HDAS-16, HDAS-8

## FEATURES

Miniature 62-pin cermanic package
12-Bit resolution, 50 kHz throughput
Full-scale input range from 50 mV to 10 V
Three-state outputs
16 S.E. or 8 differential input channels
Auto-sequencing channel addressing
MIL-STD-883 versions
No missing codes

## GENERAL DESCRIPTION

Using thin and thick-film hybrid technology, Murata Power Solutions offers complete low-cost data acquisition systems with superior performance and reliability.

The HDAS-8 (with 8 differential input channels) and the HDAS-16 (with 16 single-ended input channels) are complete, high-performance, 12-bit data acquisition systems in 62-pin packages. Each HDAS may be expanded up to 32 single-ended or 16 differential channels by adding externalmultiplexers.

Internal channel address sequencing is automatic after each conversion, or the user may supply external channel addresses.


Typical topology is shown.
Figure 1. Functional Block Diagram

Internal HDAS circuitry includes:

- Analog input multiplexer (16 S.E. or 8 diff.)

Resistor-programmable instrumentation amplifier
Sample-and-hold circuit complete with MOS hold capacitor
10 Volt buffered reference
12-bit A/D converter with three-state outputs and control logic

ABSOLUTE MAXIMUM RATINGS

| PARAMETERS | MIN. | TYP. | MAX. | UNITS |
| :--- | :---: | :---: | :---: | :---: |
| +15V Supply (pin 43) | -0.5 | - | +18 | Volts |
| -15V Supply (pin 44) | +0.5 | - | -18 | Volts |
| +5V Supply (pin 18) | -0.5 | - | +7 | Volts |
| Analoginputs $(1)$ | -35 | - | +35 | Volts |
| Digitallnputs | -0.5 | - | +7 | Volts |
| Thermal Resistances: | - | - | 15 | ${ }^{\circ} \mathrm{C}$ Watt |
| Junction-Case | - | - | 15 | ${ }^{\circ} \mathrm{C}$ Watt |
| Case-Ambient | - | - | 30 | ${ }^{\circ} \mathrm{C}$ Watt |
| Junction-Ambient | - | - | 300 | ${ }^{\circ} \mathrm{C}$ |
| Lead Temp. (10 seconds) | - |  |  |  |

## FUNCTIONAL SPECIFICATIONS

(The following specifications apply over the operating temperature range and power supply range unless otherwise indicated.)

| ANALOG INPUTS | MIN. | TYP. | MAX. | UNITS |
| :---: | :---: | :---: | :---: | :---: |
| Signal Range, Unipolar |  |  |  |  |
| Gain = 1 | 0 | - | +10 | Volts |
| Gain $=200$ | - | - | +50 | mV |
| Signal Range, Bipolar |  |  |  |  |
| Gain = 1 | -10 | - | +10 | Volts |
| Gain = 200 | -50 | - | +50 | mV |
| Input Gain Equation (2) | Gain $=1+(20 \mathrm{k} \Omega / \mathrm{RGAIN})$ |  |  |  |
| Gain Equation Error | - | - | $\pm 0.1$ | \% |
| Instrumentation Amplifier InputImpedance | 108 | 1012 | - | Ohms |
| Input Bias Current: |  |  |  |  |
| $+25^{\circ} \mathrm{C}$ | - | - | $\pm 250$ | pA |
| -55 to $+125^{\circ} \mathrm{C}$ | Doubles every $10^{\circ} \mathrm{C}$ |  |  |  |
| Input Offset Current: $+25^{\circ} \mathrm{C}$ | - | - | $\pm 1$ | nA |
| -55 to $+125^{\circ} \mathrm{C}$ | Doubles every $10^{\circ} \mathrm{C}$ |  |  |  |
| Multiplexer |  |  |  |  |
| Channel ON Resistance | - | - | 2 | k $\Omega$ |
| Channel OFF Input Leakage | - | $\pm 30$ | - | pA |
| Channel OFF Output Leakage | - | $\pm 1$ | - | nA |
| Channel ON Leakage | - | $\pm 100$ | - | pA |
| Input Capacitance |  |  |  |  |
| HDAS-16, Channel ON | - | 100 | - | pF |
| HDAS-8, Channel ON | - | 50 | - | pF |
| $+25^{\circ} \mathrm{C}$, Channel OFF | - | 5 | - | pF |
| Input Offset Voltage |  |  |  |  |
| Gain $=1,+25^{\circ} \mathrm{C}$ - - $\pm 2$ mV |  |  |  |  |
| -55 to $+125^{\circ} \mathrm{C}$ (max.) | ( $\pm 3 \mathrm{ppm} /{ }^{\circ} \mathrm{C} \times$ Gain) $\pm 20 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ |  |  |  |
| Gain $=200,+22^{\circ} \mathrm{C}$$\quad-55$ to $+125^{\circ} \mathrm{C}$ (max.) | - | - | $\pm 100$ | mV |
|  | $\left( \pm 3 \mathrm{ppm} /{ }^{\circ} \mathrm{C} \times\right.$ Gain $) \pm 20 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ |  |  |  |
| Common Mode Range | $\pm 10$ | - | - | Volts |
| CMRR, Gain $=1$, at 60 Hz | 70 | 82 | - | dB |
| Input Voltage Noise, Gain =1 <br> (Referred to input) | - | 150 | 200 | $\mu \mathrm{V} \mathrm{rms}$ |
| Channel Crosstalk | - | - | -80 | dB |
| PERFORMANCE |  |  |  |  |
| Resolution | 12 | - | - | Bits |
| Integral Nonlinearity |  |  |  |  |
| 0 to $+70^{\circ} \mathrm{C}$ | - | - | $\pm 1$ | LSB |
| -55 to $+125^{\circ} \mathrm{C}$ | - | - | $\pm 1$ | LSB |
| Differential Nonlinearity |  |  |  |  |
| 0 to $+70^{\circ} \mathrm{C}$ | - | - | $\pm 1$ | LSB |
| -55 to $+125^{\circ} \mathrm{C}$ | - | - | $\pm 1$ | LSB |
| No Missing Codes | Over the operating temperature range |  |  |  |


| PERFORMANCE (cont.) | MIN. | TYP. | MAX. | UNITS |
| :--- | :---: | :---: | :---: | :---: |
| Unipolar Zero Error |  |  |  |  |
| $+25^{\circ} \mathrm{C} 3$ | - | - | $\pm 0.1$ | $\%$ FSR |
| -55 to $+125^{\circ} \mathrm{C}$ | - | - | $\pm 0.3$ | $\%$ FSR |
| Bipolar Zero Error | - | - | $\pm 0.1$ | $\%$ FSR |
| $+25^{\circ} \mathrm{C} 3$ | - | - | $\pm 0.3$ | $\%$ FSR |
| -55 to $+125^{\circ} \mathrm{C}$ | - |  |  |  |
| Bipolar Offset Error | - | - | $\pm 0.1$ | $\%$ FSR |
| $+25^{\circ} \mathrm{C} 3$ | - | - | $\pm 0.3$ | $\%$ FSR |
| -55 to $+125^{\circ} \mathrm{C}$ | - | - | $\pm 0.2$ | $\%$ |
| Gain Error | $-25^{\circ} \mathrm{C} 3$ | - | - | $\pm 0.3$ |
| -55 to $+125^{\circ} \mathrm{C}$ |  |  |  |  |

DYNAMIC CHARACTERISTICS

| Acquisition Time, Gain =1 |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: |
| $\quad+25^{\circ} \mathrm{C}$ | - | 9 | 10 | $\mu \mathrm{~s}$ |
| $\quad-55$ to $+125^{\circ} \mathrm{C}$ | - | - | 15 | $\mu \mathrm{~s}$ |
| Aperture Delay Time | - | - | 500 | ns |
| Aperture Uncertainty | - | - | 1 | ns |
| S/H Droop Rate | - | - | $\pm 1$ | $\mu \mathrm{~V} / \mu \mathrm{s}$ |
| Feedthrough <br> A/D Conversion Time <br> $\quad+25^{\circ} \mathrm{C}$ <br> -55 to $+125^{\circ} \mathrm{C}$ <br> ThroughputRate <br> $+25^{\circ} \mathrm{C}$ <br> $\quad-55$ to $+125^{\circ} \mathrm{C}$ | - | - | $\pm 0.01$ | $\%$ |

## DIGITAL INPUTS

| Logic Levels <br> (Pins 8, 13-16, 19-21, 26, 31) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Logic 1 | +2.0 | - | +5.5 | Volts |
| Logic 0 | 0 | - | +0.8 | Volts |
| (Pin 5) |  |  |  |  |
| Logic 1 | +4.0 | - | +5.5 | Volts |
| Logic 0 | 0 | - | +0.8 | Volts |
| Logic Loading |  |  |  |  |
| $\begin{aligned} & \text { (Pins } 5,8,13-16,19-21, \\ & 26,31 \text { ) } \end{aligned}$ |  |  |  |  |
| Logic 1 | - | - | $\pm 10$ | $\mu \mathrm{A}$ |
| Logic 0 | - | - | $\pm 10$ | $\mu \mathrm{A}$ |
| Multiplexer Address Set-up Time | 20 | - | - | ns |
| ENABLE to Data Valid Delay | - | 20 | 30 | ns |
| STROBE (4) | 40 | - | - | ns |
| OUTPUTS |  |  |  |  |
| Logic Levels (OutputData) |  |  |  |  |
| Logic 1 | +2.4 | - | - | Volts |
| Logic 1 (pin 7) | +2.5 | - | - | Volts |
| Logic 0 | - | - | +0.4 | Volts |
| (Pins 9, 10, 11, and 12) |  |  |  |  |
| Logic 1 | +2.5 | - | - | Volts |
| Logic 0 | - | - | +0.4 | Volts |
| Logic Loading |  |  |  |  |
| Logic 1 | - | - | -400 | $\mu \mathrm{A}$ |
| Logic 0 | - | - | +4 | mA |
| Internal Reference: |  |  |  |  |
| Voltage, $+25^{\circ} \mathrm{C}$ | +9.99 | +10.00 | +10.01 | Volts |
| Drift | - | - | $\pm 20$ | ppm $/{ }^{\circ} \mathrm{C}$ |
| External Current | - | - | 1 | mA |
| Output Data Coding | aigh | (unipola) |  | bipolar |

FUNCTIONAL SPECIFICATIONS (Continued)

| POWER REQUIREMENTS | MIN. | TYP. | MAX. | UNITS |  |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Power Supply Ranges |  |  |  |  |  |
| +15VSupply | +14.5 | +15.0 | +15.5 | Volts |  |
| -15VSupply | -14.5 | -15.0 | -15.5 | Volts |  |
| +5V Suppy | +4.75 | +5.0 | +5.25 | Volts |  |
| Power Supply Currents |  |  |  |  |  |
| +15VSupply | - | - | +33 | mA |  |
| -15VSupply | - | - | -30 | mA |  |
| +5V Suppy | - | - | +15 | mA |  |
| PowerDissipation | - | - | 1.25 | Watts |  |
| PHYSICAL/ENVIRONMENTAL |  |  |  |  |  |
| Operating Temp. Range, Case |  |  |  |  |  |
| MC Models |  |  |  |  |  |
| MM/883 Models | 0 | - | +70 | ${ }^{\circ} \mathrm{C}$ |  |
| StorageTemperature Range | -55 | - | +125 | ${ }^{\circ} \mathrm{C}$ |  |
| Weight | -65 | - | +150 | ${ }^{\circ} \mathrm{C}$ |  |
|  |  |  |  |  |  |
| Package Type | 1.4 ounces (39.7 grams) |  |  |  |  |

Footnotes:
(1) Analog inputs will withstand $\pm 35 \mathrm{~V}$ with power on. If the power is off, the maximum safe input (no damage) is $\pm 20 \mathrm{~V}$.
(2) The gain equation error is guaranteed before external trimming and applies at gains less than 50. This error increases at gains over 50.
(3) Adjustable to zero.
(4) STROBE pulse width must be less than EOC period to achieve maximum throughput rate.

## TECHNICAL NOTES

1. Input channels are protected to 20 Volts beyond the powersupplies. All digital output pins have one second short-circuit protection.
2. To retain high system throughput rates while digitizing low-level signals, apply external high-gain amplifiers foreach channel. MPS's AM-551 is suggested for such amplifier-per-channel applications.
3. The HDAS devices have self-starting circuits for free-running sequential operation. If, however, in a power-upcondition the supply voltage slew rate is less than 3 V per microsecond, the free running state might not be initialized. Apply a negative pulse to the $\overline{\text { STROBE, }}$, to eliminate this condition.
4. For unipolar operation, connect BIPOLAR INPUT (pin 38) to S/H OUT (pin 39). For bipolar operation, connect BIPOLAR INPUT (pin 38) to +10V REFERENCE OUT (pin 40).
5. RDELAY may be a standard value $5 \%$ carbon composition or film-type resistor.
6. RGAIN must be very accurate with low temperature coefficients. If necessary, fabricate the gain resistor from a precision metal-film type in series with a low value trim resistor or potentiometer. The total resistor temperature coefficient must be no greater than $\pm 10 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$.
7. ANALOG SIGNAL COMMON, POWER COMMON and DIGITAL COMMON are connected internally. For optimal performance, tie all ground pins $(17,41$, $42,45,46)$ directly to a large analog ground plane beneath the package.
8. For HDAS-16, tie pin 50 to a "signal source common" if possible. Otherwise tie pin 50 to pin 41 (ANA SIG COM).

INPUT/OUTPUT CONNECTIONS

| PIN NO. | HDAS-16 | HDAS-8 |
| :---: | :---: | :---: |
| 1 | CH3 IN | CH3 HIGH IN |
| 2 | CH 2 IN | CH2 HIGH IN |
| 3 | CH1 IN | CH1 HIGH IN |
| 4 | CHO IN | CHO HIGH IN |
| 5 | MUX ENABLE | * |
| 6 | RDELAY | * |
| 7 | EOC | * |
| 8 | STROBE | * |
| 9 | A8 MULTIPLEXER | * |
| 10 | A4 ADDRESS | * |
| 11 | A2 OUT | * |
| 12 | A1 | * |
| 13 | RA8 MULTIPLEXER | * |
| 14 | RA4 ADDRESS | * |
| 15 | RA2 IN | * |
| 16 | RA1 | * |
| 17 | DIGITAL COMMON | * |
| 18 | +5V SUPPLY | * |
| 19 | LOAD | * |
| 20 | CLEAR | * |
| 21 | ENABLE (Bits 9-12) | * |
| 22 | BIT 12 (LSB) | * |
| 23 | BIT 11 | * |
| 24 | BIT 10 | * |
| 25 | BIT 9 | * |
| 26 | ENABLE (Bits 5-8) | * |
| 27 | BIT 8 | * |
| 28 | BIT 7 | * |
| 29 | BIT 6 | * |
| 30 | BIT 5 | * |
| 31 | ENABLE (Bits 1-4) | * |
| 32 | BIT 4 | * |
| 33 | BIT 3 | * |
| 34 | BIT 2 | * |
| 35 | BIT 1 (MSB) | * |
| 36 | GAIN ADJUST | * |
| 37 | OFFSET ADJUST | * |
| 38 | BIPOLAR INPUT | * |
| 39 | SAMPLE/HOLD OUT | * |
| 40 | +10V REFERENCE OUT | * |
| 41 | ANALOG SIGNAL COMMON | * |
| 42 | ANALOG POWER COMMON | * |
| 43 | +15V SUPPLY |  |
| 44 | -15V SUPPLY | * |
| 45 | ANALOG SIGNAL COMMON | * |
| 46 | ANALOG SIGNAL COMMON | * |
| 47 | RGAIN LOW | * |
| 48 | RGAIN HIGH | * |
| 49 | AMP. IN HIGH (1) | * |
| 50 | AMP. IN LOW ${ }^{1}$ | * |
| 51 | CH15 IN | CH7 LOW IN |
| 52 | CH14 IN | CH6 LOW IN |
| 53 | CH13 IN | CH5 LOW IN |
| 54 | CH12 IN | CH4 LOW ${ }^{\text {N }}$ |
| 55 | CH11 IN | CH3 LOW ${ }^{\text {N }}$ |
| 56 | CH10 IN | CH2 LOW IN |
| 57 | CH9 IN | CH1 LOW ${ }^{\text {N }}$ |
| 58 | CH8 IN | CH0 LOW IN |
| 59 | CH 7 IN | CH7 HIGH IN |
| 60 | CH6 IN | CH6 HIGH IN |
| 61 | CH5 IN | CH5 HIGH IN |
| 62 | CH4 IN | CH4 HIGH IN |

*Same as HDAS-16
Caution: Pins 49 and 50 do not have overvoltage protection; therefore, protected multiplexers, such as MPS's MX-1606 and MX-808 are recommended. See the General Operation description.

Table 1. Description of Pin Functions

| FUNCTION | LOGIC <br> STATE | DESCRIPTION |
| :--- | :---: | :--- |
| DIGITAL INPUTS |  |  |
| STROBE | 1 to 0 | Initiates acquisition and conversion <br> of analog signal |
| LOAD | 0 | Random address mode initiated on <br> falling edge of STROBE |
|  | 1 | Sequential address mode |
| $\overline{\text { CLEAR }}$ | 0 | Allows next STROBE pulse to reset <br> MULTIPLEXER ADDRESS to CH0 <br> overriding LOAD COMMAND |
| MUX ENABLE | 0 | Disables internal multiplexer <br> Enables internal multiplexer |
| MUX ADDRESS IN | 1 | Selects channel for random <br> address mode 8, 4, 2, 1 <br> natural binary coding |
| DIGITAL OUTPUTS |  |  |
| EOC (STATUS) | 0 | Conversion complete |
| RFFSET ADJUSTMENT | 1 | Conversion in process |
| ENABLE (1-4) | 0 | Enables three-state outputs bits 1-4 |

Table 2. Calibration Table

| UNIPOLAR RANGE | ADJUST | INPUT VOLTAGE |
| :---: | :---: | :---: |
| 0 to +5 V | $\begin{aligned} & \text { ZERO } \\ & \text { GAIN } \end{aligned}$ | $\begin{aligned} & +0.6 \mathrm{mV} \\ & +4.9982 \mathrm{~V} \end{aligned}$ |
| 0 to +10V | ZERO GAIN | $\begin{aligned} & +1.2 \mathrm{mV} \\ & +9.9963 \mathrm{~V} \end{aligned}$ |
| BIPOLAR RANGE |  |  |
| $\pm 2.5 \mathrm{~V}$ | OFFSET GAIN | $\begin{aligned} & -2.4994 \mathrm{~V} \\ & +2.4982 \mathrm{~V} \end{aligned}$ |
| $\pm 5 \mathrm{~V}$ | OFFSET GAIN | $\begin{array}{r} -4.9988 \mathrm{~V} \\ +4.9963 \mathrm{~V} \\ \hline \end{array}$ |
| $\pm 10 \mathrm{~V}$ | OFFSET GAIN | $\begin{aligned} & -9.9976 \mathrm{~V} \\ & +9.9927 \mathrm{~V} \end{aligned}$ |

## Calibration Procedures

1. Offset and gain adjustments are made by connecting two 20k trim potentiometers as shown in Figure 2.
2. Connect a precision voltage source to pin 4 (CHO IN). If the HDAS-8 is used, connect pin 58 (CHO LOW IN) to analog ground. Ground pin 20 ( $\overline{\text { CLEAR }}$ ) and momentarily short pin8 ( $\overline{\mathrm{STROBE}}$ ). Trigger the A/D by connecting pin 7 (EOC) to pin 8 (STROBE). Select proper value for RGAIN and RDELAY by referring to Table 3.
3. Adjust the precision voltage source to the value shown in Table 2 for the unipolar zero adjustment (ZERO $+1 / 2 L S B$ )or the bipolar offset adjustment (-FS + 1/2LSB). Adjust the offset trim potentiometer so that the output code flickers equally between 000000000000 and 000000000001.
4. Change the output of the precision voltage source to the value shown in Table 2 for the unipolar or bipolar gain adjustment (+FS - 1 1/2LSB). Adjust the gain trim potentiometer so that the output flickers equally between 111111111110 and 111111111111.


Figure 2. External Adjustment

## GENERAL OPERATION

The HDAS devices accept either 16 single-ended or 8 differential input signals. For single-ended circuits, the AMP INLOW (pin 50) input to the instrumentation amplifier must terminate at ANALOG SIGNAL COMMON (pin 41). For differential circuits, both the HIGH and LOW signal inputs must terminate externally for each channel. Tie unused channels to the ANALOG SIGNAL COMMON (pin 41). To obtain additional channels, connect external multiplexers to the AMP IN HIGH (pin 49) and AMP IN LOW (pin 50). Using this scheme, the HDAS-16 can provide 32 single-ended expansion channels while the HDAS-8 can provide up to 16 differential expansion channels. MPS's MX Series multiplexers are recommended.

The acquisition time is the amount of time the multiplexer, instrumentation amplifier, and sample/hold require to settle within a specified range of accuracy after STROBE (pin 8)goes low. The acquisition time period can be observed by measuring how long EOC is low after the falling edge of STROBE (see Figure 4). For higher gains, increase the acquisition time. Do this by connecting a resistor from RDELAY (pin 6 ) to +5 V (pin 18). An external resistor, RGAIN, can be added to increase the gain value. The gain is equal to 1 without an RGAIN resistor. Table 3 refers to the appropriate RDELAY and RGAIN resistors required for various gains.

The HDAS devices enter the hold mode and are ready for conversion as soon as the one-shot (controling acquisition time) times out. An internal clock is gated ON , and a start-convert pulse is sent to the 12-bit A/D converter,
driving the $\overline{\mathrm{EOC}}$ output high.The HDAS devices can be configured for either bipolar or unipolar operation (see Table 2). The conversion is complete within a maximum of 10 microseconds. The EOC now returns low, the data is valid and sent to the three-state output buffers. The sample/hold amplifier is now ready to acquire new data.The next falling edge of the STROBE pulse repeats the process for the next conversion.

## Multiplexer Addressing

The HDAS devices can be configured in either random orsequential addressing modes. Refer to Table 5 and the subsequent descriptions. The number of channels sequentially addressed can be truncated using the MUX ADDRESS OUT(pins $9,10,11$ and 12) and appropriate decoding circuitry forthe highest channel desired. The decoding circuit can drive the $\overline{C L E A R}$ (pin 20) function low to reset the addressing to channel 0 .

Table 3. Input Range Parameters (Typical)

| INPUT <br> RANGE (1) (2) | GAIN | $\operatorname{RGAIN}(\Omega)$ | RDELAY $(\Omega)$ (3) | THROUGHPUT (4) | SYSTEM ACCURACY <br> (\% OF FSR) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\pm 10 \mathrm{~V}$ | 1 | $\operatorname{OPEN}$ | $0($ SHORT $)$ | 66.6 kHz | $\pm 0.009$ |
| $\pm 5 \mathrm{~V}$ | 2 | 20.0 k | 0 (SHORT) | 66.6 kHz | $\pm 0.009$ |
| $\pm 2.5 \mathrm{~V}$ | 4 | 6.667 k | $0($ SHORT $)$ | 66.6 kHz | $\pm 0.009$ |
| $\pm 1 \mathrm{~V}$ | 10 | 2.222 k | $0($ SHORT $)$ | 66.6 kHz | $\pm 0.009$ |
| $\pm 200 \mathrm{mV}$ | 50 | 408.2 | 7 k | 40.0 kHz | $\pm 0.010$ |
| $\pm 100 \mathrm{mV}$ | 100 | 202.0 | 21 k | 25.6 kHz | $\pm 0.011$ |
| $\pm 50 \mathrm{mV}$ | 200 | 100.5 | 51 k | 14.5 kHz | $\pm 0.016$ |

## Notes

$\operatorname{RGAIN}(\Omega)=\frac{20,000}{(\operatorname{GAIN}-1)}$
$\operatorname{RDELAY}(\Omega)=[$ Total Acquisition Delay $(\mu \mathrm{s}) \times 1000]-9000$
(1) The analog input range to the A/D converter is 0 to +10 V for unipolar signals and $\pm 10 \mathrm{~V}$ for bipolar signals.
(2) Full scale can be accommodated for analog signal ranges of $\pm 50 \mathrm{mV}$ to $\pm 10 \mathrm{~V}$.
(3) For gains between 1 and 10, RDELAY (pin 6 ) must be shorted to +5 V (pin 18).
(4) Throughput period equals acquisition and settling delay, plus A/D conversion period ( 10 microseconds maximum).

Table 4. Output Coding

| UNIPOLAR |  |  | STRAIGHT BINARY |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: |
| INPUT | $\mathbf{0}$ to +10V | $\mathbf{0}$ to +5V | MSB |  | LSB |
| +FS - 1LSB | +9.9976 | +4.9988 | 1111 | 1111 | 1111 |
| $+1 / 2 F S$ | +5.0000 | +2.5000 | 1000 | 0000 | 0000 |
| +1LSB | +0.0024 | +0.0012 | 0000 | 0000 | 0001 |
| ZERO | 0.0000 | 0.0000 | 0000 | 0000 | 0000 |


| BIPOLAR |  |  | OFFSET BINARY |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: |
| INPUT | $\mathbf{\pm 1 0 V}$ | $\pm 5 V$ | MSB | LSB |  |
| +FS - 1LSB | +9.9951 | +4.9976 | 1111 | 1111 | 1111 |
| +1/2FS | +5.0000 | +2.5000 | 1100 | 0000 | 0000 |
| +1LSB | +0.0049 | +0.0024 | 1000 | 0000 | 0001 |
| ZERO | 0.0000 | 0.0000 | 1000 | 0000 | 0000 |
| -FS + 1LSB | -9.9951 | -4.9976 | 0000 | 0000 | 0001 |
| -FS | -10.000 | -5.0000 | 0000 | 0000 | 0000 |

* For 2's complement coding, add an inverter to the MSB line.

Table 5. Mux Channel Addressing

| PIN |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MUX ADDRESS |  |  |  |  |  |
| 5 | 13 | 14 | 15 | 16 |  |  |
| $\begin{gathered} \hline \text { MUX } \\ \text { ENABLE } \end{gathered}$ | RA8 | RA4 | RA2 | RA1 |  |  |
| 0 | X | X | X | X | NONE |  |
| 1 | 0 | 0 | 0 | 0 | 0 |  |
| 1 | 0 | 0 | 0 | 1 | 1 |  |
| 1 | 0 | 0 | 1 | 0 | 2 |  |
| 1 | 0 | 0 | 1 | 1 | 3 | HDAS-8 |
| 1 | 0 | 1 | 0 | 0 | 4 | ADDRESS) |
| 1 | 0 | 1 | 0 | 1 | 5 |  |
| 1 | 0 | 1 | 1 | 0 | 6 |  |
| 1 | 0 | 1 | 1 | 1 | 7 |  |
| 1 | 1 | 0 | 0 | 0 | 8 |  |
| 1 | 1 | 0 | 0 | 1 | 9 |  |
| 1 | 1 | 0 | 1 | 0 | 10 |  |
| 1 | 1 | 0 | 1 | 1 | 11 | (4-BIT |
| 1 | 1 | 1 | 0 | 0 | 12 | ADDRESS) |
| 1 | 1 | 1 | 0 | 1 | 13 |  |
| 1 | 1 | 1 | 1 | 0 | 14 |  |
| 1 | 1 | 1 | 1 | 1 | 15 |  |

## Random Addressing

Set pin 19 (LOAD) to logic 0 . The next falling edge of $\overline{\text { STROBE }}$ will load the MUX CHANNEL ADDRESS present on pin 13 to pin 16. Digital address inputs must be stable 20 ns before andafter falling edge of the STROBE pulse.

## Free Running Sequential Addressing

Set pin 19 ( $\overline{\mathrm{LOAD}})$ and pin 20 ( $\overline{\mathrm{CLEAR})}$ to logic 1 or leave open. Connect pin 7 (EOC) to pin 8 (STROBE). The fallingedge of $\overline{\text { EOC }}$ will increment channel address. This means thatwhen the EOC is low, the digital output data is valid for theprevious channel ( $\mathrm{CHn}-1$ ) rather than the channel indicated on MUX ADDRESS OUTPUT. The HDAS will continually scan all channels.

Example: CH 4 has been addressed and a conversion takes place. The $\overline{\mathrm{EOC}}$ goes low. That channel's (CH4's) data becomes valid, but MUX ADDRESS OUTPUT is now CH5.

## Triggered Sequential Addressing

Set pin 19 ( $\overline{\text { LOAD }})$ and pin 20 (CLEAR) to logic 1 or leaveopen. Apply a falling edge trigger pulse to pin 8 (STROBE).This negative transition causes the con-
tents of the address counter to be incremented by one, followed by an A/D conversion in 9 microseconds.

## Input Voltage Protection

As shown in Figure 3, the multiplexer has reversed biased diodes which protect the input channels from being damaged by overvoltage signals. The HDAS input channels areprotected up to 20V beyond the supplies and can be increasedby adding series resistors (Ri) to each channel. The input resistor must limit the current flowing through the protection diodes to 10 mA .

The value of Ri for a specific voltage protection range (Vp) can be calculated by the following formula:

$$
\text { Vp }=(\text { Rsignal }+\mathrm{Ri}+\text { Ron })(10 \mathrm{~mA}) \text { where Ron }=2 k
$$

NOTE: Increased input series resistance will increase multiplexer settling time significantly.


Figure 3. Multiplexer Equivalent Circuit


Figure 4. HDAS Timing Diagram

Mechnical Dimensions
INCHES (mm)


| Ordering Information |  |
| :--- | :--- |
| Model No. | Operating Temp. Range |
| HDAS-16MC | 0 to $+70^{\circ} \mathrm{C}$ |
| HDAS-16MM | -55 to $+125^{\circ} \mathrm{C}$ |
| HDAS-16/883 | -55 to $+125^{\circ} \mathrm{C}$ |


| HDAS-8MC | 0 to $+70^{\circ} \mathrm{C}$ |
| :--- | :--- |
| HDAS-8MM | -55 to $+125^{\circ} \mathrm{C}$ |
| HDAS-8/883 | -55 to $+125^{\circ} \mathrm{C}$ |

Receptacle for PC board mounting can be ordered through AMP Inc., Part \#3-331272-4 (Component Lead Spring Socket), 62 required.

Contact Murata Power Solutions for MIL-STD-883 product specifications.


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## Murata Power Solutions

Murata Power Solutions, Inc.
11 Cabot Boulevard, Mansfield, MA 02048-1151 U.S.A.
Tel: (508) 339-3000 (800) 233-2765 Fax: (508) 339-6356
www.murata-ps.com email: sales@murata-ps.com
ISO 9001 REGISTERED

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| USA: | Tucson (AZ), Tel: (800) 547 2537, email: sales@murata-ps.com |
| :--- | :--- |
| Canada: | Toronto, Tel: (866) 740 1232, email: toronto@murata-ps.com |
| UK: | Milton Keynes, Tel: +44 (0)1908 615232, email: mk@murata-ps.com |
| France: | Montigny Le Bretonneux, Tel: +33 (0)1 346001 01, email: france@murata-ps.com |
| Germany: | München, Tel: +49 (0)89-544334-0, email: ped.munich@murata-ps.com |
| Japan: | Tokyo, Tel: 3-3779-1031, email: sales_tokyo@murata-ps.com |
|  | Osaka, Tel: 6-6354-2025, email: sales_osaka@murata-ps.com |
|  | Website: www.murata-ps.jp |
| China: | Shanghai, Tel: +86 215 027 3678, email: shanghai@murata-ps.com |
|  | Guangzhou, Tel: +86 208 221 8066, email: guangzhou@murata-ps.com |

(AZ), Tel. (800) 547 2537, emall. sales@murata-ps.com
Canada: Toronto, Tel: (866) 740 1232, email: toronto@murata-ps.com
UK:
France: Montigny Le Bretonneux, Tel: +33 (0)1 346001 01, email: france@murata-ps.com
Germany: München, Tel: +49 (0)89-544334-0, email: ped.munich@murata-ps.com
Japan: Tokyo, Tel: 3-3779-1031, email: sales_tokyo@murata-ps.com Osaka, Tel: 6-6354-2025, email: sales_osaka@murata-ps.com Website: www.murata-ps.jp
China: Shanghai, Tel: +86 215027 3678, email: shanghai@murata-ps.com Guangzhou, Tel: +86 208221 8066, email: guangzhou@murata-ps.com

