AMC2576



3A STEP DOWN VOLTAGE REGULATOR

DESCRIPTION			FEATURES					
all the required activ with excellent line available in fixed or output version. The AMC2576 popular three-termi minimum number of not only the area of 1 some cases, no heat s The \pm 4% toler voltages and output frequency accuracy i featuring 70µA(typ includes cycle-by-cy	series is a step-down sw ve functions. It is capab and load regulations utput voltages of 3.3V, series offers a high-effic nal linear regulators. external components. S board size but also the si- sink is required. rance on output voltage load conditions is guar s within ±10%. External ical) standby current. ycle current limitation, otection under fault condi-	le of drivin . These d 5V, and an ciency repla It require ubstantially ize of the h within spec anteed. Th shutdown The outp as well	ng 3A load levices are n adjustable acement for es only a 7, it reduces leat sink. In cified input e oscillator is included, put switch	 3.3V, 5 Wide i Internative freque Wide a range, line an Low st shutdo Requin Therma protection 	adjustable ve from 1.23V t ad load condi- andby currer own mode res only 4 ext al shut down	table outpu range, up of 52 KHz f rsion outpu to 37V ±4% tions nt, typ. 70µ ernal comp and curre	it versions to 40V fixed it voltage 6 max over 1A, at ponents ent limit	
APPLICATIONS					PACKAGE PIN OUT			
 High Efficiency Efficient Pre-reg Regulators 	Switching Regulators Step-Down Regulators gulator for Linear AGE OPTIONS – 3.3V Fixed – 5.0V Fixed J – Adjustable Outpu	t	5-Pin P	Vo	5. Enable ⊐ 4. FB 3. GND 2. Vour 1. VIN DB IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII	5-Pin Plastic Surface I (Top Vi (Side Viev (Side Viev 8 GND 7 GND 6 GND 5 GND	Mount iew)	
					SO-8 (Top View)			
		ORDER	INFORMAT	ION				
Temperature Range	Plastic TO-220 5-pin	PB	Plastic TO-220B 5-pin	DD	Plastic TO-263 5-pin	DM	Plastic SO 8pin	
	AMC2576-ADJP	AMC257	*	AMC257	6-ADJDD	AMC257	6-ADJDMF	
$-40^{\circ}C \le T_{J} \le 125^{\circ}C$	AMC2576-ADJPF		6-ADJPBF		6-ADJDDF	AMC257	6-X.XDMF	
	AMC2576-X.XP	XP AMC2576-X.XI		AMC2576-X.XDD				

Note: 1.All surface-mount packages are available in Tape & Reel. Append the letter "T" to part number (i.e.AMC2576-X.XDMFT, AMC2576-X.XDDT). 2.The letter "F" is marked for Lead Free process.

AMC2576-X.XPBF

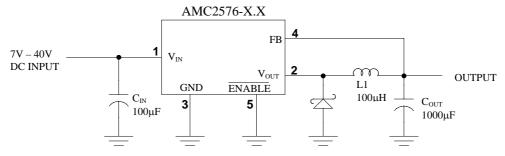
AMC2576-X.XPF

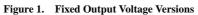
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AMC2576-X.XDDF

AMC2576

TYPICAL APPLICATION





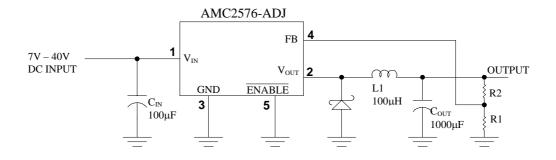


Figure 2. Adjustable Output Voltage Versions

$$V_{OUT} = V_{REF} \left(\begin{array}{c} 1 + \frac{R2}{R1} \end{array} \right)$$
$$R2 = R1 \left(\frac{V_{OUT}}{V_{REF}} - 1 \right)$$

Where $V_{REF} = 1.23V$, R1 between 1K and 5K

AMC2576

3.0°C/W

45°C /W

ABSOLUTE MAXIMUM RATINGS (Note 1)

Input Voltage, V _{IN}	45V
ENABLE Pin Input Voltage	$-0.3V \leq V \leq V_{\rm IN}$
Operating Junction Temperature, T _J	150°C
Storage Temperature Range	-65°C to 150°C
Lead Temperature (soldiering, 10 seconds)	260°C
Note 1: Exceeding these ratings could cause damage to the device. All voltages are with respect to Ground. Consegutive out of the specified terminal.	urrents are positive into,

RECOMMENDED OPERATING RATINGS

Temperature Range	$-40^\circ C \leq T_J \leq 125^\circ C$
Input Voltage, V _{IN}	40V(Max.)

THERMAL DATA

P,PB, DD PACKAGE:

Thermal Resistance-Junction to Tab, θ_{JT}

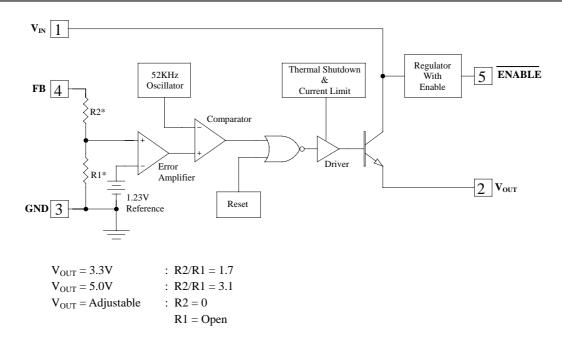
Thermal Resistance-Junction to Ambient, θ_{JA}

Junction Temperature Calculation: $T_J = T_A + (P_D \times \theta_{JA}).$

The θ_{JA} numbers are guidelines for the thermal performance of the device/pc-board system.

All of the above assume no ambient airflow.

BLOCK DIAGRAM



		DC I	ELECTRICAL CHAR	ACTERISTICS				
Unless otherw temperatures		se specifi	cations apply $V_{IN} = 12V$	I, $I_{LOAD} = 0.5A$ and the	e operati	ng ambie	nt	
Parameter		C	Symbol Test Conditions		AMC2576			
		Symbol			Min	Тур	Max	Units
Output Voltage AMC2576-3.3					3.234	3.300	3.366	v
(Note 1)	AMC2576-5.0	V _{OUT}	Test circuit of Figure 1		4.900	5.000	5.100	
Output Voltage	AMC2576-3.3	V	$0.5A \leq I_{LOAD} \leq 3A$	$6V \leq V_{IN} \leq 40V$	3.168	3.300	3.432	V
(Note 1)	AMC2576-5.0	V _{OUT}	Test circuit of Figure 1	$8V \leq \!$	4.800	5.000	5.200	
Output Voltage	AMC2576-3.3	X 7	$0.5A \le I_{LOAD} \le 3A$,	$6V \leq V_{\rm IN} \leq 40V$	3.135	3.300	3.482	
(Note 1)	AMC2576-5.0	V _{OUT}	$-40^{\circ}C \le T_J \le 125^{\circ}C$ Test circuit of Figure 1	$8V \leq V_{\rm IN} \leq 40V$	4.750	5.000	5.250	V
Feedback Voltage (Note 1)	AMC2576-ADJ	V _{OUTFB}	Test circuit of Figure 2	$V_{OUT} = 5V$	1.217	1.230	1.243	v
Feedback Voltage (Note 1)	AMC2576-ADJ	V _{OUTFB}	$8V \le V_{IN} \le 40V$, $V_{OUT} = 5V$, Test circuit of Figure 2	$0.5A \le I_{LOAD} \le 3A$	1.193	1.230	1.267	v
Feedback Voltage (Note 1)	AMC2576-ADJ	V _{OUTFB}	$8V \le V_{IN} \le 40V$, $V_{OUT} = 5V$, Test circuit of Figure 2	$\label{eq:LOAD} \begin{split} 0.5A &\leq I_{LOAD} \leq 3A, \\ -40^{\circ}C &\leq T_J \leq 125^{\circ}C \end{split}$	1.180	1.230	1.286	v
Efficiency AMC2576-3.3 AMC2576-5.0]	$I_{LOAD} = 3A$			75		
					77		%	
	AMC2576-ADJ	$I_{LOAD} = 3A, V_{OUT} = 5V$			77		\square	
Oscillator Frequency		f _{osc}	(Note 2)	$\Gamma_{\rm J} = 25^{\circ}{\rm C}$	47	52	58	kHz
			•	$40^{\circ}C \le T_J \le 125^{\circ}C$	42	52	63	
Quiescent Curre	ent	I _Q	(Note 3)			5	10	mA
Standby Curren	t	I _{STBY}	$\overline{\text{ENABLE}} = 5\text{V}$			70	200	μΑ
Saturation Volta	Saturation Valtage		$I_{LOAD} = 3A$ (Note 4)	$\Gamma_{\rm J} = 25^{\circ}{\rm C}$		1.4	1.8	v
Saturation voia		V _{SAT}	$I_{\rm LOAD} = 3A (1000 4)$	$-40^{\circ}C \le T_J \le 125^{\circ}C$			2.0	v
Feedback Bias	Current	I _{FB}	001	$\Gamma_{\rm J}=25^{\circ}{\rm C}$		50	100	nA
T CEUDACK DIAS	current	1FB	(ADJ version only)	$-40^{\circ}C \le T_J \le 125^{\circ}C$			500	
Duty Cycle (ON	1)	DC	(Note 5)		93	98		%
Current Limit		I _{LIMIT}	(Note 2, 4)	$\Gamma_{\rm J} = 25^{\circ}{\rm C}$	4.2	7	8.8	A
				$40^{\circ}C \le T_J \le 125^{\circ}C$	3.5	7.2	9	
Output Leakage Current		I _{LEAK}	(INOTE 1)	$V_{OUT} = 0V$		0.3	2	mA
				$V_{OUT} = -1V$		9	20	
 ENABLE Threshold Voltage			$V_{OUT} = 0V$	$\Gamma_{\rm J} = 25^{\circ}{\rm C}$	2.2	1.4		v
			=	$40^{\circ}C \leq T_J \leq 125^{\circ}C$	2.4			
	C	V _{IL}	001	$\Gamma_{\rm J} = 25^{\circ}{\rm C}$		1.2	1.0	-
			Output Voltage $-40^{\circ}C \le T_J \le 125^{\circ}C$				0.8	+
ENABLE Input	Current	I _{IH}	$\overline{\text{ENABLE}} = 5\text{V}$			12	30	μA
*		I _{IL}	$\overline{\text{ENABLE}} = 0\text{V}$			0	10	Pr2 1

DC ELECTRICAL CHARACTERISTICS

AMC2576

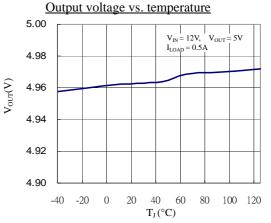
- Note 1: External components such as the catch diode, inductor, input and output capacitors can affect switching regulator system performance. Refer to Application Information for details.
- Note 2: The oscillator frequency reduces to approximately 11kHz in the event of fault conditions, such as output short or overload. And the regulated output voltage will drop approximately 40% from the nominal output voltage. This self-protection feature lowers the average power dissipation by lowering the minimum duty cycle from 5% down to approximately 2%.
- Note 3: For these parameters, FB is removed from VOUT and connected to +12V to force the output transistor OFF.
- Note 4: VOUT pin sourcing current. No diode, inductor or capacitor connect to VOUT.
- Note 5: FB is removed from VOUT and connected to 0V.

AMC2576

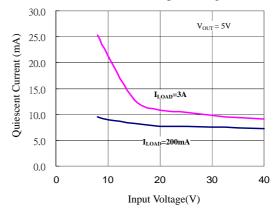
Line regulation 5.10 5.08 V_{OUT}=5V 5.06 5.04 5.02 5.02 5.00 4.98 4.96 4.94 4.92 $V_{OUT}(V)$ ILOAD=0.5A ILOAD=3A 4.90 4.88 4.86 4.84 4.82 4.80 0 5 10 15 20 25 30 35 40 $V_{IN}(V)$ Current limit vs. temperature 8.60 Vu = 25V 8.40 Current Limit (A) 8.20 8.00 7.80 7.60 7.40 7.20 7.00 -40 -20 0 20 40 60 80 100 120 $T_{\rm J}(^{\circ}C)$ Dropout voltage vs. temperature 2.10 1.80 ILOAD=3A Dropout Voltage (V) 1.50 1.20 0.90 ILOAD=0. 5A 0.60 0.30

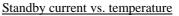
CHARACTERIZATION CURVES

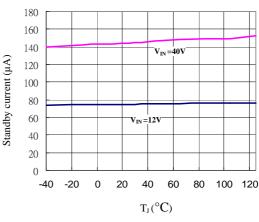
Test circuits of Figure 1 and 2, $T_J=25^{\circ}C$, unless otherwise specified.



Quiescent current vs. input voltage







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-40 -20

0 20

60 80

 $T_{\rm J}(^{\circ}C)$

40

100 120

0.00

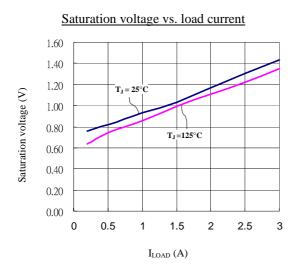
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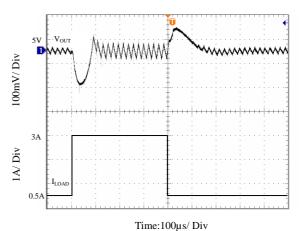
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CHARACTERIZATION CURVES (continued)

Test circuits of Figure 1 and 2, $T_J = 25^{\circ}C$, unless otherwise specified.







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APPLICATION INFORMATION

Input Capacitors (C_{IN})

It is required that V_{IN} must be bypassed with at least a 100µF electrolytic capacitor for stability. Also, it is strongly recommended the capacitor's leads must be dept short, and located near the regulator as possible.

For low operating temperature range, for example, below -25°C, the input capacitor value may need to be larger. This is due to the reason that the capacitance value of electrolytic capacitors decreases and the ESR increases with lower temperatures and age. Paralleling a ceramic or solid tantalum capacitor will increase the regulator stability at cold temperatures.

Output Capacitors (COUT)

An output capacitor is also required to filter the output voltage and is needed for loop stability. The capacitor should be located near the AMC2576 using short PC board traces. Low ESR types capacitors are recommended for low output ripple voltage and good stability. Generally, low value or low voltage (less than 12V) electrolytic capacitors usually have higher ESR numbers. For example, the lower capacitor values $(220\mu F-1000\mu F)$ will yield typically 50 mV to 150 mV of output ripple voltage, while larger-value capacitors will reduce the ripple to approximately 20 mV to 50 mV.

The amount of output ripple voltage is primarily a function of the ESR (Equivalent Series Resistance) of the output capacitor and the amplitude of the inductor ripple current (ΔI_{IND}).

 $\label{eq:output} Output \ Ripple \ Voltage = (\Delta I_{IND}) \times \quad (ESR \ of \ C_{OUT})$

Some capacitors called "high-frequency," "low-inductance," or "low-ESR." are recommended to use to further reduce the output ripple voltage to 10 mV or 20 mV. However, very low ESR capacitors, such as Tantalum capacitors, should be carefully evaluated.

Catch Diode

This diode is required to provide a return path for the inductor current when the switch is off. It should be located close to the AMC2576 using short leads and short printed circuit traces as possible.

To satisfy the need of fast switching speed and low forward voltage drop, Schottky diodes are widely used to provide the best efficiency, especially in low output voltage switching regulators (less than 5V). Besides, fast-Recovery, high-efficiency, or ultra-fast recovery diodes are also suitable. But some types with an abrupt turn-off characteristic may cause instability and EMI problems. A fast-recovery diode with soft recovery characteristics is a better choice.

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APPLICATION INFORMATION (contd.)

Output Voltage Ripple and Transients

The output ripple voltage is due mainly to the inductor saw tooth ripple current multiplied by the ESR of the output capacitor.

The output voltage of a switching power supply will contain a saw tooth ripple voltage at the switcher frequency, typically about 1% of the output voltage, and may also contain short voltage spikes at the peaks of the saw tooth waveform.

Due to the fast switching action, and the parasitic inductance of the output filter capacitor, there is voltage spikes presenting at the peaks of the saw tooth waveform. Cautions must be taken for stray capacitance, wiring inductance, and even the scope probes used for transients evaluation. To minimize these voltage spikes, shortening the lead length and PCB traces is always the first thought. Further more, an additional small LC filter $(20\mu H \& 100\mu F)$ (as shown in Figure 3) will possibly provide a 10X reduction in output ripple voltage and transients.

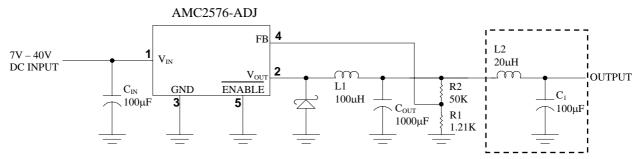


Figure 3. LC Filter for Low Output Ripple

Inductor Selection

The AMC2576 can be used for either continuous or discontinuous modes of operation. Each mode has distinctively different operating characteristics, which can affect the regulator performance and requirements.

With relatively heavy load currents, the circuit operates in the continuous mode (inductor current always flowing), but under light load conditions, the circuit will be forced to the discontinuous mode (inductor current falls to zero for a period of time). For light loads (less than approximately 300 mA) it may be desirable to operate the regulator in the discontinuous mode, primarily because of the lower inductor values required for the discontinuous mode.

Inductors are available in different styles such as pot core, toroid, E-frame, bobbin core, et., as well as different core materials, such as ferrites and powdered iron. The least expensive, the bobbin core type, consists of wire wrapped on a ferrite rod core. This type of construction makes for an inexpensive inductor, but since the magnetic flux is not completely contained within the core, it generates more electromagnetic interference (EMI). This EMI can cause problems in sensitive circuits, or can give incorrect scope readings because of induced voltages in the scope probe.

An inductor should not be operated beyond its maximum rated current because it may saturate. When an inductor begins to saturate, the inductance decreases rapidly and the inductor begins to look mainly resistive (the DC resistance of the winding). This will cause the switch current to rise very rapidly. Different inductor types have different saturation characteristics, and this should be well considered when selecting as inductor.

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APPLICATION INFORMATION (contd.)

Feedback Connection

For fixed output voltage version, the FB (feedback) pin must be connected to V_{OUT} . For the adjustable version, it is important to place the output voltage ratio resistors near AMC2576 as possible in order to minimize the noise introduction.

ENABLE

It is required that the ENABLE must **not** be left open. For normal operation, connect this pin to a "LOW" voltage (typically, below 1.6V). On the other hand, for standby mode, connect this pin with a "HIGH" voltage. This pin can be safely pulled up to $+V_{IN}$ without a resistor in series with it.

Grounding

To maintain output voltage stability, the power ground connections must be low-impedance. For the 5-lead TO-220 and TO-263 style package, both the tab and pin 3 are ground and either connection may be used.

Heat Sink and Thermal Consideration

Although the AMC2576 requires only a small heat sink for most cases, the following thermal consideration is important for all operation. With the package thermal resistances θ_{JA} and θ_{JC} , total power dissipation can be estimated as follows:

 $P_{D} = (V_{IN} \times I_{Q}) + (V_{OUT} / V_{IN})(I_{LOAD} \times V_{SAT});$

When no heat sink is used, the junction temperature rise can be determined by the following:

 $\Delta T_{\rm J}=P_{\rm D}\times\theta_{\rm JA};$

With the ambient temperature, the actual junction temperature will be:

 $T_J = \Delta T_J + T_A$;

If the actual operating junction temperature is out of the safe operating junction temperature (typically 125°C), then a heat sink is required. When using a heat sink, the junction temperature rise will be reduced by the following:

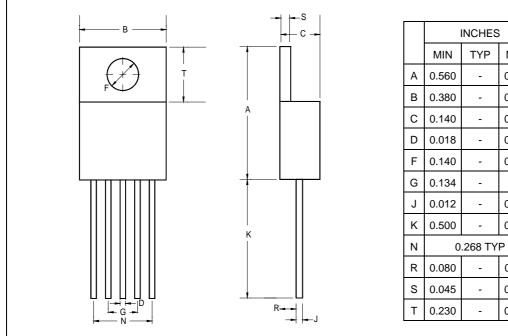
 $\Delta T_{J} = P_{D} \times (\theta_{JC} + \theta_{interface} + \theta_{Heat sink});$

As one can see from the above, it is important to choose an heat sink with adequate size and thermal resistance, such that to maintain the regulator's junction temperature below the maximum operating temperature.

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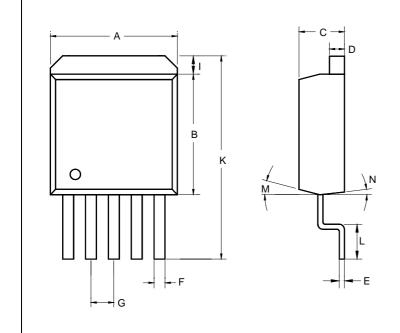
PACKAGE

5-Pin Plastic TO-220 (P)



	INCHES			MILLIMETERS		
	MIN	TYP	MAX	MIN	TYP	MAX
А	0.560	-	0.650	14.23	I	16.51
В	0.380	-	0.420	9.66	I	10.66
С	0.140	-	0.190	3.56	-	4.82
D	0.018	-	0.035	0.46	-	0.89
F	0.140	-	0.160	3.56	I	4.06
G	0.134	-	-	3.40	-	-
J	0.012	-	0.045	0.31	-	1.14
К	0.500	-	0.580	12.70	I	14.73
Ν	0.268 TYP			6.80 TYP		
R	0.080	-	0.115	2.04	-	2.92
S	0.045	-	0.055	1.14	-	1.39
Т	0.230	-	0.270	5.85	-	6.85

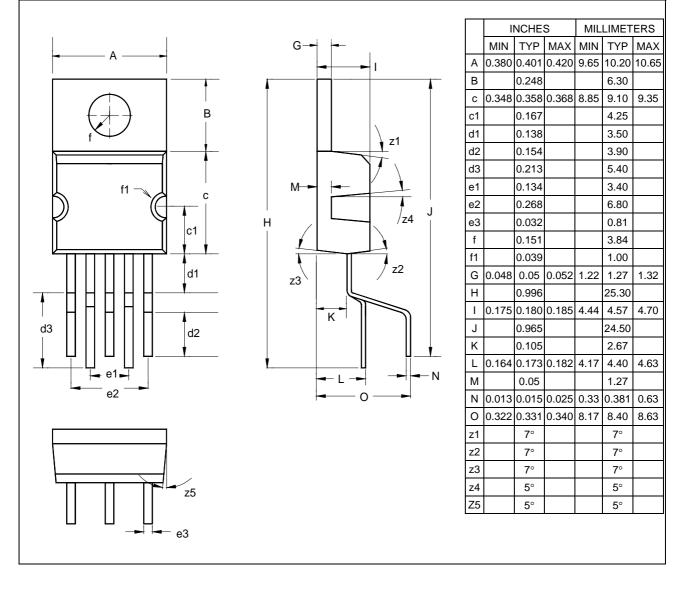
5-Pin Surface Mount TO-263 (DD)



	INCHES			MILLIMETERS		
	MIN	TYP	MAX	MIN	TYP	MAX
А	0.395	1	0.420	10.03	-	10.67
В	0.325	-	0.361	8.25	-	9.17
С	0.171	1	0.181	4.34	-	4.59
D	0.045	1	0.055	1.14	-	1.40
Е	0.013	1	0.017	0.330	-	0.432
F	0.029	1	0.035	0.737	-	0.889
G	0.062	1	0.072	1.57	-	1.83
I	-	I	0.065	-	-	1.65
Κ	0.575		0.635	14.60		16.13
L	0.090		0.110	2.29		2.79
М		7 °			7 °	
Ν		3°			3°	

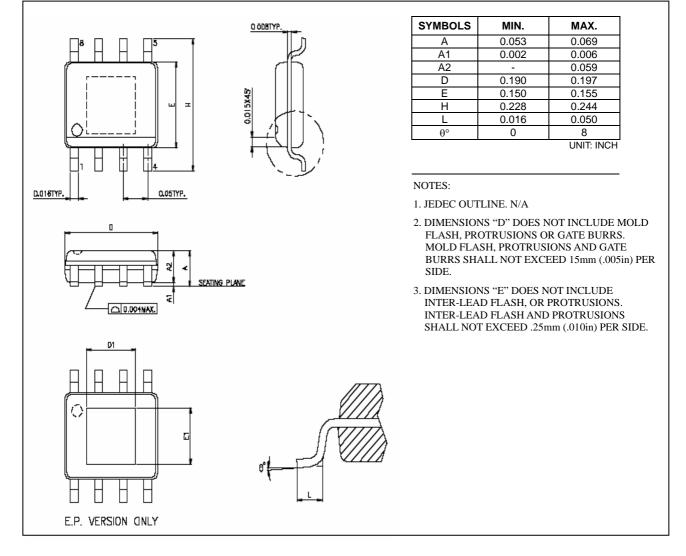
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5-Pin Plastic TO-220B (PB)



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8-Pin Plastic S.O.I.C.



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