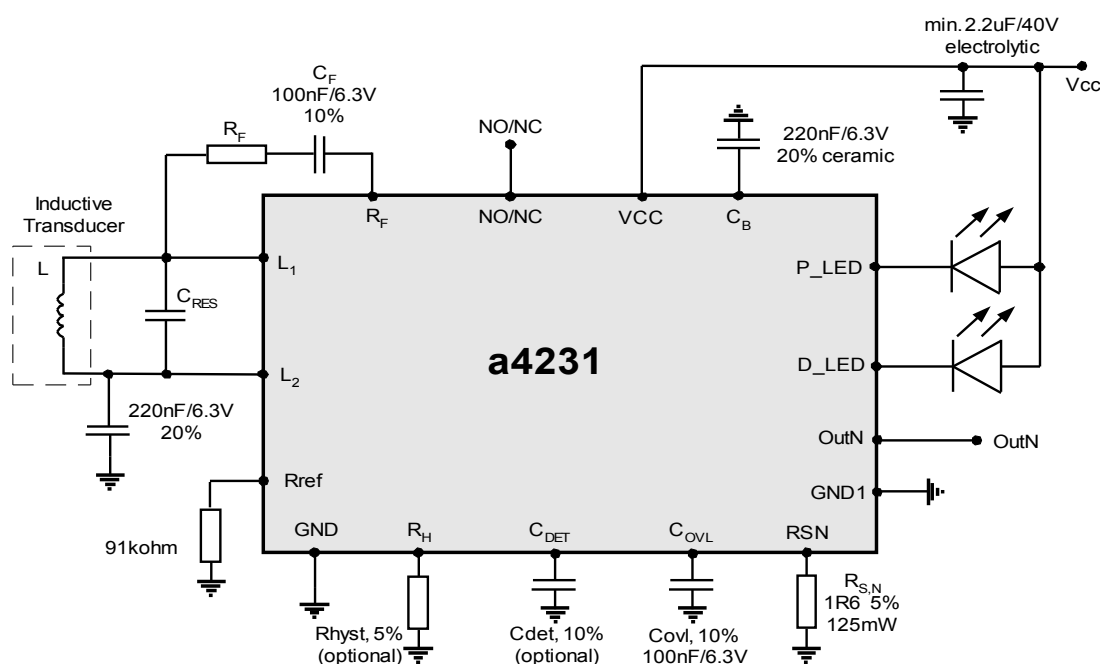


## a4231 general features

The a4231 is a proximity sensor integrated circuit to be used with a broad range of inductive single-coiled proximity transducers in proximity detection applications

- ☐ Monolithic IC in bipolar technology
- ☐ User-adjustable sensing range by means of a single external resistor
- ☐ User-adjustable hysteresis (0...15%)
- ☐ 5.5V...35V broad supply voltage range
- ☐ Low-voltage operation possible using stabilised 4.5V...5.5V voltage source
- ☐ Internal voltage regulator to improve immunity against fluctuations of supply voltage
- ☐ Broad operating temperature range: -25°C...90°C
- ☐ Can work with a broad selection of inductive transducers
- ☐ NPN open collector output with guaranteed sink current of 150mA
- ☐ Output overload/over current protection
- ☐ Integrated power-on and detect LED drivers
- ☐ Normally open(NO)/normally closed(NC) select pin
- ☐ Broad range of operating frequencies: 100kHz...1MHz
- ☐ Output over current and short-circuit protection
- ☐ Easy temperature compensation of proximity transducers
- ☐ Package – QFN-24

## example application schematic



Typical application schematic of a proximity sensor/detector

## electrical characteristics

### DC Characteristics

The typical values are given for  $V_{CC} = 24V$  and  $T_j = 25^\circ C$  unless otherwise specified.

#	Symbol	Parameter	Conditions	Min	Typ	Max	Unit
1	$I_{VCC,OFF}$	Supply current	Output inactive (off)		3.8	4.8	mA
2	$I_{VCC,ON}$	Supply current	Output active (on)		8.5	12	mA
3	$V_{SAT,OUT}$	Output saturation voltage	$I_{OUT}=150mA$		0.50	0.70	V
4	$I_{LED}$	LED current		1.0	1.2	1.6	mA
5	$I_{LKG}$	Output leakage current			<1	20	$\mu A$
6	$I_{TH,OVL}$	Overload threshold current <sup>*1)</sup>		158	190	220	mA

<sup>\*1)</sup>—overload threshold current is the level of the output current which triggers the overload protection circuit.

### AC and Timing Characteristics

The typical values are given for  $V_{CC} = 24V$  and  $T_j = 25^\circ C$  unless otherwise specified.

#	Symbol	Parameter	Conditions	Min	Typ	Max	Unit
1	$f_{OSC}$	Operating frequency	Defined by external LC tank	0.1		1.0	MHz
2	$R_N$	Negative resistance between pin L1 and ground	$R_N = -2 \cdot R_F \pm 3\%$	-200		-2	k $\Omega$
3	$f_{MAX}$	Maximum switching frequency <sup>*1)</sup>	$C_{DET}=4.7pF, f_{OSC}=600kHz$ $C_{DET}=33pF, f_{OSC}=100kHz$		5 2		kHz
4	$H_W$	Hysteresis width	Depends on $R_{HYST}$	0		15	%
5	$t_R$	Output rise time	Load=1kohm		<1.5		$\mu s$
6	$t_F$	Output fall time <sup>*2)</sup>	Load=1kohm		<1		$\mu s$
7	$T_{S,OVL}$	Sampling period in overload mode	Depends on $C_{OVL}$	50	120	250	ms
8	$T_{STARTUP}$	Startup time <sup>*3)</sup>		50	120	250	ms
10	$C_{IN}$	Input capacitance	Measured between Pin L1 and AC ground (Pin L2) for $f_{OSC}=0.2...1MHz$ and $ R_N  = 2...100kohm$	6	8.5	13	pF

<sup>\*1)</sup> – these are maximum switching frequencies of the IC itself; switching frequencies of sensors may be higher than those given above,

<sup>\*2)</sup> – the fall time on leaving the start-up interval depends on the load used and can be as long as 10ms,

<sup>\*3)</sup> – this is the maximum start-up time of the chip itself; this parameter does not reflect performance of a sensor; during the start-up interval the output is inactive (OFF) regardless of the state of the NO/NC pin.