | I2C Clock w.r.t. LOGIC_GND |
| 13 | LOGIC_GND | Logic / Secondary / Isolated Ground |
| 14 | ALARM | Opto-isolated -48V A/B Feed Loss or Open Fuse Alarm (w.r.t LOGIC_GND) |
| 15 | -48V_OUT | OR'd and Inrush protected -48V Output Bus |
| 16 | TRIM_HLDP | Holdup capacitor output voltage trim w.r.t. -48V_OUT |
| 17 | VRTN_OUT | OR'd and Inrush protected VRTN Output Bus |
| 18 | V_HLDP | +ve terminal connection point for Holdup capacitor |

* Pins 10, 11 & 12 are present only on modules with I2C digital interface option (-K)

PIM400 Series; ATCA Board Power Input Modules

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Feature Descriptions

Introduction

The PIM400X module is designed to support the Advanced Telecommunications Computing Architecture (ATCA) power entry distribution requirements for the Front Board / Blade per the PICMG 3.0 specifications.

The PICMG 3.0 specification defines the Mechanical, Shelf Management Interface, Power Distribution, Thermal, Data I/O and Regulatory requirements for the next generation of modular telecom architecture platform for use in Central Office telecom environments.

Input Pin Connections

The ATCA board is specified to accept up to a maximum of 400W of input power via dual, redundant -48Vdc Feeds through the Zone 1 (Power and Management) connector, designated P10.

The power connector provides board to backplane engagement via pins of varying lengths. Please consult the PICMG 3.0 specifications for details.

The following are the design considerations of the input pin connections of the PIM400X to the ATCA power connector.

| From ATCA (P10 Connector) | | Connection Requirement | To PIM400X | |
|---------------------------|-----------------|------------------------|------------|--------------------|
| Pin # | Pin Designation | | Pin # | Signal Designation |
| 33 | -48V_A | Via Fuse(F3) | 1 | -48V_AF |
| 34 | -48V_B | Via Fuse(F4) | 2 | -48V_BF |
| 28 | VRTN_A | Via Fuse(F1) | 3 | VRTN_AF |
| 29 | VRTN_B | Via Fuse(F2) | 4 | VRTN_BF |
| 30 | EARLY_A | Via Resistor(R1) * | | -48V_A |
| 31 | EARLY_B | Via Resistor(R2) * | | -48V_B |
| 32 | ENABLE_A | Via Fuse(F5) | 5 | ENABLE_AF |
| 27 | ENABLE_B | Via Fuse(F6) | 6 | ENABLE_BF |
| 25 | SHELF_GND | Direct | 7 | SHELF_GND |
| 26 | LOGIC_GND | Direct | 11 | LOGIC_GND |

* Pre-charge resistors

The first pins to mate in the ATCA power connector are the EARLY_A, EARLY_B, the two grounds (LOGIC_GND, SHELF_GND) and the two returns (VRTN_A, VRTN_B); followed by staggered connections of -48V_A and -48V_B power Feeds. The last pins to engage are the two short pins, ENABLE_A & ENABLE_B. The ATCA backplane connects the ENABLE_A to VRTN_A, ENABLE_B to VRTN_B, EARLY_A to -48V_A and EARLY_B to -48V_B.

EARLY_A & EARLY_B Connections: During hot insertion of the ATCA board, the Inrush Control circuit limits the surge current to the C_FLTR capacitor. However, due to the presence of a small amount of internal EMI filter capacitance (located before the Inrush Control circuit), it is recommended that Precharge resistors, R1 & R2 (100 Ohms, with appropriate surge capability) be connected as shown in the Typical Application circuit.

Output Pin Connections (Standard Module: PIM400Z)

The output pin connections of the PIM400X to the system board are described below:

| From PIM400X | | To ATCA Front Board | | Notes |
|--------------|-----------------|----------------------|-----------------------|-------|
| Pin # | Pin Designation | Terminal | Component | |
| 15 | -48V_OUT | Vin(-) | DC/DC Converter | (1) |
| 17 | VRTN_OUT | Vin(+) | DC/DC Converter | |
| 18 | V_HLDP | +ve | Holdup Capacitor | (2) |
| 16 | TRIM_HLDP | RTrim | Holdup Capacitor | |
| 8 | +5V0 | | Management Power | (3) |
| 9 | +3V3 | | | |
| 14 | ALARM | R _{pull-up} | IPM/System Controller | (4) |

Additional Output Pin Connections (Modules with optional I²C Digital Interface: Option - K)

The following additional output pins of the PIM400KZ available for I²C Digital Interface to the IMP/System Controller are defined below:

| From PIM400KZ | | To ATCA Front Board | Notes |
|---------------|-----------------|-------------------------------------|-------|
| Pin # | Pin Designation | IPM/System Controller I2C Interface | |
| 10 | ADD | I2C Address w.r.t. LOGIC_GND | (5) |
| 11 | DAT | I2C Data w.r.t. LOGIC_GND | |
| 12 | CLK | I2C Clock w.r.t. LOGIC_GND | |

Inrush Current Control / Hot Plug Functionality

The module provides inrush current control / hot plug capability. The peak value of the inrush current and the duration complies with the PICMG 3.0's Inrush Transient specifications. The specifications shall be met with the external C_HLDP and C_FLTR capacitances as specified in the previous sections.

The unique design of the module where the large energy storage capacitors are segregated from the input filter capacitors allows the module to meet the stringent PICMG's inrush transient specifications with minimal energy storage capacitors.

Design Considerations

-48V Main Output Bus:

(Signal Names: -48V_OUT & VRTN_OUT)

This is the main -48V output bus that provides the payload power to the downstream (one or more) DC/DC converters. The

PIM400 Series; ATCA Board Power Input Modules

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PIM400X module does not regulate or provide isolation from the input -48V A/B feeds.

The main functionality of the module is to provide -48V A/B Feeds OR'ing, inrush protection for hot swap capability and EMI filtering to attenuate the noise generated by the downstream DC/DC converters.

- The -48V_OUT pin connects to the Vin(-) pin and the VRTN_OUT pin connects to the Vin(+) pin of the DC/DC converter(s).
- The -48V_OUT bus may require a fuse depending on the power and fusing requirements of the DC/DC converter.
- Input filtering of the DC/DC converter is provided by C_FLTR close to the input pins of the DC/DC converter(s); additional high frequency decoupling ceramic capacitors (0.01 to 0.1µF are recommended for improved EMI performance.
- The maximum C_FLTR capacitance across all the downstream DC/DC converters should not exceed 270µF.
- The minimum C_FLTR capacitance (80µF) recommendation is based on meeting the EMI requirements.

Holdup Capacitor Output Voltage (V_HLDP)

This output provides the user settable high voltage to charge the C_HLDP capacitor(s) to allow the ATCA board to meet the 5ms, 0Volts transient requirements.

- The V_HLDP pin connects to the +ve terminals of the C_HLDP capacitors while the -ve terminals of the C_HLDP connects to the -48V_OUT bus.
- The C_HLDP capacitance is dependent on the system power and the holdup time requirements based on the following formula

$$C_{HLDP} = \frac{2T_{HU}P_{HU}}{V_{HLDP}^2 - V_{UV}^2}$$

Where T_{HU} is the desired holdup time, P_{HU} is the holdup power drawn from the holdup capacitors (=input power of the downstream DC/DC bus converter + Management Power), V_{HLDP} is the trimmed holdup capacitor voltage and V_{UV} is the undervoltage lockout threshold of either the downstream bus or the Management Power DC/DC converter (higher of the two).

Holdup Capacitor Trim Voltage (TRM_HLDP)

The resistor R_TRIM sets the external holdup capacitor voltage to the desired setting. The output voltage is adjustable from 50 to 90V. The resistor, R_TRIM is selected by the following equation:

$$R_{TRIM}(\Omega) = \left(\frac{500,000}{V_{HLDP} - 50.0} - 10,000 \right)$$

High Voltage Discharge Mechanism:

Per the PICMG 3.0 specifications, the PIM400 provides an internal discharge mechanism to discharge the holdup/bulk

capacitance to less than -60Vdc and less than 20 joules within one second of disconnection from the backplane.

Management Power (+3V3, +5V0)

Two isolated secondary output voltages (+3V3 & +5V0) are provided for ATCA Front Board's IPM/System Controller (3.3V) and for the Blue LED's (5.0V) power requirements. Both the outputs are referenced to LOGIC_GND.

- The management power is available even when the input voltage is down to -36Vdc.
- No additional output capacitors are required, but a 22µF tantalum/ceramic and a 0.01 to 0.1µF ceramic capacitors are highly recommended to contain the switching ripple and noise.

Input Fault Alarm Signal (ALARM)

Both the input feeds, -48V_AF & -48V_BF are monitored via the -48V_ALARM signal. In the event of a loss of power from either feeds (-48V_A or -48V_B) or the opening of their respective fuses, the -48V_ALARM shall change its logical state indicating a fault. During normal operation, the signal is Low. During fault condition, the alarm signal shall assume a HI state when the ALARM pin is pulled up to an external pull voltage (maximum 5.0V) via an external pullup resistor (R_{Pullup}). The ALARM output is internally referenced to the LOGIC_GND. A 3.3K pull up resistor to 3.3V Management Power should suffice.

EMI Filtering

The module incorporates an EMI filter that is designed for the ATCA board to help meet the conducted emissions requirements of CISPR 22 Class B when used in conjunction with GE's DC/DC bus converters recommended for ATCA applications.

The following Figure 14 depicts the Class B EMI performance of PIM400F when tested with GE's bus converter, QBVW033A0B1 with both modules mounted on the PIM400 Evaluation Board together with additional high frequency EMI capacitors (Fig 15).

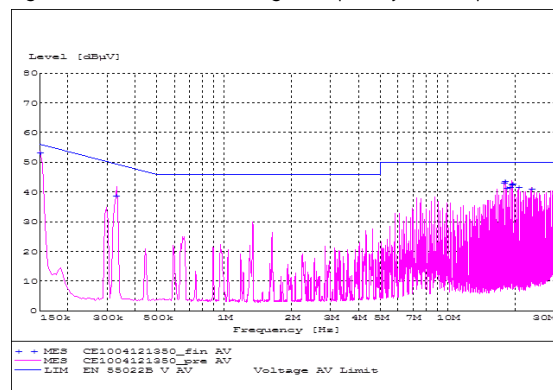


Figure 14. Typical Class B EMC signature of PIM400F as tested with GE's bus converter, QBVW033A0B1 module.

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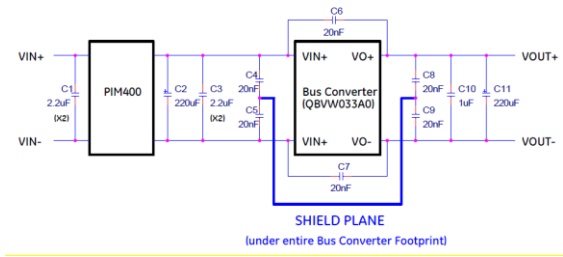


Figure 15. PIM400 & QBVW033A0 Bus Converter Test setup schematic

For Safety and noise considerations, copper traces must not be routed directly under the power module (PWB top layer). C_EMI capacitors must make direct connections (preferably without vias) to the bus converter (DC/DC) module pins with as much copper width as possible. In case vias are necessary, allow for multiple connections to the inner plane with vias placed outside the footprint of the module. For additional layout guide-lines, refer to GE's FLT012A0Z Input Filter Module data sheet.

Safety Considerations

For safety-agency approval of the system in which the power module is used, the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standard, i.e. UL* 60950-1, 2nd Ed. Recognized, CSA† C22.2 No. 60950-1-07 Certified, and VDE‡ (EN60950-1, 2nd Ed.) Licensed

The power input to these units is to be provided with a maximum of fast acting 20A fuses with a voltage rating of at least 75Vdc.

Refer to "Thermal Consideration" section for additional safety considerations.

Thermal Considerations

The power modules operate in a variety of thermal environments; however, sufficient cooling should be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel.

The thermal reference point, T_{ref}, used in the specifications is shown in Figure 16. For reliable operation this temperature should not exceed 130°C.

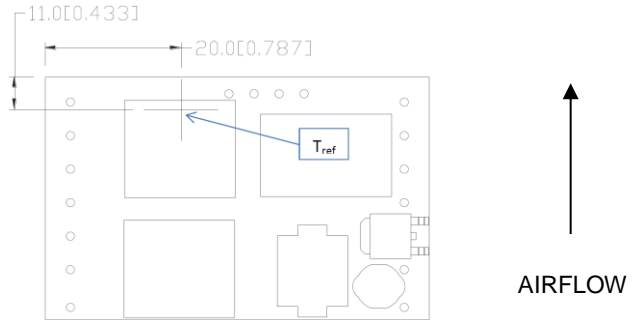


Figure 16. T_{ref} Temperature Measurement Location.

Heat Transfer via Convection

Increased airflow over the module enhances the heat transfer via convection. Derating curves showing the maximum output current that can be delivered by each module versus local ambient temperature (T_A) for natural convection and up to 2 m/s (400 lfm) forced airflow are shown in Figures 17 & 18.

Please refer to the Application Note "Thermal Characterization Process For Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.

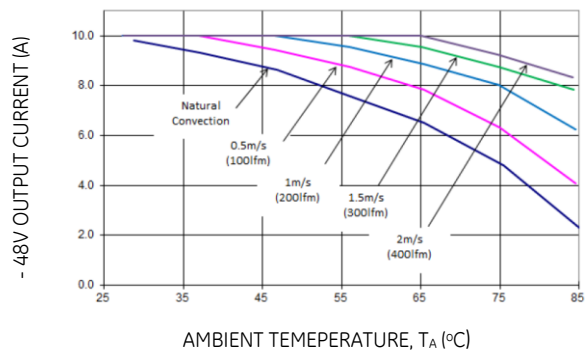


Figure 17. -48V Output Current Derating for the Module; Airflow in the Transverse Direction from Pin7 to Pin1; Vin =48V & 3.3V @ 1.5A.

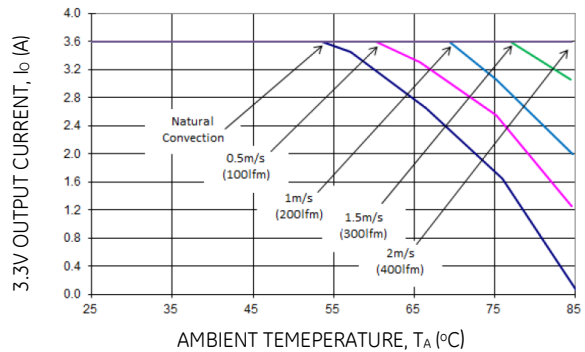


Figure 18. 3.3V Output Current Derating for the Module; Airflow in the Transverse Direction from Pin7 to Pin1; Vin =48V & -48V Output current = 4A.

PIM400 Series; ATCA Board Power Input Modules

-36 to -75 Vdc; 400W/10A

Layout Considerations

The power modules are low profile in order to be used in fine pitch system card architectures. As such, component clearance between the bottom of the power module and the mounting board is limited. Avoid placing copper areas on the outer layer directly underneath the power module. Also avoid placing via interconnects underneath the power module. Particular attention should be paid to the clearance area as noted in the Bottom View of the Mechanical Outline drawing.

For additional layout guidelines, refer to FLT012A0Z Data Sheet.

Process Considerations

Through-Hole Lead-Free Soldering Information

The RoHS-compliant, Z version, through-hole products use the SAC (Sn/Ag/Cu) Pb-free solder and RoHS-compliant components. The module is designed to be processed through single or dual wave soldering machines. The pins have a RoHS-compliant, pure tin finish that is compatible with both Pb and Pb-free wave soldering processes. A maximum preheat rate of 3°C/s is suggested. The wave preheat process should be such that the temperature of the power module board is kept below 210°C. For Pb solder, the recommended pot temperature is 260°C, while the Pb-free solder pot is 270°C max.

Reflow Lead-Free Soldering Information

The RoHS-compliant through-hole products can be processed with paste-through-hole Pb or Pb-free reflow process.

Max. sustain temperature :

245°C (J-STD-020C Table 4-2: Packaging Thickness \geq 2.5mm / Volume > 2000mm³),

Peak temperature over 245°C is not suggested due to the potential reliability risk of components under continuous high-temperature.

Min. sustain duration above 217°C : 90 seconds

Min. sustain duration above 180°C : 150 seconds

Max. heat up rate: 3°C/sec

Max. cool down rate: 4°C/sec

In compliance with JEDEC J-STD-020C spec for 2 times reflow requirement.

Pb-free Reflow Profile

BMP module will comply with J-STD-020 Rev. C (Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices) for both Pb-free solder profiles and MSL classification procedures. BMP will comply with JEDEC J-STD-020C specification for 3 times reflow requirement. The suggested Pb-free solder paste is Sn/Ag/Cu (SAC). The recommended linear reflow profile using Sn/Ag/Cu solder is shown in Figure 19.

MSL Rating

The modules have a MSL rating of 2a.

Storage and Handling

The recommended storage environment and handling procedures for moisture-sensitive surface mount packages is detailed in J-STD-033 Rev. A (Handling,

Packing, Shipping and Use of Moisture/Reflow Sensitive Surface Mount Devices). Moisture barrier bags (MBB) with desiccant are required for MSL ratings of 2 or greater. These sealed packages should not be broken until time of use. Once the original package is broken, the floor life of the product at conditions of \leq 30°C and 60% relative humidity varies according to the MSL rating (see J-STD-033A). The shelf life for dry packed SMT packages will be a minimum of 12 months from the bag seal date, when stored at the following conditions: < 40° C, < 90% relative humidity.

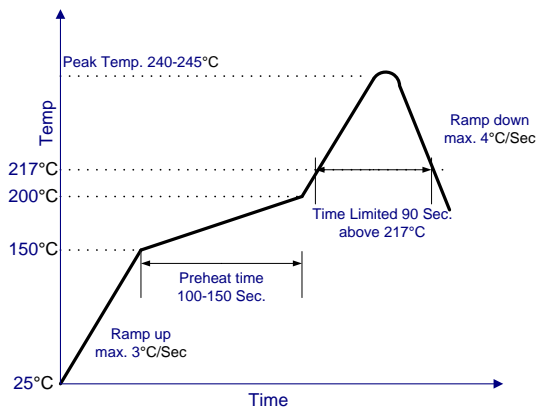


Figure 19. Recommended linear reflow profile using Sn/Ag/Cu solder.

Post Solder Cleaning and Drying Considerations

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to Lineage Power Board Mounted Power Modules: Soldering and Cleaning Application Note (AP01-056EPS).

For additional information, please contact your Sales representative for more details.

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Digital Feature Descriptions

Full featured modules are available with I²C Digital Interface (Option -K).

Modules with I²C capability monitor up to five analog parameters and six status bits identified below in Tables 1 and 2 respectively.

Modules with I²C Option Features:

| Data Pointer Value | Parameter | Description | Scaling Factor |
|--------------------|-------------|-------------------------------------|-----------------------|
| 1Eh | STATUS_BITS | Digital Signals (see Table 2) | N/A |
| 1Fh | V_HLDP | Holdup voltage w.r.t. -48V_OUT | 0.398 V/bit |
| 21h | -48V_IOUT | -48V_OUT current | 0.094 A/bit |
| 22h | -48V_AF | Voltage between -48V_AF and VRTN_AF | 0.325 V/bit |
| 23h | -48V_BF | Voltage between -48V_BF and VRTN_BF | 0.325 V/bit |
| 28h | TEMP | Module Temperature | (1.961 °C/bit) - 50°C |

Table 1: Internal register memory map

| Bit | Name | Description | Value | Translation |
|-----|------------------|------------------------------------|-------|-----------------------------|
| 0 | ENABLE_AF_STATUS | ENABLE_AF signal status | 0 | ENABLE_AF is Disabled |
| | | | 1 | ENABLE_AF is Enabled |
| 1 | ENABLE_BF_STATUS | ENABLE_BF signal status | 0 | ENABLE_BF is Disabled |
| | | | 1 | ENABLE_BF is Enabled |
| 2 | ALARM_STATUS | ALARM signal status | 0 | ALARM not set |
| | | | 1 | ALARM is set |
| 3 | N/A | Reserved | | |
| 4 | HLDP_STATUS | Holdup status | 0 | C_HLDP not connected |
| | | | 1 | C_HLDP is connected |
| 5 | HOTSWAP_STATUS | Hotswap status | 0 | Hotswap switch is off |
| | | | 1 | Hotswap switch is on |
| 6 | -48VOUT_STATUS | -48V_OUT Undervoltage alarm status | 0 | -48V_OUT is below threshold |
| | | | 1 | -48V_OUT is above threshold |
| 7 | N/A | Reserved | | |

Table 2: Digital signals

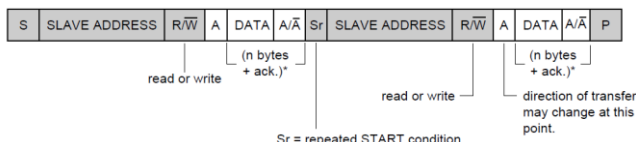
Note: Bit 0=LSB, Bit 7=MSB

I²C Command Structure:

The I²C is a 2-wire interface supporting multiple devices and masters on a single bus. The connected devices can only pull the bus wires low and they never drive the bus high. The bus wires should be externally connected to a positive supply voltage via a pull-up resistor. When the bus is idle, both DAT and CLK are high.

Each device on the I²C bus is recognized by a unique address stored in that device. Devices can be classified as masters or slaves when performing data transfers. A master is a device which initiates a data transfer on the bus and generates clock signals to permit that transfer. At the same time, any device addressed is considered slave. The PIM400 always acts as a slave.

In PIM400 module, I²C interface is used for reporting critical parameters like input voltage, output current, holdup capacitor voltage and temperature data. The read protocol is shown in the Fig 20 below.



*not shaded because transfer direction of data and acknowledge bits depends on R/W bits.

Fig 20: Typical I²C Read protocol

Address Structure:

7 bit Address + R/W bit

Four bits are fixed (0101), three bits (xyz) are variable, and the least-significant bit is the read/write bit.

| 8 bit Address | | |
|---------------|------|-----|
| 0101 | xyz* | R/W |

Table 3: Address structure

Address Selection:

The three bits (xyz) of the address are set with a single external resistor from the ADD (pin10) to LOGIC_GND (pin 13). The 8 possible addresses are shown in Table 4 with the respective resistance values.

| Address for write (R/W=0) | Yxz from Table 3 | R (Ω) |
|---------------------------|------------------|--------|
| 5Eh | 111 | Open |
| 5Ch | 110 | 100000 |
| 5Ah | 101 | 40200 |
| 58h | 100 | 20000 |
| 56h | 011 | 10000 |
| 54h | 010 | 4020 |
| 52h | 001 | 2000 |
| 50h | 000 | Short |

Table 4: I²C Addressing

PIM400 Series; ATCA Board Power Input Modules
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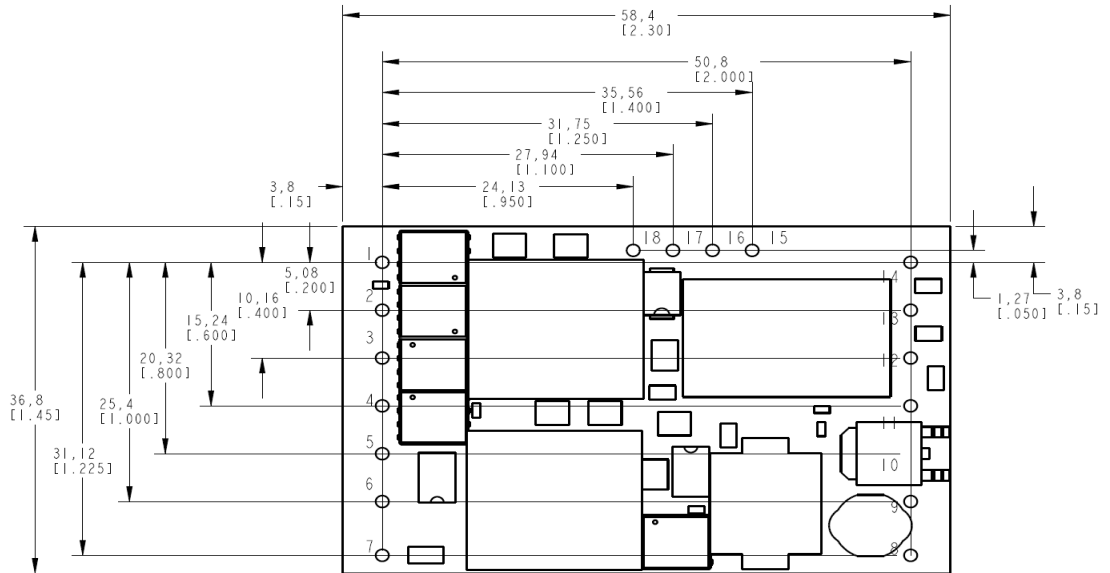
Mechanical Outline

Dimensions are in millimeters and (inches).

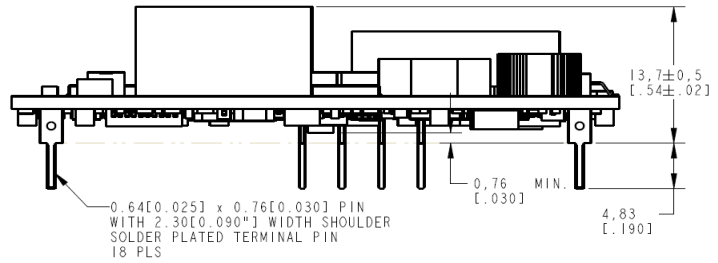
Tolerances: x.x mm ± 0.5 mm (x.xx in. ± 0.02 in.) [unless otherwise indicated]

x.xx mm ± 0.25 mm (x.xxx in. ± 0.010 in.)

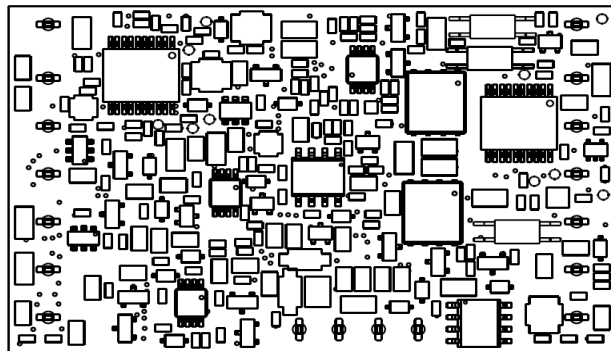
Top View



Side View



Bottom View



PIM400 Series; ATCA Board Power Input Modules

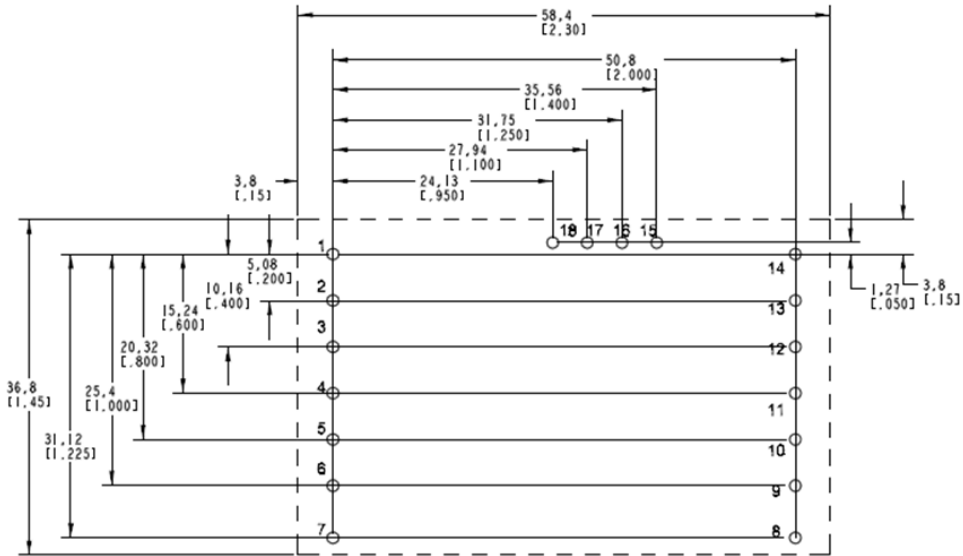
-36 to -75 Vdc; 400W/10A

Recommended Pad Layout

Dimensions are in millimeters and (inches).

Tolerances: x.x mm ± 0.5 mm (x.xx in. ± 0.02 in.) [unless otherwise indicated]

x.xx mm ± 0.25 mm (x.xxx in ± 0.010 in.)



NOTES:

- FOR 0.030" X 0.025" RECTANGULAR PIN, USE 0.050" PLATED THROUGH HOLE

| Pin No. | Signal Name | Pin No. | Signal Name |
|---------|-------------|---------|-------------|
| 1 | -48V_AF | 10* | ADD |
| 2 | -48V_BF | 11* | DAT |
| 3 | VRTN_AF | 12* | CLK |
| 4 | VRTN_BF | 13 | LOGIC_GND |
| 5 | ENABLE_AF | 14 | ALARM |
| 6 | ENABLE_BF | 15 | -48V_OUT |
| 7 | SHELF_GND | 16 | TRIM_HLDP |
| 8 | +5V0 | 17 | VRTN_OUT |
| 9 | +3V3 | 18 | V_HLDP |

* Pins 10, 11 & 12 are present only on modules with I²C digital interface option (-K).

PIM400 Series; ATCA Board Power Input Modules

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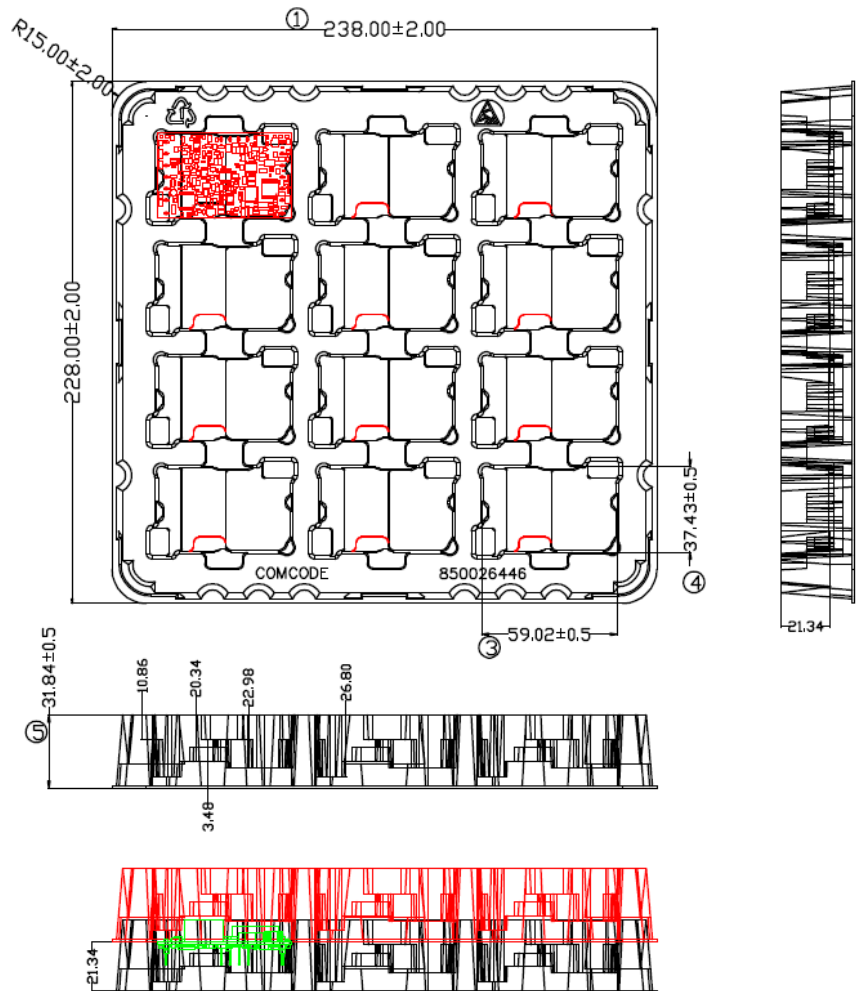
Packaging Details

The modules are supplied as standard in the plastic trays shown in Figure below.

Tray Specification

| | |
|-------------------------|---|
| Material | Antistatic coated PVC |
| Max surface resistivity | $10^{12}\Omega/\text{sq}$ |
| Color | Clear |
| Capacity | 12 power modules |
| Min order quantity | 24 pcs (1 box of 2 full trays + 1 empty top tray) |

Each tray contains a total of 12 power modules. The trays are self-stacking and each shipping box for the modules will contain 2 full trays plus 1 empty hold down tray giving a total number of 24 power modules.



Notes:

1. All radius unspecified are R2.0mm
2. All angle unspecified are 5°
3. Dimension unit: mm(L); A°(A).

PIM400 Series; ATCA Board Power Input Modules

-36 to -75 Vdc; 400W/10A

Ordering Information

Please contact GE's Sales Representative for pricing, availability and optional features.

Table 1. Device Code

| Input Voltage | Current Rating | Auxiliary Output #1 | Auxiliary Output #2 | Options | Product codes | Comcodes |
|----------------|----------------|---------------------|---------------------|--|---------------|-----------|
| -36 to -75 Vdc | 10A | 3.3V/3.6A | 5.0V/0.15A | - | PIM400Z | 150019196 |
| -36 to -75 Vdc | 10A | 3.3V/3.6A | 5.0V/0.15A | I ² C Digital Interface | PIM400KZ | 150019197 |
| -36 to -75 Vdc | 10A | 3.3V/3.6A | 5.0V/0.15A | I ² C Digital Interface & Short pins (3.68mm) | PIM400K6Z | 150033384 |

Table 2. Device Options

| Option | Device Code Suffix |
|---|--------------------|
| Short pins: 3.68mm ± 0.25mm (0.145 in. ± 0.010 in.) | 6 |
| Short pins: 2.79mm ± 0.25mm (0.110 in. ± 0.010 in.) | 8 |
| I ² C Digital Interface | K |

Table 3. Related Products

| Description | Product Code | Comcode |
|---|---------------|-------------|
| PIM400 Evaluation Board | EVAL_PIM400 | 150030502 |
| QBDW033A0B Series Power Modules; DC-DC Converters 36-75V _{dc} Input; 8.1-13.2V _{dc} Output; 33A Output Current | QBDW033A0B41Z | CC109159307 |
| QBVW033A0B Series Power Modules; DC-DC Converters 36-75V _{dc} Input; 8.1-13.2V _{dc} Output; 33A Output Current | QBVW033A0B41Z | CC109165247 |

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