

FEATURES

- Miniature 62-pin cermanic package
- 12-Bit resolution, 50kHz throughput
- Full-scale input range from 50mV to 10V
- Three-state outputs
- 16 S.E. or 8 differential input channels
- Auto-sequencing channel addressing
- MIL-STD-883 versions
- No missing codes

GENERAL DESCRIPTION

Using thin and thick-film hybrid technology, Murata Power Solutions offers complete low-cost data acquisition systems with superior performance and reliability.

The HDAS-8 (with 8 differential input channels) and the HDAS-16 (with 16 single-ended input channels) are complete, high-performance, 12-bit data acquisition systems in 62-pin packages. Each HDAS may be expanded up to 32 single-ended or 16 differential channels by adding externalmultiplexers.

Internal channel address sequencing is automatic after each conversion, or the user may supply external channel addresses.



HDAS-16, HDAS-8

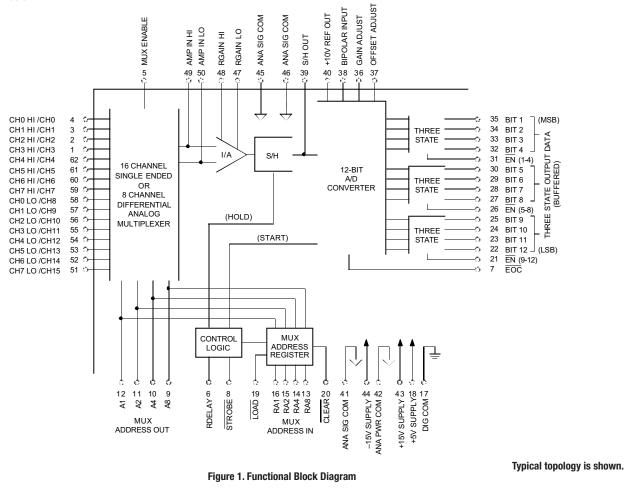
12-Bit, 50kHz, Complete

Data Acquisition Systems

Internal HDAS circuitry includes:

Analog input multiplexer (16 S.E. or 8 diff.)

- Resistor-programmable instrumentation amplifier
- Sample-and-hold circuit complete with MOS hold capacitor
- 10 Volt buffered reference
- 12-bit A/D converter with three-state outputs and control logic



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HDAS-16, HDAS-8

ABSOLUTE MAXIMUM RATINGS

PARAMETERS	MIN.	TYP.	MAX.	UNITS
+15V Supply (pin 43)	-0.5	_	+18	Volts
–15V Supply (pin 44)	+0.5	_	-18	Volts
+5V Supply (pin 18)	-0.5	_	+7	Volts
Analog Inputs 1	-35	_	+35	Volts
DigitalInputs	-0.5	_	+7	Volts
Thermal Resistances:				
Junction-Case	_	-	15	°C/Watt
Case-Ambient	_	-	15	°C/Watt
Junction-Ambient	_	-	30	°C/Watt
Lead Temp. (10 seconds)	-	—	300	°C

FUNCTIONAL SPECIFICATIONS

(The following specifications apply over the operating temperature range and power supply range unless otherwise indicated.)

ANALOG INPUTS	MIN.	TYP.	MAX.	UNITS
Signal Range, Unipolar				
Gain = 1	0	_	+10	Volts
Gain = 200	_	_	+50	mV
Signal Range, Bipolar				
Gain = 1	-10	_	+10	Volts
Gain = 200	-50	_	+50	mV
Input Gain Equation 2	(Gain = 1 + (20) kΩ/RGAIN)
Gain Equation Error	_	_	±0.1	%
Instrumentation Amplifier				
InputImpedance	108	1012	-	Ohms
Input Bias Current:				
+25°C	_	—	±250	pА
–55 to +125°C		Doubles e	very 10°C	
Input Offset Current:				
+25°C			±1	nA
–55 to +125°C		Doubles e	very 10°C	
Multiplexer				
Channel ON Resistance	-	_	2	kΩ
Channel OFF Input Leakage	-	±30	-	рА
Channel OFF Output Leakage	-	±1	-	nA
Channel ON Leakage	-	±100	-	pА
Input Capacitance				_
HDAS-16, Channel ON	-	100	_	pF
HDAS-8, Channel ON	_	50 5	_	pF
+25°C, Channel OFF Input Offset Voltage	-	5	_	pF
Gain = 1,+25°C			±2	mV
$-55 \text{ to } +125^{\circ}\text{C} \text{ (max.)}$	- (+5		$\underline{1}$ \underline{1} $\underline{1}$ $\underline{1}$ \underline{1} $\underline{1}$ \underline{1} $\underline{1}$ \underline{1} $\underline{1}$ \underline{1} $\underline{1}$	
Gain = 200, +25°C	(14		±100	mV
$-55 \text{ to } +125^{\circ}\text{C} \text{ (max.)}$	(+?	Boom/°C v G	ain) ± 20 ppm	
Common Mode Range	±10			Volts
CMRR, Gain = 1, at 60Hz	70	82	_	dB
Input Voltage Noise, Gain = 1				
(Referred to input)	_	150	200	μVrms
Channel Crosstalk	-	-	-80	dB
PERFORMANCE	1	ļ	ļ	
Resolution	12	_	_	Bits
Integral Nonlinearity	.=			
0 to +70°C	_	_	±1	LSB
–55 to +125°C	_	_	±1	LSB
Differential Nonlinearity				
0 to +70°C	_	_	±1	LSB
–55 to +125°C	_	_	±1	LSB
No Missing Codes	Over t	he operating	temperature	range

PERFORMANCE (cont.)	MIN.	TYP.	MAX.	UNITS
Unipolar Zero Error				
+25°C3	_	_	±0.1	%FSR
-55 to +125°C	_	_	±0.1	%FSR
Bipolar Zero Error			10.0	
+25°C ③	l _		±0.1	%FSR
-55 to +125°C			±0.1	%FSR
Bipolar Offset Error			±0.5	/01 011
+25°C ③			±0.1	%FSR
-55 to +125°C			±0.1	%FSR
Gain Error			10.5	
+25°C3	_	_	±0.2	%
-55 to +125°C	_	_	±0.2	%
DYNAMIC CHARACTERIST			10.0	,,,
			i	
Acquisition Time, Gain = 1				
+25°C	-	9	10	μs
-55 to +125°C	-	-	15	μS
Aperture Delay Time	-	-	500	ns
Aperture Uncertainty	-	-	1	ns
S/H Droop Rate	-	-	±1	μV/μs
Feedthrough	-	-	±0.01	%
A/D Conversion Time				
+25°C	-	6	8	μs
-55 to +125°C	-	-	10	μs
Throughput Rate				니트
+25°C	50	66	-	kHz
-55 to +125°C	33	_		kHz
DIGITAL INPUTS				
Logic Levels				
(Pins 8, 13–16, 19–21, 26, 31)				
Logic 1	+2.0	-	+5.5	Volts
Logic 0	0	-	+0.8	Volts
(Pin 5)				
Logic 1	+4.0	-	+5.5	Volts
Logic 0	0	-	+0.8	Volts
Logic Loading				
(Pins 5, 8, 13–16, 19–21,				
26, 31)				
Logic 1	-	-	±10	μΑ
Logic 0 Multiplever Address Set un Time		-	±10	μA
Multiplexer Address Set-upTime	20			ns
ENABLE to Data Valid Delay	40	20	30	ns
	40			ns
OUTPUTS				
Logic Levels (Output Data)				
Logic 1	+2.4	-	-	Volts
Logic 1 (pin 7)	+2.5	-	-	Volts
Logic 0	-	-	+0.4	Volts
(Pins 9, 10, 11, and 12)				
Logic 1	+2.5	-	-	Volts
Logic 0	-	-	+0.4	Volts
Logic Loading				
Logic 1	-	-	-400	μA
Logic 0	-	-	+4	mA
Internal Reference:				
Voltage, +25°C	+9.99	+10.00	+10.01	Volts
Drift	-	-	±20	ppm/°C
Evtornol Current				- mA
External Current Output Data Coding			1) or offset bin	mA

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HDAS-16, HDAS-8

FUNCTIONAL SPECIFICATIONS (Continued)

POWER REQUIREMENTS	MIN.	TYP.	MAX.	UNITS
Power Supply Ranges				
+15V Supply	+14.5	+15.0	+15.5	Volts
-15V Supply	-14.5	-15.0	-15.5	Volts
+5V Suppy	+4.75	+5.0	+5.25	Volts
Power Supply Currents				
+15VSupply	—	—	+33	mA
-15V Supply	—	—	-30	mA
+5VSuppy	—	—	+15	mA
PowerDissipation	—	—	1.25	Watts
PHYSICAL/ENVIRONMENT	AL			
Operating Temp. Range, Case				
MC Models	0	_	+70	°C
MM/883 Models	-55	—	+125	°C
Storage Temperature Range	-65	—	+150	°C
Weight	1.4 ounces (39.7 grams)			
PackageType		62-pin cer	manic DIP	

Footnotes:

- ① Analog inputs will withstand ±35V with power on. If the power is off, the maximum safe input (no damage) is ±20V.
- ② The gain equation error is guaranteed before external trimming and applies at gains less than 50. This error increases at gains over 50.
- 3 Adjustable to zero.
- ③ STROBE pulse width must be less than EOC period to achieve maximum throughput rate.

TECHNICAL NOTES

- 1. Input channels are protected to 20 Volts beyond the powersupplies. All digital output pins have one second short-circuit protection.
- To retain high system throughput rates while digitizing low-level signals, apply external high-gain amplifiers foreach channel. MPS's AM-551 is suggested for such amplifier-per-channel applications.
- 3. The HDAS devices have self-starting circuits for free-running sequential operation. If, however, in a power-upcondition the supply voltage slew rate is less than 3V per microsecond, the free running state might not be initialized. Apply a negative pulse to the STROBE, to eliminate this condition.
- 4. For unipolar operation, connect BIPOLAR INPUT (pin 38) to S/H OUT (pin 39). For bipolar operation, connect BIPOLAR INPUT (pin 38) to +10V REFERENCE OUT (pin 40).
- 5. RDELAY may be a standard value 5% carbon composition or film-type resistor.
- RGAIN must be very accurate with low temperature coefficients. If necessary, fabricate the gain resistor from a precision metal-film type in series with a low value trim resistor or potentiometer. The total resistor temperature coefficient must be no greater than ±10ppm/°C.
- ANALOG SIGNAL COMMON, POWER COMMON and DIGITAL COMMON are connected internally. For optimal performance, tie all ground pins (17, 41, 42, 45, 46) directly to a large analog ground plane beneath the package.
- 8. For HDAS-16, tie pin 50 to a "signal source common" if possible. Otherwise tie pin 50 to pin 41 (ANA SIG COM).

INPUT/OUTPUT CONNECTIONS

	INPUT/OUTPUT CONNECTIO	5/10
PIN NO.	HDAS-16	HDAS-8
$\begin{array}{c}1\\2\\3\\4\\5\\6\\7\\8\\9\\10\\11\\12\\13\\14\\15\\16\\17\\18\\19\\20\\21\\22\\32\\4\\25\\26\\27\\28\\29\\30\\31\\32\\33\\4\\35\\36\\37\\38\\39\\40\\41\\42\end{array}$	HDAS-16 CH3 IN CH2 IN CH1 IN CH0 IN MUX ENABLE RDELAY EOC STROBE A8 MULTIPLEXER A4 A4 ADDRESS A2 OUT A1 RA8 MULTIPLEXER A4 ADDRESS A2 OUT A1 RA8 MULTIPLEXER A4 ADDRESS A2 IN RA1 DIGITAL COMMON +5V SUPPLY LOAD CLEAR ENABLE (Bits 9–12) BIT 12 (LSB) BIT 11 BIT 0 BIT 9 ENABLE (Bits 5–8) BIT 8 BIT 7 BIT 6 BIT 5 ENABLE (Bits 1–4) BIT 4 BIT 3 BIT 2 BIT 1 (MSB) GAIN ADJUST OFFSET ADJUST BIPOLAR INPUT SAMPLE/HOLD OUT +10V REFERENCE OUT ANALOG SIGNAL COMMON ANALOG POWER COMMON	
31 32 33 34 35 36 37 38 39 40 41	ENABLE (Bits 1-4) BIT 4 BIT 3 BIT 2 BIT 1 (MSB) GAIN ADJUST OFFSET ADJUST BIPOLAR INPUT SAMPLE/HOLD OUT +10V REFERENCE OUT ANALOG SIGNAL COMMON	* * * *
43 44 45 46 47 48 49 50 51 52 53 54 55 56 57	+15V SUPPLY -15V SUPPLY ANALOG SIGNAL COMMON ANALOG SIGNAL COMMON RGAIN LOW RGAIN HIGH AMP. IN HIGH ① AMP. IN LOW ① CH15 IN CH15 IN CH14 IN CH13 IN CH12 IN CH11 IN CH10 IN CH9 IN	* * * CH7 LOW IN CH6 LOW IN CH6 LOW IN CH5 LOW IN CH5 LOW IN CH3 LOW IN CH3 LOW IN CH2 LOW IN
58 59 60 61 62	CH8 IN CH7 IN CH6 IN CH5 IN CH4 IN	CH0 LOW IN CH7 HIGH IN CH6 HIGH IN CH5 HIGH IN CH4 HIGH IN

*Same as HDAS-16

Caution: Pins 49 and 50 do not have overvoltage protection; therefore, protected multiplexers, such as MPS's MX-1606 and MX-808 are recommended. See the General Operation description.



HDAS-16, HDAS-8

Table 1. Description of Pin Functions

FUNCTION	LOGIC STATE	DESCRIPTION		
DIGITAL INPUTS				
STROBE	1 to 0	Initiates acquisition and conversion of analog signal		
LOAD	0	Random address mode initiated on falling edge of STROBE		
	1	Sequential address mode		
CLEAR	0	Allows next STROBE pulse to reset MULTIPLEXER ADDRESS to CH0 overriding LOAD COMMAND		
MUX ENABLE	0 1	Disables internal multiplexer Enables internal multiplexer		
MUX ADDRESS IN		Selects channel for random address mode 8, 4, 2, 1 natural binary coding		
DIGITAL OUTPUTS				
EOC (STATUS)	0	Conversion complete		
	1	Conversion in process		
ENABLE (1-4)	0	Enables three-state outputs bits 1-4		
	1	Disables three-state outputs bits 1-4		
ENABLE (5-8)	0	Enables three-state outputs bits 5-8		
	1	Disables three-state outputs bits 5-8		
ENABLE (9–12)	0	Enables three-state outputs bits 9-12		
	1	Disables three-state outputs bits 9-12		
MUX ADDRESS OUT		Output of multiplexer address register 8, 4, 2, 1 natural binary coding		
ANALOG INPUTS		DESCRIPTION		
CHANNEL INPUTS		Limit voltage to ±20V beyond power supplies		
BIPOLAR INPUT		For unipolar operation, connect to pin 39 (S/H OUT). For bipolar operation, connect to in 40 (+10V OUT)		
amp. In Low Amp. In High		These pins are direct inputs to the instrumentation amplifier for external channel expansion beyond 16SE or 8D channels.		
ANALOG OUTPUTS				
S/H OUT		Sample/hold output		
+10V REFERENCE (DUT	Buffered +10V reference output		
ADJUSTMENT PINS				
ANALOG SIGNAL CO	OMMON	Low level analog signal return		
GAIN ADJUSTMENT		External gain adjustment. See calibration instructions.		
OFFSET ADJUSTME	INT	External offset adjustment. See calibration instructions.		
RGAIN		Optional gain selection point. Factory adjusted for G = 1 when left open.		
RDELAY		Optional acquisition time adjustment when connected to $+5V$. Factory adjusted for 9μ s. Must be connected to $+5V$ either directly or through a resistor.		

Table 2. Calibration Table

UNIPOLAR RANGE	ADJUST	INPUT VOLTAGE
0 to +5V	ZERO GAIN	+0.6mV +4.9982V
0 to +10V	ZERO GAIN	+1.2mV +9.9963V
BIPOLAR RANGE		
±2.5V	OFFSET GAIN	-2.4994V +2.4982V
±5V	OFFSET GAIN	-4.9988∨ +4.9963∨
±10V	OFFSET GAIN	-9.9976V +9.9927V

Calibration Procedures

- 1. Offset and gain adjustments are made by connecting two 20k trim potentiometers as shown in Figure 2.
- Connect a precision voltage source to pin 4 (CH0 IN). If the HDAS-8 is used, connect pin 58 (CH0 LOW IN) to analog ground. Ground pin 20 (CLEAR) and momentarily short pin8 (STROBE). Trigger the A/D by connecting pin 7 (EOC) to pin 8 (STROBE). Select proper value for RGAIN and RDELAY by referring to Table 3.
- 3. Adjust the precision voltage source to the value shown in Table 2 for the unipolar zero adjustment (ZERO + 1/2LSB)or the bipolar offset adjustment (-FS + 1/2LSB). Adjust the offset trim potentiometer so that the output code flickers equally between 0000 0000 0000 and 0000 0000 0001.
- 4. Change the output of the precision voltage source to the value shown in Table 2 for the unipolar or bipolar gain adjustment (+FS – 1 1/2LSB). Adjust the gain trim potentiometer so that the output flickers equally between 1111 1111 1110 and 1111 1111 1111.

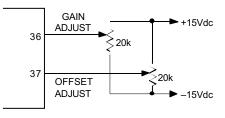


Figure 2. External Adjustment

GENERAL OPERATION

The HDAS devices accept either 16 single-ended or 8 differential input signals. For single-ended circuits, the AMP INLOW (pin 50) input to the instrumentation amplifier must terminate at ANALOG SIGNAL COMMON (pin 41). For differential circuits, both the HIGH and LOW signal inputs must terminate externally for each channel. Tie unused channels to the ANALOG SIGNAL COMMON (pin 41). To obtain additional channels, connect external multiplexers to the AMP IN HIGH (pin 49) and AMP IN LOW (pin 50). Using this scheme, the HDAS-16 can provide 32 single-ended expansion channels. MPS's MX Series multiplexers are recommended.



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The acquisition time is the amount of time the multiplexer, instrumentation amplifier, and sample/hold require to settle within a specified range of accuracy after STROBE (pin 8)goes low. The acquisition time period can be observed by measuring how long $\overline{\text{EOC}}$ is low after the falling edge of $\overline{\text{STROBE}}$ (see Figure 4). For higher gains, increase the acquisition time. Do this by connecting a resistor from RDELAY (pin 6) to +5V (pin 18). An external resistor, RGAIN, can be added to increase the gain value. The gain is equal to 1 without an RGAIN resistor. Table 3 refers to the appropriate RDELAY and RGAIN resistors required for various gains.

The HDAS devices enter the hold mode and are ready for conversion as soon as the one-shot (controling acquisition time) times out. An internal clock is gated ON, and a start-convert pulse is sent to the 12-bit A/D converter,

driving the EOC output high. The HDAS devices can be configured for either bipolar or unipolar operation (see Table 2). The conversion is complete within a maximum of 10 microseconds. The EOC now returns low, the data is valid and sent to the three-state output buffers. The sample/hold amplifier is now ready to acquire new data. The next falling edge of the STROBE pulse repeats the process for the next conversion.

Multiplexer Addressing

The HDAS devices can be configured in either random orsequential addressing modes. Refer to Table 5 and the subsequent descriptions. The number of channels sequentially addressed can be truncated using the MUX ADDRESS OUT(pins 9, 10, 11 and 12) and appropriate decoding circuitry forthe highest channel desired. The decoding circuit can drive the CLEAR (pin 20) function low to reset the addressing to channel 0.

	-	Table 5. Ilipu	Range Farameters (Typica	ai <i>)</i>	
INPUT RANGE ① ②	GAIN	RGAIN (Ω)	RDELAY (Ω) ③	THROUGHPUT ④	SYSTEM ACCURACY (% OF FSR)
±10V	1	OPEN	0 (SHORT)	66.6kHz	±0.009
±5V	2	20.0k	0 (SHORT)	66.6kHz	±0.009
±2.5V	4	6.667k	0 (SHORT)	66.6kHz	±0.009
±1V	10	2.222k	0 (SHORT)	66.6kHz	±0.009
±200mV	50	408.2	7k	40.0kHz	±0.010
±100mV	100	202.0	21k	25.6kHz	±0.011
±50mV	200	100.5	51k	14.5kHz	±0.016

Table 3. Input Range Parameters (Typical)

Notes

 $\mathsf{RGAIN}(\Omega) = \frac{20,000}{(\mathsf{GAIN} - 1)}$

 The analog input range to the A/D converter is 0 to +10V for unipolar signals and ±10V for bipolar signals.

② Full scale can be accommodated for analog signal ranges of ±50mV to ±10V.
 ③ For gains between 1 and 10, RDELAY (pin 6) must be shorted to +5V (pin

RDELAY (Ω) = [Total Acquisition Delay (μ s) x 1000] – 9000 (3) FOr g 18)

Throughput period equals acquisition and settling delay, plus A/D conversion period (10 microseconds maximum).

UNIPOLAR			STRA	GHT B	INARY
INPUT	0 to +10V	0 to +5V	MSB		LSB
+FS – 1LSB	+9.9976	+4.9988	1111	1111	1111
+1/2FS	+5.0000	+2.5000	1000	0000	0000
+1LSB	+0.0024	+0.0012	0000	0000	0001
ZERO	0.0000	0.0000	0000	0000	0000

Table 4. Output Coding

	BIPOLAR	OFFS	Set Bin	IARY*	
INPUT	±10V	±5V	MSB		LSB
+FS – 1LSB +1/2FS +1LSB ZERO -FS + 1LSB -FS	+9.9951 +5.0000 +0.0049 0.0000 -9.9951 -10.000	+4.9976 +2.5000 +0.0024 0.0000 -4.9976 -5.0000	1111 1100 1000 1000 0000 0000	1111 0000 0000 0000 0000 0000	1111 0000 0001 0000 0001 0000

* For 2's complement coding, add an inverter to the MSB line.

Table 5. Mux Channel Addressing

		PIN				
		MUX AI	DDRESS	ᆿ		
5	13	14	15	16	ANN	
MUX ENABLE	RA8	RA4	RA2	RA1	ON CHANNEL	
0	Х	X	Х	Х	NONE	
1	0	0	0	0	0	
1	0	0	0	1	1	
1	0	0	1	0	2	
1	0	0	1	1	3	HDAS-8
1	0	1	0	0	4	(3-BIT ADDRESS)
1	0	1	0	1	5	/12211200)
1	0	1	1	0	6	
1	0	1	1	1	7	
1	1	0	0	0	8	
1	1	0	0	1	9	
1	1	0	1	0	10	HDAS-16
1	1	0	1	1	11	(4-BIT
1	1	1	0	0	12	ADDRESS)
1	1	1	0	1	13	
1	1	1	1	0	14	
1	1	1	1	1	15	



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Random Addressing

Set pin 19 (LOAD) to logic 0. The next falling edge of STROBE will load the MUX CHANNEL ADDRESS present on pin 13 to pin 16. Digital address inputs must be stable 20ns before andafter falling edge of the STROBE pulse.

Free Running Sequential Addressing

Set pin 19 ($\overline{\text{LOAD}}$) and pin 20 ($\overline{\text{CLEAR}}$) to logic 1 or leave open. Connect pin 7 ($\overline{\text{EOC}}$) to pin 8 ($\overline{\text{STROBE}}$). The fallingedge of $\overline{\text{EOC}}$ will increment channel address. This means thatwhen the $\overline{\text{EOC}}$ is low, the digital output data is valid for theprevious channel (CHn – 1) rather than the channel indicated on MUX ADDRESS OUTPUT. The HDAS will continually scan all channels.

Example: CH4 has been addressed and a conversion takes place. The EOC goes low. That channel's (CH4's) data becomes valid, but MUX ADDRESS OUTPUT is now CH5.

Triggered Sequential Addressing

Set pin 19 (LOAD) and pin 20 (CLEAR) to logic 1 or leaveopen. Apply a falling edge trigger pulse to pin 8 (STROBE). This negative transition causes the con-

tents of the address counter to be incremented by one, followed by an A/D conversion in 9 microseconds.

Input Voltage Protection

As shown in Figure 3, the multiplexer has reversed biased diodes which protect the input channels from being damaged by overvoltage signals. The HDAS input channels areprotected up to 20V beyond the supplies and can be increasedby adding series resistors (Ri) to each channel. The input resistor must limit the current flowing through the protection diodes to 10mA.

The value of Ri for a specific voltage protection range (Vp) can be calculated by the following formula:

Vp = (Rsignal + Ri + Ron) (10mA) where Ron = 2k

NOTE: Increased input series resistance will increase multiplexer settling time significantly.

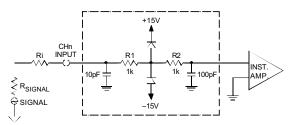


Figure 3. Multiplexer Equivalent Circuit

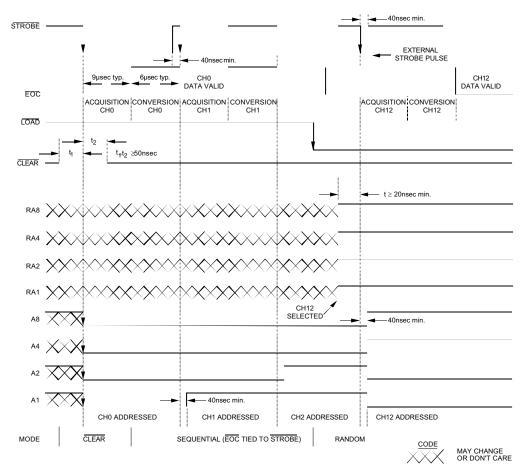


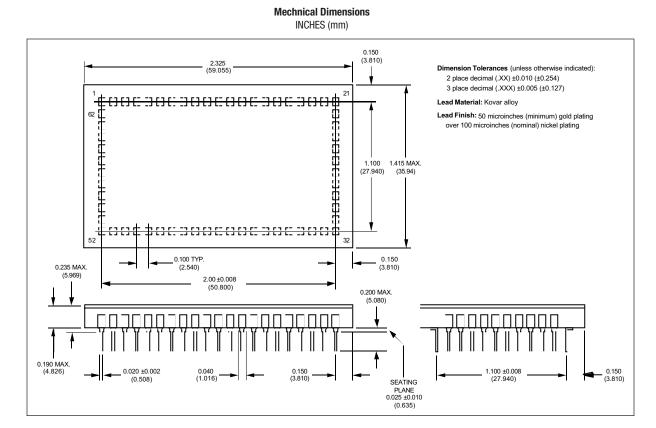
Figure 4. HDAS Timing Diagram



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HDAS-16, HDAS-8



Ordering Information				
Model No.	Operating Temp. Range			
HDAS-16MC 0 to +70°C				
HDAS-16MM	HDAS-16MM -55 to +125°C			
HDAS-16/883 -55 to +125°C				
HDAS-8MC	0 to +70°C			
HDAS-8MM	–55 to +125°C			
HDAS-8/883 -55 to +125°C				
Receptacle for PC board mounting can be ordered through AMP Inc., Part #3-331272-4 (Component Lead Spring Socket), 62 required.				
Contact Murata Power Solutions for MIL-STD-883 product specifications.				





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