

Rev 3, 27-Feb-14

## ActivePSR<sup>TM</sup> Quasi-Resonant PWM Controller

#### **FEATURES**

- Patented Primary Side Regulation Technology
- Quasi-Resonant Operation
- Adjustable up to 120kHz Switching Frequency
- +/-5% Output Voltage Regulation
- Accurate OCP/OLP Protection
- Integrated Output Cord Compensation
- Integrated Line and Primary Inductance Compensation
- Built-in Soft-Start Circuit
- Line Under-Voltage, Thermal, Output Overvoltage, Output Short Protections
- Current Sense Resistor Short Protection
- Transformer Short Winding Protection
- Less than 100mW Standby Power
- Complies with Global Energy Efficiency and CEC Average Efficiency Standards
- Tiny SOT23-6 Package

#### **APPLICATIONS**

- AC/DC Adaptors/Chargers for Smart Phones, iPADs, ADSL, PDAs, E-books
- Adaptors for Portable Media Player, DSCs, and Other

## GENERAL DESCRIPTION

The ACT410 is a high performance peak current mode PWM controller which applies  $ActivePSR^{TM}$  and  $ActiveQR^{TM}$  technology. ACT410 achieves accurate voltage regulation without the need of an opto-coupler or reference device.

The ACT410 is designed to achieve less than 100mW Standby Power. By applying frequency fold back and  $ActiveQR^{TM}$  technology, ACT410 exceeds the latest ES2.0 efficiency standard.

ACT410 integrates comprehensive protection. In case of over temperature, over voltage, short winding, short current sense resistor, open loop

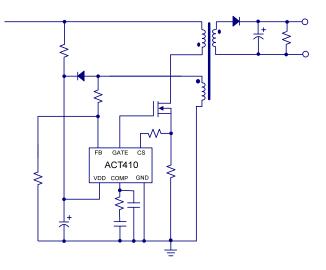
and overload conditions, it would enter auto restart mode including cycle-by-cycle current limiting.

ACT410 is to achieve no overshoot and very short rise time even with big capacitive load ( $4000\mu F$ ) with the built-in fast and soft start process, .

The Quasi-Resonant (QR) operation mode can effectively improve efficiency, reduce the EMI noise and further reduce the components in input filter.

ACT410 is idea for application up to 36 Watt.

Figure 1: Simplified Application Circuit

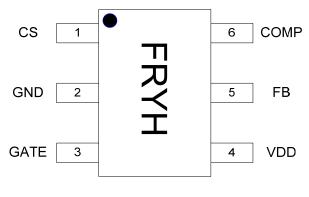




## **ORDERING INFORMATION**

PART NUMBER	TEMPERATURE RANGE	PACKAGE	PINS	PACKING METHOD	OPTION (DC CORD %)	TOP MARK
ACT410US-T	-40°C to 85°C	SOT23-6	6	TUBE & REEL	6	FRYH

## **PIN CONFIGURATION**



**SOT23-6 ACT410US** 

## **PIN DESCRIPTIONS**

PIN	NAME	DESCRIPTION					
1	CS	Current Sense Pin. Connect an external resistor ( $R_{CS}$ ) between this pin and ground to set peak current limit for the primary switch.					
2	GND	Ground.					
3	GATE	Gate Drive. Gate driver for the external MOSFET transistor.					
4	VDD	Power Supply. This pin provides bias power for the IC during startup and steady state operation.					
5	FB	Feedback Pin. Connect this pin to a resistor divider network from the auxiliary winding.					
6	COMP	Compensation Pin.					



## **ABSOLUTE MAXIMUM RATINGS<sup>®</sup>**

PARAMETER	VALUE	UNIT
FB, CS, COMP to GND	-0.3 to + 6	V
VDD, GATE to GND	-0.3 to + 22	٧
Maximum Power Dissipation (SOT23-6)	0.45	W
Operating Junction Temperature	-40 to 150	°C
Junction to Ambient Thermal Resistance (θ <sub>JA</sub> )	220	°C/W
Operating Junction Temperature	-40 to 150	°C
Storage Temperature	-55 to 150	°C
Lead Temperature (Soldering, 10 sec)	300	°C

①: Do not exceed these limits to prevent damage to the device. Exposure to absolute maximum rating conditions for long periods.

## **ELECTRICAL CHARACTERISTICS**

 $V_{DD} = 15 \text{V}, \ L_{M} = 0.37 \text{mH}, \ R_{CS} = 1 \Omega, \ V_{OUT} = 5 \text{V}, \ N_{P} = 76, \ N_{S} = 7, \ N_{A} = 20, \ T_{A} = 25 ^{\circ}\text{C}, \ unless otherwise specified}, \ 5 \text{V2A application.})$ 

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Supply	•					
VDD Turn-On Voltage	$V_{DDON}$	V <sub>DD</sub> Rising from 0V	11.11	12.35	13.58	V
VDD Turn-Off Voltage	$V_{DDOFF}$	V <sub>DD</sub> Falling after Turn-on	6.1	6.8	7.5	V
VDD Over Voltage Protection	$V_{DDOVP}$	V <sub>DD</sub> Rising from 0V	18.45	20.5	22.55	V
Start Up Supply Current	I <sub>DDST</sub>	V <sub>DD</sub> = 11V, before VDD Turn-on		5	10	μΑ
IDD Supply Current	I <sub>DD</sub>	V <sub>DD</sub> = 12V, after VDD Turn-on (no switching)		0.55	1	mA
IDD Supply Current at Fault Mode	I <sub>DD</sub>	V <sub>DD</sub> = 12V, after VDD Turn-on, fault = 1	Γurn-on, 0.25			mA
Feedback						
Effective FB Reference Voltage	$V_{FBREF}$		2.23	2.25	2.28	V
	_	Light load	0.38	0.45	0.52	μs
FB Sampling Blanking Time	T <sub>FB_BLK</sub>	Heavy Load	1.1	1.3	1.5	μs
Time needed for FB Sampling	1_	FB sampling	0.5	0.65	0.75	μs
(After blanking)	T <sub>FB_SAMP</sub>	CC and Knee point detecting	0.22	0.25	0.29	μs
FB Leakage Current	I <sub>BVFB</sub>	V <sub>FB</sub> = 3V			1	μA
Current Limit	•					
CS Current Limit Threshold	$V_{CSLIM}$		0.99	1.00	1.01	V
CS Minimum Current Limits Threshold	V <sub>CSMIN</sub>			300		mV
CS to GATE Propagation Delay				60		ns
Loading Edgo Planking Time	_	Light Load		150		ns
Leading Edge Blanking Time	T <sub>CSBLANK</sub>	Heavy Load		636		ns



## **ELECTRICAL CHARACTERISTICS CONT'D**

 $V_{DD}$  = 15V,  $L_{M}$  = 0.37mH,  $R_{CS}$  = 1 $\Omega$ ,  $V_{OUT}$  = 5V,  $N_{P}$  = 76,  $N_{S}$  = 7,  $N_{A}$  = 20,  $T_{A}$  = 25°C, unless otherwise specified,5V2A application.)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	TYP MAX	
RCORD	•					
Output Cable Resistance Compensation	DV <sub>COMP</sub>	ACT410		6		%
GATE DRIVE						
Gate Rise Time	T <sub>RISE</sub>	VDD = 10V, CL = 1nF		150	250	ns
Gate Falling Time	T <sub>FALL</sub>	VDD = 10V, CL = 1nF		90		ns
Gate Low Level ON-Resistance	R <sub>ONLO</sub>	I <sub>SINK</sub> = 30mA		10		Ω
Gate High Level ON-Resistance	R <sub>ONHI</sub>	I <sub>SOURCE</sub> = 30mA		31		Ω
Gate Leakage Current		GATE = 18V, before VDD turn-on			1	μA
COMPENSATION						
Inside Compensate Resistor	R <sub>COMP</sub>	ACT410		0		kΩ
Output Sink Current	I <sub>COMP_SINK</sub>	$V_{FB} = 3V$ , $V_{COMP} = 2V$	15	40		μΑ
Output Source Current	I <sub>COMP_SOUR</sub>	V <sub>FB</sub> = 1.5V, V <sub>COMP</sub> = 2V	15	40		μA
Transconductance of Error Amplifier	Gm			71		μA/V
Maximum Output Voltage	$V_{COMPMAX}$	V <sub>FB</sub> = 1.5V		3.5		V
Minimum Output Voltage	V <sub>COMPMIN</sub>	V <sub>FB</sub> = 3V		0.4		V
CS to COMP Gain				2		V/V
Pre-Amp Gain				1		V/V
COMP Leakage Current		COMP = 2.5V			1	μΑ
OSCILLATOR						
Maximum Switching	f <sub>MAX</sub>		108	120	132	kHz
Maximum Duty Cycle	D <sub>MAX</sub>		65	75		%
Minimum Switching Frequency	f <sub>MIN</sub>			1164		Hz



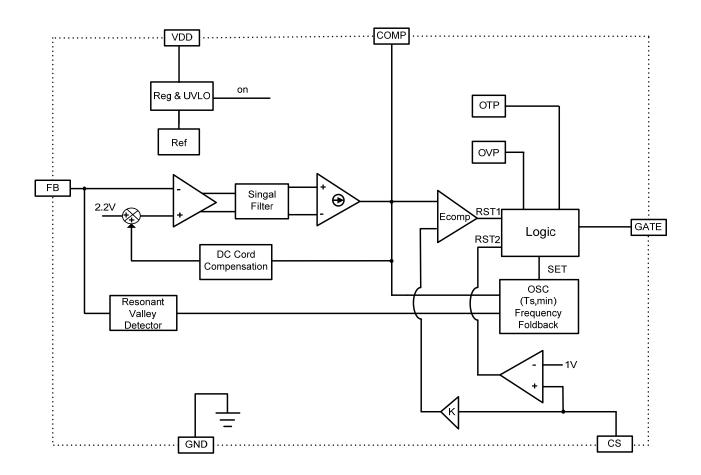
## **ELECTRICAL CHARACTERISTICS CONT'D**

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PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT		
Protection								
CS Short Waiting Time			2	2.25	3	μs		
CS Short Detection Threshold				0.1	0.15	٧		
CS Open Threshold Voltage				1.75		V		
Abnormal OCP Blanking Time				190		ns		
Inductance Short CS Threshold Voltage				1.75		V		
Thermal Shutdown Temperature				135		°C		
Thermal Hysteresis				20		°C		
Line UVLO	I <sub>FBUVLO</sub>			0.2		mA		
Line UVLO Hysteresis				20		μA		
Line OVP	I <sub>FBOVP</sub>			2.4		mA		
VFB Over Voltage Protection				3		V		
Valley Detection	Valley Detection							
Valley Detection Time Window		$V_{COMP} = 0.45V$		3.3		μs		



## **FUNCTIONAL BLOCK DIAGRAM**





#### **FUNCTIONAL DESCRIPTION**

ACT410 is a high performance peak current mode low-voltage PWM controller IC. The controller includes the most advance features that are required in the adaptor applications up to 36 Watt. Unique fast startup, frequency fold back, QR switching technique, accurate OLP, low standby mode operation, external compensation adjustment, short winding protection, OCP, OTP, OVP and UVLO are included in the controller.

#### **Startup**

Startup current of ACT410 is designed to be very low so that VDD could be charged to VDDON threshold level and device starts up quickly. A large value startup resistor can therefore be used to minimize the power loss yet reliable startup in application. For a typical AC/DC adaptor with universal input range design, two 1M $\Omega$ , 1/8 W startup resistors could be used together with a VDD capacitor(4.7uF) to provide a fast startup and yet low power dissipation design solution.

During startup period, the IC begins to operate with minimum lppk to minimize the switching stresses for the main switch, output diode and transformers. And then, the IC operates at maximum power output to achieve fast rise time. After this,  $V_{\text{OUT}}$  reaches about 90%  $V_{\text{OUT}}$ , the IC operates with a 'soft-landing' mode (decrease lppk) to avoid output overshoot.

## **Constant Voltage (CV) Mode Operation**

In constant voltage operation, the ACT410 senses the output voltage at FB pin through a resistor divider network R5 and R6 in Figure 2. The signal at FB pin is pre-amplified against the internal reference voltage, and the secondary side output voltage is extracted based on Active-Semi's proprietary filter architecture.

This error signal is then amplified by the internal error amplifier. When the secondary output voltage is above regulation, the error amplifier output voltage decreases to reduce the switch current. When the secondary output voltage is below regulation, the error amplifier output voltage increases to ramp up the switch current to bring the secondary output back to regulation. The output regulation voltage is determined by the following relationship:

$$V_{OUTCV} = 2.20 V \times (1 + \frac{R_{FB1}}{R_{FB2}}) \times \frac{N_S}{N_A} - V_D$$
 (1)

where  $R_{FB1}$  (R5) and  $R_{FB2}$  (R6) are top and bottom feedback resistor,  $N_S$  and  $N_A$  are numbers of

transformer secondary and auxiliary turns, and  $V_{\text{D}}$  is the rectifier diode forward drop voltage at approximately 0.1A bias.

## **Constant Current (CC) Mode Operation**

When the secondary output current reaches a level set by the internal current limiting circuit, the ACT410 enters current limit condition and causes the secondary output voltage to drop. As the output voltage decreases, so does the flyback voltage in a proportional manner. An internal current shaping circuitry adjusts the switching frequency based on the flyback voltage so that the transferred power remains proportional to the output voltage, resulting in a constant secondary side output current profile. The energy transferred to the output during each switching cycle is  $\frac{1}{2}(LP \times ILIM^2) \times \eta$ , where LP is the transformer primary inductance, ILIM is the primary peak current, and η is the conversion efficiency. From this formula, the constant output current can be derived:

$$I_{OUTCC} = \frac{1}{2} \times L_{p} \times \left(\frac{V_{CS}}{R_{CS}}\right)^{2} \times \left(\frac{\eta \times f_{SW}}{V_{OUTCV}}\right)$$
 (2)

where  $f_{SW}$  is the switching frequency and  $V_{OUTCV}$  is the nominal secondary output voltage. The constant current operation typically extends down to lower than 40% of nominal output voltage regulation.

## Standby (No Load) Mode

In no load standby mode, the ACT410 oscillator frequency is further reduced to a minimum frequency while the current pulse is reduced to a minimum level to minimize standby power. The actual minimum switching frequency is programmable with an output preload resistor.

#### **Loop Compensation**

The ACT410 allows external loop compensation by connecting a capacitor and a resistor to extend its applications, especially with different  $V_{\text{OUT}}$  in a wide output power range.

## **Primary Inductance Compensation**

The ACT410 integrates a built-in primary inductance compensation circuit to maintain constant OLP despite variations in transformer manufacturing. The compensated ranges is +/-7%.

# Primary Inductor Current Limit Compensation

The ACT410 integrates a primary inductor peak



#### FUNCTIONAL DESCRIPTION CONT'D

current limit compensation circuit to achieve constant OLP over wide line and wide load range.

## **Output Cable Resistance Compensation**

The ACT410 provides internal programmable output cable resistance compensation during constant voltage regulation, monotonically adding an output voltage correction up to predetermined percentage at full power.

The feature allows better output voltage accuracy by compensating for the output voltage drop due to the output cable resistance.

## Frequency Fold-back

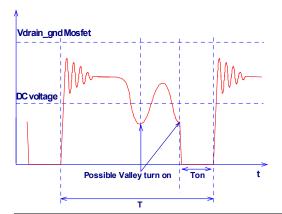
When the load drops to 75% of full load level, ACT410 starts to decrease the switching frequency, which is proportional to the load current ,to improve the efficiency of the converter as show in Functional Block Diagram.

This enables the application to meet all latest green energy standards. The actual minimum switching frequency is programmable with a small dummy load (while still meeting standby power).

## **Valley Switching**

ACT410 employed valley switching from medium load to heavy load to reduce switching loss and EMI. After the switch is turned off, the ringing voltage from the auxiliary winding is applied to the VFB pin through feedback network R5, R6. Internally, the VFB pin is connected to an zero-crossing detector to generate the switch turn on signal when the conditions are met. In light load, the frequency fold back scheme starts to take control to determine the switch turn on signal, so thus the switching frequency.

Figure 1: Valley Switching at heavy load



#### **Protection Features**

The ACT410 provides full protection functions. The following table summarizes all protection functions.

PROTECTION FUNCTIONS	FAILURE CONDITION	PROTECTION MODE
V <sub>DD</sub> Over Voltage	V <sub>DD</sub> > 20.5V (4 duty cycle)	Auto Restart
VFB Over Voltage	V <sub>FB</sub> > 3V (4 duty cycle)	Auto Restart
Over Temperature	T > 135°C	Auto Restart
Short Winding/ Short Diode	V <sub>CS</sub> > 1.75V	Auto Restart
Over Load	IPK = I <sub>LIMIT</sub>	Auto Restart
Output Short Circuit	V <sub>FB</sub> < 0.56V	Auto Restart
Open Loop	No switching for 4 cycle	Auto Restart
V <sub>CC</sub> Under Voltage	V <sub>CC</sub> < 6.8V	Auto Restart

#### **Auto-Restart Operation**

ACT410 will enter auto-restart mode when a fault is identified. There is a startup phase in the auto-restart mode. After this startup phase the conditions are checked whether the failure is still present. Normal operation proceeds once the failure mode is removed. Otherwise, new startup phase will be initiated again.

To reduce the power loss during fault mode, the startup delay control is implemented. The startup delay time increases over lines.

## Over Load Protection (OLP)

When the secondary output current reaches a level set by the internal current limiting circuit, the ACT410 enters current limit condition and causes the secondary output voltage to drop, the IC enters fault mode and enter auto restart mode.

ACT410 is able to achieve very accurate OLP (constant  $I_{\text{OUT}}$ ) independent of input lines and primary inductor values.

#### **Short Circuit Protection**

When the secondary side output is short circuited, the ACT410 enters hiccup mode operation. This hiccup behavior continues until the short circuit is removed.



## TYPICAL APPLICATION CONT'D

#### FB Over Voltage Protection

The ACT410 includes output over-voltage protection circuitry, which shuts down the IC when the output voltage is 40% above the normal regulation voltage 4 consecutive switching cycles. The ACT410 enters hiccup mode when an output over voltage fault is detected.

#### **VDD Over Voltage Protection**

ACT410 can monitor the converter output voltage. The voltage generated by the auxiliary winding tracks converter's output voltage through VDD, which is in proportion to the turn ratio ( $V_{\text{OUT}}+V_{\text{DIODE}}$ ) xN<sub>A</sub>/N<sub>S</sub>. When the  $V_{\text{OUT}}$  is abnormally higher than design value for four consecutive cycles, IC will enter the restart process. A counter is used to reduce sensitivity to noise and prevent the auto start unnecessary.

#### **Open Loop Protection**

ACT410 is able to protect itself from damage when the control loop is open. The typical open loop condition includes either VFB floating or RFB5 open.

#### Over Temperature Shutdown

The thermal shutdown circuitry detects the ACT410 die temperature. The threshold is set at typical 135°C. When the die temperature rises above this threshold (135°C) the ACT410 is disabled and remains disabled until the die temperature falls below 115°C, at which point the ACT410 is reenabled.



## TYPICAL APPLICATION CONT'D

## Design Example

The design example below gives the procedure for a DCM fly back converter using an ACT410. Refer to Application Circuit Figure 2, the design for an adapter application starts with the following specification:

Input Voltage Range	90VAC - 265VAC, 50/60Hz
Output Power, Po	10W
Output Voltage, V <sub>OUTCV</sub>	5V
Full Load Current, IOUTFL	2A
CC Current, I <sub>OUTMAX</sub>	2-2.6A
System Efficiency CV, η	0.75

The operation for the circuit shown in Figure 1 is as follows: the rectifier bridge BD1 and the capacitor C1/C2 convert the AC line voltage to DC. This voltage supplies the primary winding of the transformer T1 and the startup resistor R7/R8 to VDD pin of ACT410 and C4. The primary power current path is formed by the transformer's primary winding, the mosfet, and the current sense resistor R9. The resistors R3, R2, diode D2 and capacitor C3 create a snubber clamping network that protects Q1 from voltage spike from the transformer primary winding leakage inductance. The consisting of capacitor C4, diode D3 and resistor R4 provides a VDD supply voltage for ACT410 from the auxiliary winding of the transformer. The resistor R4 is optional, which filters out spikes and noise to makes VDD more stable. C4 is the decoupling capacitor of the supply voltage and energy storage component for startup. During power startup, the current charges C4 through startup resistor R7/R8 from the rectified high voltage. The diode D4 and the capacitor C7/L2/C6 rectify filter the output voltage. The resistor divider consists of R5 and R6 programs the output voltage.

Since a bridge rectifier and bulk input capacitors are used, the resulting minimum and maximum DC input voltages can be calculated:

$$V_{INDC\_MIN} = \sqrt{2V_{INAC\_MIN}^2} \frac{2P_{OUT}(\frac{1}{2f_L} - t_C)}{\eta \times C_{IN}}$$

$$= \sqrt{2 \times 85^2 - \frac{2 \times 10.5 \times (\frac{1}{2 \times 47} - 3.5 \text{ ms})}{0.75 \times 2 \times 10 \,\mu\text{F}}} \approx 100 \text{ V}$$
(3)

$$V_{IN(MAX)DC} = \sqrt{2} \times V_{IN(MAX)AC} = \sqrt{2} \times (265 V_{AG}) = 375 V$$
 (4)

Where  $\eta$  is the estimated circuit efficiency,  $f_L$  is the line frequency,  $t_C$  is the estimated rectifier conduction time,  $C_{IN}$  is empirically selected to be  $2x10\mu F$  electrolytic capacitors.

The maximum duty cycle is set to be 35% at low line voltage 85VAC and the circuit efficiency is estimated to be 75%. Then the maximum average input current is:

$$I_{IN\_MAX} = \frac{V_{OUT} \times I_{OUT\_CC}}{V_{INDC\_MIN} \times \eta}$$

$$= \frac{12 \times 2.3}{100 \times 0.75} = 153 \text{ mA}$$
(5)

The maximum input primary peak current:

$$I_{LIM} = \frac{2 \times L_{IN}}{D_{MAX}} = \frac{2 \times 153}{0.35} = 874 \text{ mA}$$
 (6)

The primary inductance of the transformer:

$$L_{p} = \frac{V_{INDC\_MIN} D_{max}}{I_{LIM} \times f_{s}}$$

$$= \frac{100 \times 0.35}{874 \text{ mA} \times 110 \text{ k}} = 0.37 \text{ mH}$$
(7)

The maximum primary turns on time:

$$T_{ON\_MAX} = L_p \frac{I_{LIM}}{V_{INDC\_MIN}}$$

$$= \frac{0.37 \text{ mH} \times 874 \text{ mA}}{100} = 3.23 \,\mu\text{s}$$
(8)

The ringing periods from primary inductance with mosfet Drain-Source capacitor:

$$T_{RINGING\_MAX} = 2\pi \sqrt{L_{p\_MAX}}C_{DS\_MAX}$$
  
=  $2 \times 3.14 \times \sqrt{0.37mH \times (1+7\%) \times 100PF} = 1.25 \mu s$  (9)

Design only an half ringing cycle at maximum load in minimum low line, so secondly reset time:

$$T_{RST} = T_{SW} - T_{ON\_MAX} - 0.5T_{RINGING\_MAX}$$
 (10)  
= 1/110kHz- 3.23\(\omega\)s - 0.5\times 1.25\(\omega\)s = 5.24\(\omega\)s

Base on conservation of energy and transformer transform identity, the primary to secondary turns ratio  $N_{\text{P}}/N_{\text{S}}$ :

$$\frac{N_{P}}{N_{S}} = \frac{T_{ON}}{T_{RST}} \times \frac{V_{IN\_MIN}}{V_{OUT} + V_{D}}$$

$$= \frac{3.23}{5.24} \times \frac{100}{5 + 0.45} = 11.31$$
(11)

The auxiliary to secondary turns ratio N<sub>A</sub>/N<sub>S</sub>:

$$\frac{N_A}{N_S} = \frac{V_{DD} + V_D'}{V_{OUT} + V_D} = \frac{12 + 0.45}{5 + 0.45} = 2.28$$
 (12)



## TYPICAL APPLICATION CONT'D

An EFD15 core is selected for the transformer. From the manufacture's catalogue recommendation, the gapped core with an effective inductance  $A_{LE}$  of 64  $nH/T^2$  is selected. The turn of the primary winding is:

$$N_{P} = \sqrt{\frac{L_{P}}{A_{LF}}} = \sqrt{\frac{0.37mH}{64nH/T^{2}}} = 76T \tag{13}$$

The turns of secondary and auxiliary winding can

be derived accordingly:  

$$N_{S} = \frac{N_{s}}{N_{p}} \times N_{p} = \frac{1}{11.32} \times 76 \approx 7T$$
(14)

$$N_A = \frac{N_A}{N_S} \times N_S = 2.28 \times 7 \approx 20T \tag{15}$$

Determining the value of the current sense resistor (R9) uses the peak current in the design. Since the ACT410 internal current limit is set to 1V, the design of the current sense resistor is given by:

$$R_{\text{CS}} = \frac{V_{\text{CS}}}{\sqrt{\frac{2 \times I_{\text{OUT\_OCP}} \times V_{\text{OUT}}}{L_P \times F_{\text{SW}} \times \eta_{\text{system}}}}}$$

$$= \frac{1}{\sqrt{\frac{2 \times 2.6 \times 5}{0.37 \text{mH} \times 100 \text{kHz} \times 0.75}}} \approx 1.07.\Omega$$
(16)

Where Fsw is the frequency at 4.75V CC mode.

The voltage feedback resistors are selected according to the loccmax and Vo. The design lo\_cc max is given by:

$$f_{s} = \frac{N_{p}}{N_{s}} \times \frac{R_{fb1} \times R_{fb2}}{R_{fb1} + R_{fb2}} \times \frac{V_{O} + V_{D}}{L_{p} \times \frac{V_{cs}}{R_{cs}} \times K_{f_{-sw}}}$$
(17)

The design Vo is given by:

$$V_o = (1 + \frac{R_{fb1}}{R_{fb2}}) \times \frac{N_s}{N_a} \times V_{FB} - V_D$$
 (18)

Where k is IC constant and K=0.000075, then we can get the value:

$$R_{fh1} = 68K, R_{fh2} = 11.5K (19)$$

When selecting the output capacitor, a low ESR electrolytic capacitor is recommended to minimize ripple from the current ripple. The approximate equation for the output capacitance value is given

$$C_{OUT} = \frac{I_{OUT}}{f_{sw} \times V_{const}} = \frac{2}{110k \times 50mV} = 364\mu F$$
 (20)

Two 820µF electrolytic capacitors are used to keep the ripple small.

### **PCB Layout Guideline**

Good PCB layout is critical to have optimal performance. Decoupling capacitor (C4) and feedback resistor (R5/R6) should be placed close to VDD and FB pin respectively. There are two main power path loops. One is formed by C1/C2, primary winding, Mosfet transistor and current sense resistor (R9). The other is secondary winding, rectifier D4 and output capacitors (C7/C6). Keep these loop areas as small as possible. Connecting high current ground returns, the input capacitor ground lead, and the ACT410 GND pin to a single point (star ground configuration).



Figure 2:
ACT410, Universal VAC Input, 5V/2A Output Charger

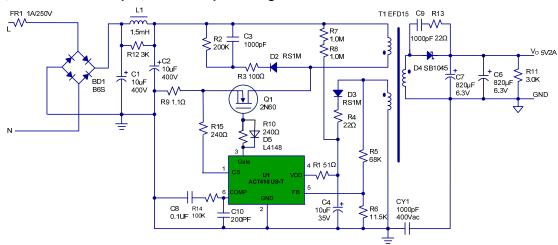


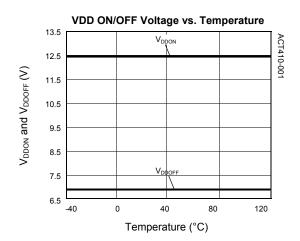
Table 1:

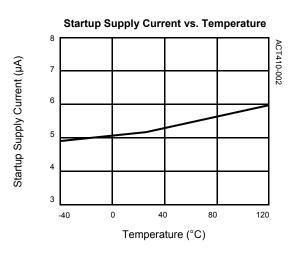
**ACT410 Bill of Materials** 

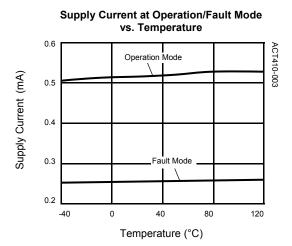
ITEM	REFERENCE	DESCRIPTION	QTY	MANUFACTURER
1	U1	IC, ACT410,SOT23-6	1	Active-Semi.
2	C1,C2	Capacitor, Electrolytic, 10µF/400V, 10x15mm	2	KSC
3	C3	Capacitor, Ceramic, 1000pF/500V, 0805,SMD	1	POE
4	C4	Capacitor, Electrolytic,10µF/35V,5x11mm	1	KSC
5	C6,C7	Capacitor, Electrolytic, 820µF/6.3V, 6.3 × 16mm	2	KSC
6	C8	Capacitor, Ceramic, 0.1µF/25V, 0805,SMD	1	POE
7	C9	Capacitor, Ceramic, 1000pF/100V, 0805,SMD	1	POE
8	C10	Capacitor, Ceramic, 200pF/50V, 0805,SMD	1	POE
9	CY1	Safety Y1,Capacitor,1000pF/400V,Dip	1	UXT
10	BD1	Bridge Rectifier,D1010S,1000V/1.0A,SDIP	1	PANJIT
11	D2,D3	Fast Recovery Rectifier, RS1M,1000V/1.0A, RMA	2	PANJIT
12	D4	Diode, Schottky, 45V/10A, S10U45S, SMD	1	Vishay
13	D5	Diode, 1N4148 SMD	1	PANJIT
14	L1	Axial Inductor, 1.5mH, 5*7,Dip	1	SoKa
15	L2	Axial Inductor, 0.55*5T, 5*7,Dip	1	SoKa
16	Q1	Mosfet Transistor, 2N60,TO-251	1	Infineon
17	PCB1	PCB, L*W*T=40x28x1.6mm,Cem-1,Rev:A	1	Jintong
18	FR1	Fuse,1A/250V	1	TY-OHM
19	R2	Carbon Resistor, 200KΩ, 1206, 5%	1	TY-OHM
20	R3	Chip Resistor, 100Ω, 0805, 5%	1	TY-OHM
21	R1	Chip Resistor, 51Ω, 0805, 5%	1	TY-OHM
22	R4,R13	Chip Resistor, 22Ω, 0805, 5%	2	TY-OHM
23	R5	Chip Resistor, 68KΩ, 0805,1%	1	TY-OHM
24	R6	Chip Resistor, 11.5KΩ, 0805, 1%	1	TY-OHM
25	R7	Chip Resistor, $1M\Omega$ , $0805$ , $5\%$	1	TY-OHM
26	R8	Chip Resistor, $1M\Omega$ , $0805$ , $5\%$	1	TY-OHM
27	R9	Chip Resistor, 1.1Ω, 1206,1%	1	TY-OHM
28	R10,R15	Chip Resistor, 240Ω, 0805 , 5%	2	TY-OHM
29	R11,R12	Chip Resistor, 3KΩ, 0805 , 5%	2	TY-OHM
30	R14	Chip Resistor, 100KΩ, 0805, 5%	1	TY-OHM
31	T1	Transformer, Lp=0.37mH, EFD15	1	

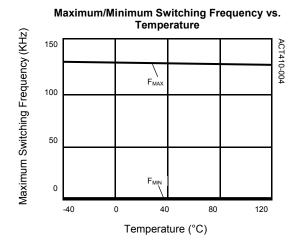


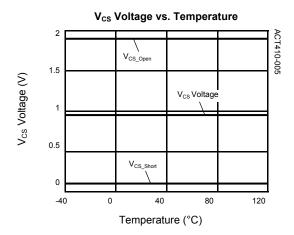
## TYPICAL PERFORMANCE CHARACTERISTICS

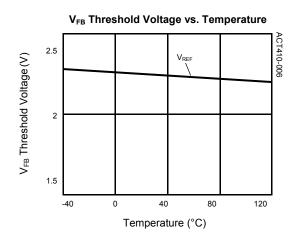






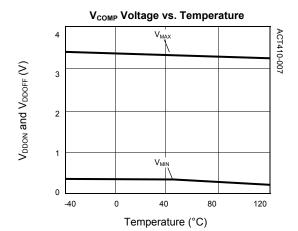








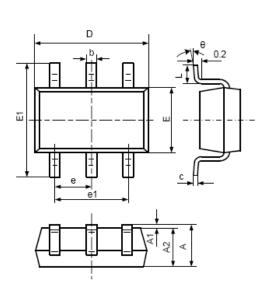
## TYPICAL PERFORMANCE CHARACTERISTICS





## **PACKAGE OUTLINE**

## **SOT23-6 PACKAGE OUTLINE AND DIMENSIONS**



SYMBOL		NSION IN DIMENS		
	MIN	MAX	MIN	MAX
Α	1.050	1.250	0.041	0.049
A1	0.000	0.100	0.000	0.004
A2	1.050	1.150	0.041	0.045
b	0.300	0.500	0.012	0.020
С	0.100	0.200	0.004	0.008
D	2.820	3.020	0.111	0.119
Е	1.500	1.700	0.059	0.067
E1	2.650	2.950	0.104	0.116
е	0.950	TYP	0.037	TYP
e1	1.800	2.000	0.071	0.079
L	0.700	REF	0.028 REF	
L1	0.300	0.600	0.012	0.024
θ	0°	8°	0°	8°

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