

LK204-25 Technical Manual

Revision: 2.1

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1 Getting Started



The LK204-25 is an intelligent LCD display designed to decrease development time by providing an instant solution to any project. With the ability to communicate via serial RS-232/TTL and $\rm I^2C$ protocols, the versatile LK204-25 can be used with virtually any controller. The ease of use is further enhanced by an intuitive command structure to allow display settings such as backlight brightness, contrast and baud rate to be software controlled. Additionally, up to thirty-two custom charaters such as character sets for bar graphs, medium and large numbers may be stored in the non-volitile memory to be easily recalled and displayed at any time.

1.1 Display Options Available

The LK204-25 comes in a wide variety of colors including the standard yellow/green or inverse yellow, the popular blue/white and the crisp white/grey as well as inverse red which is excellent for viewing at night. Extended voltage, and temperature options are also available, to allow you to select the display which will best fit your project needs.

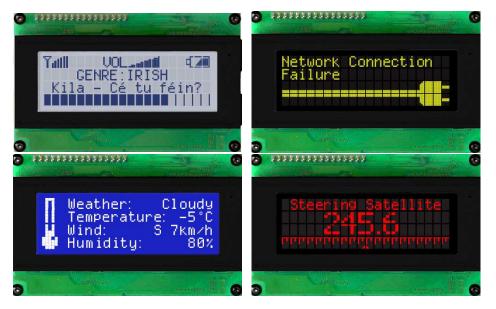


Figure 1: LK204-25 Options

1.2 Accessories

NOTE Matrix Orbital provides all the interface accessories needed to get your display up and running. You will find these accessories and others on our e-commerce website at http://www.matrixorbital.com. To contact a sales associate see Section 14.6 on page 58 for contact information.



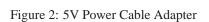




Figure 3: 12V Power Cable Adapter (V/VPT Models)

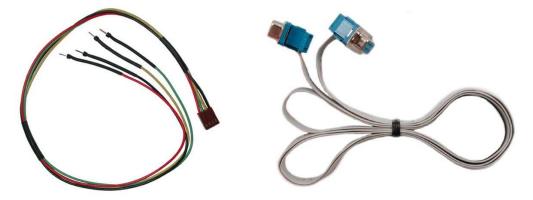


Figure 4: Breadboard Cable

Figure 5: Serial Cable 4FT



Figure 6: Communication and 5V Power Cable



Figure 7: Aluminum Mountings



Figure 8: Keypad Mountings



Figure 9: Mounting Kits



Figure 10: 4X4 Keypad

1.3 Features

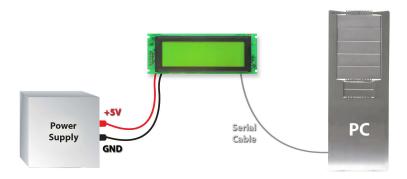
- 20 column by 4 line alphanumeric liquid crystal display
- Selectable communication protocol, serial at RS-232 or TTL levels or I²C
- Six, 5V -20mA, general purpose outputs for a variety of applications
- Lightning fast communication speeds, up to 57.6 kbps for RS-232 and 100 kbps for I²C
- Extended temperature available for extreme environments of -20C to 70C
- Extended voltage and efficient power supply available
- Built in font with provision for up to 8 user defined characters
- Use of up to 127 modules on the same 2 wire I²C interface
- Optional Dallas One-Wirebus that is capable of communicating with up to 32 devices
- Fully buffered so that no delays in transmission are ever necessary
- Ability to add a customized splash / startup screen
- Software controlled contrast and brightness with configurable time-out setting up to 90 minutes
- Use of up to a 25 key keypad with a 10 key buffer
- Horizontal or vertical bar graphs
- Fits Matrix Orbital's mountings without any modifications

1.4 Connecting to a PC

The LK204-25 connects seamlessly to a PC and it is an excellent means of testing the functionality. To connect your display to a PC, you will require a standard RS-232 9-pin serial cable such as the one pictured in *figure 5 on page 3*, as well as a modified 5V power adapter such as the one pictured in *figure 2 on page 2*.

In order to connect your display to a personal computer follow these easy instructions:

- 1. Plug the serial cable into the com port you wish to use.
- 2. Connect the modified 5V power adapter to a power lead from your PC power supply (you will have to open your computer case).
- 3. Connect the serial cable to the DB-9 connector on the back of the display.
- 4. Connect the 5V power adapter to the 4-pin connector on the back of the display.



WARNING DO NOT use the standard floppy drive power connector, as this will not provide you with the correct voltage and will damage the display module.

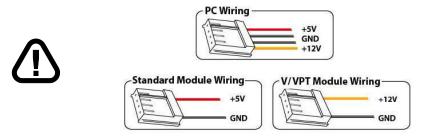


Figure 11: PC vs Matrix Orbital Display Module Wiring

1.5 Installing the Software

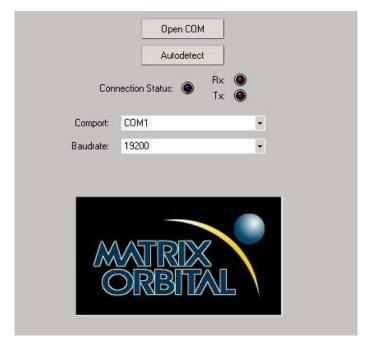
1.5.1 uProject

uProject was designed by Matrix Orbital to provide a simple and easy to use interface that will allow you to test all of the features of our alpha numeric displays.

To install uProject from the Matrix Orbital CD, follow the following steps:

- 1. Insert the Matrix Orbital CD-ROM into the CD drive
- 2. Locate the file, *uProject.exe*, which should be in the "CD-drive:\Download" directory.
- 3. Copy *uProject.exe* to a directory that you wish to run it from.
- 4. Double click on "uProject.exe"

Be sure to check the information selected in the COM Setup the first time uProject is run. Once this information is entered correctly the program can be used to control all functions of the graphic display.



Comport The serial port the display

is plugged in to.

Baudrate The communication speed

the display

module is set to. (Default

19,200)

Figure 12: uProject Settings

NOTES

• uProject and other alphanumeric software may also be downloaded from Matrix Orbital's support site at http://www.matrixorbital.ca/software/software_alpha/

2 Hardware Information

Refer to the following diagram for this chapter:

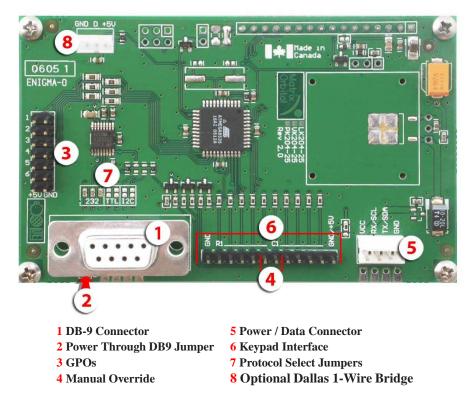
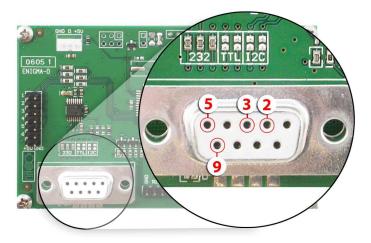


Figure 13: LK204-25

2.1 DB-9 Connector

The LK204-25 provides a DB-9 Connector to readily interface with serial devices which use the EIA232 standard signal levels of ± 12 V to ± 12 V. It is also possible to communicate at TTL levels of 0 to +5V by setting the $Protocol\ Select\ Jumpers$ to TTL. As an added feature it is also possible to apply power through pin 9 of the DB-9 Connector in order to reduce cable clutter. However, in order to accomplish this you must set the $Power\ Through\ DB$ -9 Jumper.



Pin 2 Tx \ SDA (I^2C data)

Pin 3 Rx \ SCL (I^2 C clock)

Pin 5 GND

Pin 9 PWR (Must solder Power Through DB-9 Jumper. See table 70 on page 54 for power requirements.)

Figure 14: RS-232 Pin out

2.1.1 Power Through DB-9 Jumper

In order to provide power through pin 9 of the *DB-9 Connector* you must place a solder jumper on the *Power through DB-9 Jumper* pictured in *figure 15* below. The LK204-25 allows all voltage models to use the power through DB-9 option, see table 70 on page 54 for display module voltage requirements.



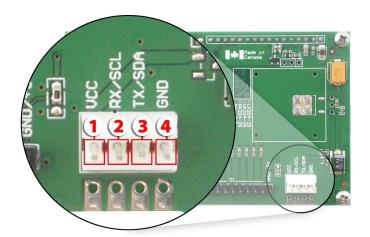
Figure 15: Power Through DB-9 Jumper



WARNING Do not apply voltage through pin 9 of the DB-9 connector AND through the Power/Data Connector at the same time.

2.2 Power/Data Connector

The *Power/Data Connector* provides a standard connector for powering the display module. The LK204-25 requires five volts for the standard display module, between nine to fifteen for the wide voltage (V) and between nine to thirty-five volts for the wide voltage with efficient power supply module (VPT). The voltage is applied through pins one and four of the four pin *Power/Data connector*. Pins two and three are reserved for serial transmission, using either the RS-232/TTL or the I²C protocol, depending on what has been selected by the *Protocol Select Jumpers*.



Pin 1 PWR (See table 70 on page 54)

Pin 2 Rx \ SCL (I^2 C clock)

Pin 3 Tx \ SDA (I^2C data)

Pin 4 GND

Figure 16: Power Connector and Pin out



WARNINGS

- Do not apply any power with reversed polarization.
- Do not apply any voltage other than the specified voltage.

2.3 Protocol Select Jumpers

The *Protocol Select Jumpers*, pictured below in *figure 17*, provide the means necessary to toggle the display module between RS-232, TTL and I²C protocols. As a default, the jumpers are set to RS-232 mode with solder jumps on the 232 jumpers. In order to place the display module in I²C mode you must first remove the solder jumps from the 232 jumpers and then place them on the I2C jumpers. The display will now be in I²C mode and have a default slave address of 0x50 unless it has been changed. Similarly, in order to change the display to TTL mode, simply remove the zero ohm resistors from the 232 or I²C jumpers and solder them to the TTL jumpers.

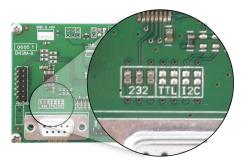
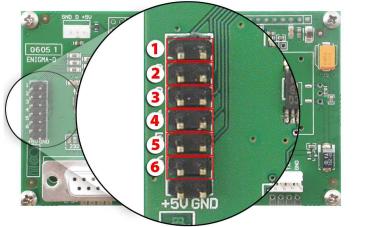


Figure 17: Protocol Select Jumpers

2.4 General Purpose Outputs

A unique feature of the LK204-25 is the ability to control relays and other external devices using a *General Purpose Output*, which can provide up to 20 mA of current and +5Vdc from the positive side of the GPO. This is limited by a 240 ohm resistor which is located to the above right of the GPOs as pictured below in *figure 21*. If the device, which is being driven by a GPO, requires a relatively high current (such as a relay) and has an internal resistance of its own greater than 250 ohms, then the 240 ohm resistor may be removed and replaced with a Jumper.



- (right) GND + (left) MAX: 20 mA, +5Vdc

Figure 18: General Purpose Output



WARNING If connecting a relay, be sure that it is fully clamped using a diode and capacitor in order to absorb any electro-motive force (EMF) which will be generated.

2.5 Dallas 1-Wire Bridge

In addition to the six general purpose outputs the LK204-25 offers an optional Dallas 1-wire bridge, to allow for an aditional thirty two 1-wire devices to be connected to the display. Please note that the display normally does not come with the Dallas 1-wire bridge. It will have to be ordered as a custom. Please talk to your sales representative if you would like this option. See *Section 8 on page 33*.



Figure 19: Dallas 1-Wire Bridge

2.6 Manual Override

The *Manual Override* is provided to allow the LK204-25 to be reset to factory defaults. This can be particularly helpful if the display module has been set to an unknown baud rate or I²C Slave Address and you are no longer able to communicate with it. If you wish to return the module to its default settings you must:

- 1. Power off the display module.
- 2. Place a Jumper on the Manual Override pins.
- 3. Power up the display module.
- 4. The display module is now set to its default values listed below in table 1.
- 5. Edit and save settings.

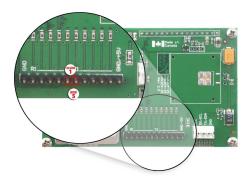


Figure 20: Manual Override Jumper

Table 1: Default Values

Brightness	255
Baud Rate	19.2 kbps
I ² C Slave Address	0x50
Data Lock	False
RS232AutoTransmitData	True

NOTE The display module will revert back to the old settings once turned off, unless the settings are saved.

2.7 Keypad Interface Connector

The LK204-25 provides a *Keypad Interface Connector* which allows for up to a five by five matrix style keypad to be directly connected to the display module. Key presses are generated when a short is detected between a row and a column. When a key press is generated a character, which is associated with the particular key press, is automatically sent on the Tx communication line. If the display module is running in I²C mode, the "Auto Transmit Keypress" function may be turned off, to allow the key presses to remain in the buffer so that they may be polled. The character that is associated with each key press may also be altered using the "Assign Key Codes" command, for more detailed information see the *Keypad Section*, on page 35.

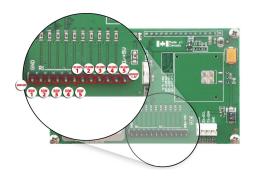


Figure 21: Keypad Interface Connector

NOTE The Ground / +5V pin is toggled by the jumper to the right of the keypad connector. Jump 1 & 2 for +5V or 2 & 3 for GND.

3 Troubleshooting

3.1 The display does not turn on when power is applied.

- First, you will want to make sure that you are using the correct power connector. Standard floppy drive power cables from your PC power supply may fit on the Power/Data Connector however they do not have the correct pin out as can be seen in *figure 11 on page 6*. Matrix Orbital supplies power cable adapters for connecting to a PC, which can be found in the *Accessories Section on page 2*.
- The next step is to check the power cable which you are using for continuity. If you don't have an ohm meter, try using a different power cable, if this does not help try using a different power supply.
- The last step will be to check the *Power / Data Connector* on the LK204-25. If the *Power / Data Connector* has become loose, or you are unable to resolve the issue, please contact Matrix Orbital, see *14.6 on page 58* for contact information.

3.2 The display module is not communicating.

- First, check the communication cable for continuity. If you don't have an ohm meter, try using a different communication cable. If you are using a PC try using a different Com Port.
- Second, please ensure that the display module is set to communicate on the protocol that you are using, by checking the *Protocol Select Jumpers*. To change the protocol used by the display module see *Section 2.3 on page 10*.
- Third, ensure that the host system and display module are both communicating on the same baud rate. The default baud rate for the display module is 19200 bps.
- If you are communicating to the display via I²C please ensure that the data is being sent to the correct address. The default slave address for the display module is 0x50.

NOTE I²C communication will always require pull up resistors.

• Finally, you may reset the display to it's default settings using the *Manual Override Jumper*, see *Section 2.6 on page 12*.

3.3 The display module is communicating, however text cannot be displayed.

• A common cause may be that the contrast settings have been set to low. The solution to this problem is to adjust the contrast settings. The default setting that will work in most environments is 128.

NOTE Optimal contrast settings may vary according to factors such as temperature, viewing angle and lighting conditions.

If you are unable to resolve any issue please contact Matrix Orbital. See 14.6 on page 58 for contact information.

4 Communications

4.1 Introduction

The commands listed in this chapter describe how to configure data flow on the LK204-25.

4.1.1 I²C Communication Summary

The LK204-25 is capable of communicating at 100 KHz in I^2C mode, with 127 units addressable on a single I^2C communication line. However, in order to communicate via I^2C you must first ensure that pull up resistors, with a nominal value of 1K to 10K, are placed on the SCL and SDA communication lines coming from pins two and three of the Data / Power Connector respectively. Data responses by the module are automatically output via RS232, in case the host will be querying the module, it is necessary for the host to inform the module that its responses are to be output via I^2C . This can be done by sending command 254 /160 / 0 to turn off auto transmission of data in RS232. This will keep the data in the buffer until the master clocks a read of the slave. The I^2C data lines operate at 5V normally or 3.3V for -1U style units. The LK204-25 uses 8-bit addressing, with the 8th or Least Significant Bit (LSB) bit designated as the read/write bit, a 0 designates a write address and a 1 designates a read address. The default read address of the display module will be 0x51, whereas the write address is 0x50 by default. This address may be changed by using cmd 254 / 51 / <address>. The LK204-25 should only be sent addresses that are even (LSB is 0). When the I^2C master wishes to write to the display, the effective address is \$50 (0101 0000), since the LSB has to be 0 for an I^2C master write. When the I^2C master wishes to read the LK204-25, the effective address is \$51 (0101 0001), since the LSB has to be 1 for an I^2C master read.

If we take a standard Phillips 7 bit address of \$45 (100 0101), Matrix Orbital's LK204-25 would describe this Phillips I²C address as \$8A (1000 1010). The read address would be \$8B (1000 1011).

The unit does not respond to general call address (\$00).

When communicating in I²C the LK204-25 will send an ACK on the 9th clock cycle when addressed. When writing to the display module, the display will respond with a ACK when the write has successfully been completed. However if the buffer has been filled, or the module is too busy processing data it will respond with a NAK. When performing a multiple byte read within one I²C transaction, each byte read from the slave should be followed by an ACK to indicate that the master still needs data, and a NAK to indicate that the transmission is over.

The LK204-25 has some speed limitations, especially when run in I^2C mode. Here are some considerations when writing I^2C code:

- * to be able to read the replies of query commands (eg. cmds 54, 55) the following command must be sent (only needs to be sent once, so this can be done somewhere in init): 254 / 160 / 0 this command puts the reply data in the I^2C output buffer instead of the RS232 output buffer. Please note that due to a 16 byte output buffer, query commands that reply with more than 16 bytes cannot be read (eg cmd Get FileSystem Directory)
 - * 3ms delay between the read commands
 - * 625us delay in between data bytes within a transaction is necessary
 - * 375us between transactions is necessary

NOTE These delays are consrevative, and may be decreased based on performance

4.1.2 I²C Transaction Example

The typical I²C transaction contains four parts: the start sequence, addressing, information, and stop sequence. To begin a transaction the data line, SDA, must toggle from high to low while the clock line, SCL, is high. Next, the display must be addressed using a one byte hexadecimal value, the default to write to the unit is 0x50, while read is 0x51. Then information can be sent to the unit; even when reading, a command must first be sent to let the unit know what type of information it is required to return. After each bit is sent, the display will issue an ACK or NACK as described above. Finally, when communication is complete, the transaction is ended by toggling the data line from low to high while the clock line is high. An example of the use of this algorithm to write a simple "HELLO" message can be seen in 2.

Table 2: I²C Transaction Algorithm

START	Toggle SDA high to low		
Address	0x50		
Information	0x48 0x45 0x4C 0x4C 0x4F		
STOP	Toggle SDA low to high		

4.1.3 Serial Communication

In addition to being able to communicate via I^2C the LK204-25 communicates natively through the RS-232 protocol at at a default baud rate of 19,200 bps and is capable of standard baud rates from 9600 to 115,200 bps. Furthermore the LK204-25 is also capable of reproducing any non-standard baud rate in between using values entered into our baud rate generation algorithm and set through command 164 (0xA4). The display module communicates at standard voltage levels of -30V to +30V or at TTL levels of 0 to +5V by setting the *Protocol Select Jumpers* to TTL.

4.2 Changing the I²C Slave Address

Syntax	Hexadecimal	0xFE 0x33 [adr]	
	Decimal	254 51 [adr]	
	ASCII	254 "3" [adr]	
Parameters	Parameter	Length	Description
	adr	1	The new I ² C write address (0x00 -
			0xFF).
Description			address of the module between 0x00
	and 0xFF. The I	² C write address:	must be an even number and the read

and 0xFF. The I^2C write address must be an even number and the read address is automatically set to one higher. For example if the I^2C write address is set to 0x50, then the read address is 0x51.

NOTE The change in address is immediate.

Remembered Always Default 0x50

4.3 Changing the Baud Rate

Syntax	Hexadecimal	0xFE 0x39 [speed]		
·	Decimal	254 57 [speed]		
	ASCII	254 "9" [speed]		
Parameters	Parameter	Length	Description	
	speed	1	Hex value corresponding to a baud	
			rate.	

This command sets the RS-232 port to the specified [speed]. The change takes place immediately. [speed] is a single byte specifying the desired port speed. Valid speeds are shown in the table below. The display module can be manually reset to 19,200 baud in the event of an error during transmission, including transmitting a value not listed below, by setting the manual override jumper during power up. However, it should be noted that this command will be ignored until the manual override jumper is removed again.

Hex Value	Baud Rate
53	1200
29	2400
CF	4800
67	9600
33	19200
22	28800
19	38400
10	57600
8	115200

NOTE This command is not available in I²C mode.

Remembered Always
Default 19,200 bps

4.4 Setting a Non-Standard Baud Rate

Syntax Hexadecimal 0xFE 0xA4 [speed]

Decimal 254 164 [speed]

Parameters Parameter Length Description
speed 2 Inputed LSB MSB from baud rate
formula (12-2047).

Description This command sets the RS-232 port to a non-standard baud rate. The

command accepts a two byte parameter that goes directly into the modules baud generator. Use the formula, $speed = \frac{CrystalSpeed}{8 \times DesiredBaud} - 1$ to calculate the [speed] for any baud rate setting. The speed can be anywhere from 12 to 2047 which corresponds to a baud range of 977 to 153,800 baud. Setting the baud rate out of this range could cause the display to stop working properly and require the Manual Override

jumper to be set.

Remembered Always

Crystal Speed 16 Mhz

Desired BAUD 13,500

$$speed = \frac{crystalspeed}{8*DesiredBaud} - 1$$
 $speed = \frac{16,000,000}{8*13,500} - 1$

$$speed = 148.15 - 1$$
 $speed = 147.15$

- LSB = 0x93 (rounded)
- MSB = 0x00
- Intended Baud Rate: 13,500 baud Actual Baud Rate: $\frac{16,000,000}{8(147+1)}$ =13,514 Percent Difference: 0.1%

NOTES

- Results from the formula are rounded down to the nearest whole number (i.e 73.07 = 73).
- This formula becomes less acurate as baud rates increase, due to rounding.
- Place the speed result backwards into the formula to receive the actual baud rate. $(Baud = \frac{CrystalSpeed}{8(speed+1)})$
- The actual baud rate must be within 3% of the intended baud rate for the device to communicate.

NOTES

• This command is not available in I²C mode.

5 Text

5.1 Introduction

The LK204-25 is an intelligent display module, designed to reduce the amount of code necessary to begin displaying data. This means that it is able to display all ASCII formated characters and strings that are sent to it, which are defined in the current character set. The display module will begin displaying text at the top left corner of the display area, known as home, and continue to print to the display as if it was a page on a typewriter. When the text reaches the bottom right row, it is able to automatically scroll all of the lines up and continue to display text, with the auto scroll option set to on.

5.1.1 Character Set

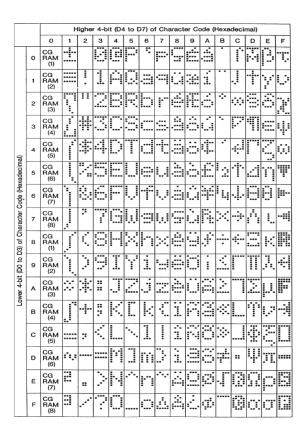


Figure 22: Character Set

5.1.2 Control Characters

In addition to a full text set, the LK204-25 display supports the following ASCII Control characters:

0x08 Backspace

0x0C Clear screen / New page

0x0D Carriage return

0x0A Line feed / New line

5.2 Auto Scroll On

Syntax Hexadecimal 0xFE 0x51

Decimal 254 81 ASCII 254 "O"

Description When auto scrolling is on, it causes the display to shift the entire

display's contents up to make room for a new line of text when the text

reaches the end of the last row.

Remembered Yes Default On

5.3 Auto Scroll Off

Syntax Hexadecimal 0xFE 0x52

Decimal 254 82 ASCII 254 "R"

Description When auto scrolling is disabled the text will wrap to the top left corner

of the display area when the text reaches the end of last row.

Remembered Yes

5.4 Clear Screen

Syntax Hexadecimal 0xFE 0x58

Decimal 254 88 ASCII 254 "X"

Description This command will immediately clear all of the contents of the display.

Remembered No

5.5 Changing the Startup Screen

Syntax Hexadecimal 0xFE 0x40

Decimal 254 64 ASCII 254 "@"

Description In order to change the text that is displayed by the LK204-25 when it

starts up simply send the command bytes 254 64 followed by the characters that you wish to display, starting from the top left. This command will automatically line wrap the characters that are sent to it.

Remembered Yes

5.6 Set Auto Line Wrap On

Hexadecimal 0xFE 0x43 **Syntax**

> Decimal 254 67 254 "C" **ASCII**

Description Enabling Auto Line Wrap will allow the cursor to automatically wrap

over to the next line when the current line is full.

NOTE Line wraps may occur in the middle of a word.

Remembered Yes

Set Auto Line Wrap Off 5.7

Syntax Hexadecimal 0xFE 0x44

> Decimal 254 68 **ASCII** 254 "D"

Disabling Auto Line Wrap will allow you to change the line Description

> configuration. The normally sequentional progression becomes an alternating pattern. Rather than moving from line 1 to 2 to 3, the display will write from line 1 to 3 to 2. For a two line display, this means that a row's worth of characters written between the first and second lines or after the second will not be displayed on the screen or wrapped. The

four line models will see only an alteration in line flow.

Yes Remembered

Set Cursor Position

Hexadecimal 0xFE 0x47 [col] [row] **Syntax**

> Decimal 254 71 [col] [row] **ASCII** 254 "G" [col] [row]

Parameters

Length Description Parameter col Column Row row 1

Description This command will allow you to manually set the cursor position, which

controls the text insertion point, by specifying the [col] and [row] of the

new proposed cursor position.

NOTE If the cursor position is set past the end of a line it will wrap to the beginning of the next line.

Remembered No

5.9 Go Home

Syntax Hexadecimal 0xFE 0x48

Decimal 254 72 ASCII 254 "H"

Description This command will return the cursor to the top left corner of the display

area, identified as row one, column one.

Remembered No

5.10 Move Cursor Back

Syntax Hexadecimal 0xFE 0x4C

Decimal 254 76 ASCII 254 "L"

Description This command will move the cursor back one space. If this command is

sent when the cursor is at the home position the cursor will wrap to the last row / column position if line wrap is on. Sending this command will not effect the text displayed on the module, however any characters that are sent will over write the current characters that are being displayed.

Remembered No

5.11 Move Cursor Forward

Syntax Hexadecimal 0xFE 0x4D

Decimal 254 77 ASCII 254 "M" Description This command will move the cursor forward one space. If this

command is sent when the cursor is at the bottom right position the cursor will wrap back to the home position if line wrap is on. Sending this command will not effect the text displayed on the module, however any characters that are sent will over write the current characters that are

being displayed.

Remembered No

5.12 Underline Cursor On

Syntax Hexadecimal 0xFE 0x4A

Decimal 254 74 ASCII 254 "J"

Description This command will cause the LK204-25 to display an underline cursor

at the current text insertion point.

Remembered Yes

5.13 Underline Cursor Off

Syntax Hexadecimal 0xFE 0x4B

Decimal 254 75 ASCII 254 "K"

Description This command will turn the the underline cursor off.

Remembered Yes

5.14 Blinking Block Cursor On

Syntax Hexadecimal 0xFE 0x53

Decimal 254 83 ASCII 254 "S"

Description This command will cause the LK204-25 to display a block cursor at the

current text insertion point.

Remembered Yes

5.15 Blinking Block Cursor Off

Syntax Hexadecimal 0xFE 0x54

Decimal 254 84

ASCII 254 "T"

Description This command will turn the block cursor off.

Remembered Yes

6 Special Characters

6.1 Introduction

The LK204-25 has the ability to create four different sets of eight custom characters and save them to internal banks of memory. Each set of eight can be recalled from memory at any time, and selected characters can be written to the display screen. Characters and sets can be created at any time, saved for later use, and displayed to the screen through the intuitive command structure described below.

6.2 Creating a Custom Character

Syntax	Hexadecimal	0xFE 0x4E [refID] [data]		
·	Decimal	254 78 [refID]	[data]	
	ASCII	254 "N" [refID]] [data]	
Parameters	Parameter	Length	Description	
	refID	1	Character reference ID (0-7).	
	data	8	Character data.	

The LK204-25 allows for upta to eight custom defined characters to be added onto the character set. A custom character is a five by eight pixel matrix with each row represented by a byte value. For example:

-	Custom	Chara	Decimal	Hex		
1	0	0	0	0	16	0x10
1	0	0	0	0	16	0x10
1	0	0	0	0	16	0x10
1	0	0	0	0	16	0x10
1	0	1	1	0	22	0x16
1	1	0	0	1	25	0x19
1	0	0	0	1	17	0x11
1	0	0	0	1	17	0x11

Each bit value of one, in the table, represents an on pixel, whereas a value of zero represents a pixel that is turned off. Therefore in order to define custom character 'h' you would send the command byte prefix 254 followed by the command 78. Next, you will have to select the memory location in which you wish to save the character in. The available memory locations for this command are zero through to seven. After sending the memory location, or [refID], you may then send the eight byte custom character data in sequence from the top to the bottom.

Once you have defined a custom character you may display it by sending the display module the [refID]. For example if a custom character was saved in position one, the command to display the custom character, at the current cursor position, would be simply to send the number one to the display module without quotes.

Remembered

No

6.3 Saving Custom Characters

Syntax	Hexadecimal	0xFE 0xC1 [Ba	ank] [ID] [Data]
·	Decimal	254 193 [Bank]] [ID] [Data]
Parameters	Parameter	Length	Description
	Bank	1	Memory bank to save to (0-4).
	ID	1	Character ID (0-7)
	Data	8	Character Definition

New to the LK204-25 has added five non-volatile memory banks for custom character storage. This is intended to allow you to create your own custom bar graphs, medium/large numbers and startup screen. However, each memory bank may be used to store a set of any eight custom characters; with the only provision being that memory bank zero contains the characters that will be used in the startup screen. By default the memory banks will be loaded as follows:

[Bank]	Description
0	Startup screen characters.
1	Horizontal bars
2	Vertical bars
3	Medium numbers
4	Large numbers

In order to save new custom characters into a memory bank, follow the same process as you would for creating a custom character, see Section 6.2 on page 25, only use 254 193 [Bank Number] before sending the [ID] and character [Data].

Remembered

Yes

6.4 Loading Custom Characters

Syntax	Hexadecimal	0xFE 0xC0 [Ba	nk]	
•	Decimal	254 192 [Bank]		
Parameters	Parameter	Length	Description	
	Bank	1	Memory bank to save to (0-4).	
Description This command is used to load the custom characters into the vomemory so that they may be used. If custom bar graph or number characters are stored in the memory banks, this command may be used.			custom characters into the volatile	
			. If custom bar graph or number	
			ory banks, this command may be used	
	instead of initializing the bar graph / number. To use this command send			
	the command bytes followed by the [Bank] that contains the custom			
	character data th	nat you want to re	trieve.	

Remembered No

6.5 Save Startup Screen Custom Characters

Syntax	Hexadecimal	0xFE 0xC2 [refID] [data]		
•	Decimal	254 194 [refID] [data]		
Parameters	Parameter	Length	Description	
	refID	1	Character reference ID (0-7).	
	data	8	Character data.	

Using this command you may create the custom characters. that will be stored in memory bank zero, which will be used in the startup screen. For more information about creating custom characters see *Section 6.2 on page 25*.

NOTES

- Changes only take place once the power has been cycled.
- This command is the same as sending CMD 254 / 193 / 0 / [ID] / [DATA]

Remembered

Yes

6.6 Initialize Medium Number

Syntax Hexadecimal 0xFE 0x6D

Decimal 254 109 ASCII 254 "m"

Description This command will load the default medium number characters into the

volatile memory. If you have stored your own custom medium numbers, use the 'Load Custom Characters' command to load your custom character data into the volatile memory. This command will allow you

to use the 'Place Medium Numbers' command.

Remembered No

6.7 Place Medium Numbers

Syntax	Hexadecimal	0xFE 0x6F [Row] [Col] [Digit]		
	Decimal	254 111 [Row]	[Col] [Digit]	
	ASCII	254 "o" [Row] [Col] [Digit]		
Parameters	Parameter	Length	Description	
·	Row	1	The row number.	
	Col	1	The column number.	
	Digit	1	Medium number to place (0-9).	

This command will place a medium number (two columns high) at the [row] and [col] specified.

NOTE Medium Numbers must be initialized before this command is executed.

Remembered No

Description

6.8 Initialize Large Numbers

Syntax Hexadecimal 0xFE 0x6E

Decimal 254 110 ASCII 254 "n"

Description This command will load the default large number characters into the

volatile memory. If you have stored your own custom large numbers, use the 'Load Custom Characters' command instead to load your custom character data into the volatile memory. This command will

allow you to use the 'Place Large Numbers' command.

Remembered No

6.9 Place Large Number

Syntax Hexadecimal 0xFE 0x23 [Col] [Digit]

Decimal 254 35 [Col] [Digit] ASCII 254 "#" [Col] [Digit]

Parameters Parameter Length Description

Col 1 The column number.
Digit 1 Large number to place (0-9).

Description This command will place a large number (four columns high) at the

[row] and [col] specified.

NOTE Large Numbers must be initialized before this command is executed.

Remembered No

6.10 Initialize Horizontal Bar

Syntax Hexadecimal 0xFE 0x68

Decimal 254 104 ASCII 254 "h"

Description This command will load the default horizontal bar characters into the

volatile memory. If you have stored your own custom horizontal bar data, use the 'Load Custom Characters' command instead to load your custom bar data into the volatile memory. This command will allow you

to use the 'Place Horizontal Bar' command.

Remembered No

6.11 Place Horizontal Bar Graph

Syntax	Hexadecimal Decimal ASCII	254 124 [Col] [J	l] [Row] [Dir] [Length] Row] [Dir] [Length] .ow] [Dir] [Length]	
Parameters	Parameter	Length	Description	
	Col	1	The column number.	
	Row	1	The row number.	
	Dir	1	The direction of the bar data (0 or	
			1).	
	Length	1	The length of the bar data.	
Description	This command w	his command will place a bar graph at [row], [column]. A [Dir] value		
	of zero will cause the bar to go right, and one will cause the bar to go			
left. The [Length] is the size in pixels of the bar graph.				

NOTES

- Horizontal Bars must be initialized before this command is executed.
- Bar graphs may be one directional only.

Remembered No

6.12 Initialize Narrow Vertical Bar

Syntax	Hexadecimal	0xFE 0x73

Decimal 254 115 ASCII 254 "s"

Description This command will load the narrow vertical bar characters into the

volatile memory. If you have stored your own custom vertical bar data, use the 'Load Custom Characters' command instead to load your custom bar data into the volatile memory. This command will allow you

to use the 'Place Vertical Bar' command.

NOTE Narrow bars have a width of two pixels.

Remembered No

6.13 Initialize Wide Vertical Bar

Syntax Hexadecimal 0xFE 0x76

Decimal 254 118 ASCII 254 "v"

Description This command will load the wide vertical bar characters into the volatile

memory. If you have stored your own custom vertical bar data, use the 'Load Custom Characters' command instead to load your custom bar data into the volatile memory. This command will allow you to use the

'Place Vertical Bar' command.

NOTE Wide bars have a width of five pixels.

Remembered No

6.14 Place Vertical Bar

Sv	ntax	Hexadecimal	0xFE 0x3D	[Column]	[Length]

Decimal 254 61 [Column] [Length] ASCII 254 "=" [Column] [Length]

Parameters Parameter Length Description

Parameter Length Description

Column 1 The column number.

Length 1 The length of the bar data.

Description This command will place a bar graph at the specified [Column] with the

specified [Length]. The [Length] is the size in pixels of the bar graph.

NOTES

- A Vertical Bar style must be initialized before this command is executed.
- Bar graphs may be one directional only.

Remembered No

7 General Purpose Output

7.1 Introduction

General purpose outputs allow you to connect devices, such as LEDs, to the LK204-25 and supply them with up to 20mA of current at 5V. The LK204-25 has 6 GPOs which are software controlled, with functions to turn them on/off and set the power state for the next startup.

7.2 General Purpose Output Off

Syntax Hexadecimal 0xFE 0x56 [Num]

Decimal 254 86 [Num] ASCII 254 "V" [Num]

Parameters Parameter Length Description

Num 1 GPO number.

Description This command turns OFF general purpose output [num].

NOTE OFF means that the output is pulled LOW.

Remembered Yes

7.3 General Purpose Output On

Syntax Hexadecimal 0xFE 0x57 [Num]

Decimal 254 87 [Num] ASCII 254 "W" [Num]

Parameters Parameter Length Description

Num 1 GPO number.

Description This command turns ON general purpose output [num]. The standard

GPO's on the LK204-25 output 20mA of current at 5V.

NOTE ON means the output is pulled HIGH.

Remembered Yes

7.4 Set Startup GPO state

Syntax Hexadecimal 0xFE 0xC3 [Num] [state]

Decimal 254 195 [Num] [state]

Parameters Parameter Length Description

Num 1 GPO number. state 1 Startup state (0: Off, 1: On) Description This command will set the startup state for the GPO on the next power

up. A value of one will cause the GPO to be off on the next startup

while a value of one will cause the GPO to be on.

NOTE This command does not affect the current state of the GPO.

Remembered Always

8 Dallas 1-Wire

8.1 Introduction

Another convenient feature of the LK204-25 is that it provides a Dallas 1-wire interface in order to readily communicate with up to thirty two 1-wire devices on a single bus. 1-wire communication is begun by discovering the address of the device that you wish to communicate with. To do this you must send the "Search for a 1-Wire Device' command. After you have established the address of the device that you wish to communicate with, you may begin a transaction with the device

8.2 Search for a 1-Wire Device

Syntax Hexadecimal 0xFE 0xC8 0x2

Decimal 254 200 2

This command will allow you to begin communicating with the devices on the 1-wire bus by returning a packet containing device information for each 1-wire device on the bus in the form of:

Search Return Packet

Offset	Offset	Description
(Bytes)	(Bytes)	
0	2	
		0x232A Preamble
2	1	
		0x8A Packet is 10 bytes long, another address will follow
		0x0A Packet is 10 bytes long, this is the last address
3	1	0x31 - 1-Wire Packet Type
4	1	Error Code (0x00 for success)
5	8	1-Wire Address
13	1	CRC8 0x00 means the last address was valid
		was vanu

Remembered

No

8.3 Dallas 1-Wire Transaction

Syntax	Hexadecimal Decimal	0xFE 0xC8 0x1 [flags] [SndBits] [RcvBits] [Data] 254 200 1 [flags] [SndBits] [RcvBits] [Data]			
Parameters	Parameter	Length	Description		
·	flags	1	Flags to control optional		
			components of the transaction.		
	SndBits	1	The number of bits you will be		
			transmitting on the bus.		
	RcvBits	1	The number of bits you will be		
			reading on the bus.		
	Data	variable	Data to be transmitted, LSB to		
			MSB.		

This command will perform a single transaction on the 1-wire bus in this order:

- 1. Bus Reset.
- 2. Transmit data onto the bus.
- 3. Receive data from the bus.

The number of bits to be transmitted and read must be specified for this command to be successful.

NOTE To determine what functions the device will respond to, consult the devices' data sheet.

1-Wire Flags

Bit	Description
7	
6	Unused
5	(0 for future compatibility)
4	
3	Add a CRC8 to the end of the transmitted data
2	(0 for future compatibility)
1	Assume last received byte is a CRC8 and validate it
0	Reset bus before transaction

1-Wire Error Codes

Code	Description
0x00	Success
0x01	Unknown 1-Wire Command
0x02	No devices on the bus
0x03	Fatal search error

Remembered No

9 Keypad

9.1 Introduction

The LK204-25 supports up to a 25 key, matrix style, keypad and may be configured to allow key presses to be automatically transmitted via RS-232 or polled through I²C. The LK204-25 also allows for autorepeating key presses, and remapping of all keypad character codes.

The connector is not keyed so the keypad will probably plug in either of two ways. The display will not be damaged by reversing the connector. However, the keypad will generate a different ASCII character mapping for each position. If the connector has fewer than 10 pins it should be centered on the display

connector. The keypad is scanned whenever a key is pressed; there is no continuous key scan. This means that key presses are dealt with immediately without any appreciable latency. This also prevents electrical noise which is often caused by continuous key scans.

9.1.1 I²C Interface

The keypad is read by I^2C master read. In short, this means that a read of the module will always return the first unread key press. A read is initiated by writing to the module with its base address plus 1, then clocking the module's return byte after the module releases the SDA line. Much more detail on this basic I^2C function can be found in the I^2C specification by Phillips.

9.1.2 RS232 Interface

By default on any press of a key, the module will immediately send out the key code at the selected baud rate. This behavior can be modified using commands found in the next section.

9.2 Auto Transmit Key Presses On

Syntax Hexadecimal 0xFE 0x41

Decimal 254 65 ASCII 254 "A"

Description In this mode, all key presses are sent immediately to the host system

without the use of the poll keypad command. This is the default mode

on power up.

NOTE This command is not available in I^2C .

Remembered Yes Default On

9.3 Auto Transmit Key Presses Off

Syntax Hexadecimal 0xFE 0x4F

Decimal 254 79 ASCII 254 "O" Description In this mode, up to 10 key presses are buffered until the unit is polled by

the host system, via the poll keypad command 254 38. Issuing this

command places the unit in polled mode.

NOTE This command is not available in I^2C .

Remembered Yes

9.4 Poll Key Press

Syntax Hexadecimal 0xFE 0x26

Decimal 254 38 ASCII 254 "&"

Description This command returns any buffered key presses via the serial interface.

The host system must be set up to receive key codes. When the display receives this command, it will immediately return any buffered key presses which may have not been read already. If there is more than one key press buffered, then the high order bit (MSB) of the returned key code will be set (1). If this is the only buffered key press, then the MSB will be cleared (0). If there are no buffered key presses, then the returned code will be 0x00. Please note that to make use of this command, the "Auto Transmit Key Presses" mode should be off.

NOTE This command is not available in I^2C . To read keys in I^2C mode, one just needs to address the module and read a byte. No preceding commands are necessary. If there are no keys pressed the read will result in a 0x00.

Remembered No

9.5 Clear Key Buffer

Syntax Hexadecimal 0xFE 0x45

Decimal 254 69 ASCII 254 "E"

Description This command clears any unread key presses. In a menu application, if

the user presses a key which changes the menu context, any following key presses may be inaccurate and can be cleared out of the buffer between menu changes to prevent jumping around the menu tree. It may also be used, in effect, to reset the keypad in case the host application

resets for whatever reason.

Remembered No

9.6 Set Debounce Time

Syntax	Hexadecimal	OxFE 0x55 [time	eJ
	Decimal	254 85 [time]	
_	ASCII	254 "U" [time]	
Parameters	Parameter	Length	Description
_	time	1	Debounce time in increments of

6.554ms (0 - 255).

Description This command sets the time between key press and key read. All key

types with the exception of latched piezo switches will 'bounce' for a varying time, depending on their physical characteristics. The [time] value is in increments of 6.554ms. The default debounce time for the module is 8 (about 52ms), which is adequate for most membrane

keypads.

Remembered Yes Default 8

9.7 Set Auto Repeat Mode

Syntax	Hexadecimal	0xFE 0x7E [mode]		
	Decimal	254 126 [mode]		
	ASCII	254 "~" [mode]		
Parameters	Parameter	Length	Description	
	mode	1	Auto Repeat Mode (0: Resend Key	
			, 1: Key Up/Down)	

Two auto repeat modes are available and are set via the same command:

Resend Key Mode: 0x00Key Up/Down Mode: 0x01

Resend Key Mode This mode is similar to the action of a keyboard on a PC. In this mode, when a key is held down, the key code is transmitted immediately followed by a 1/2 second delay. After this delay, key codes will be sent via the RS-232 interface at a rate of about 5 codes per second. This mode has no effect if polling or if using the I²C interface.

Key Up/Down Mode This mode may be used when the typematic parameters of the "Resend Key Code" mode are unacceptable or if the unit is being operated in polled mode. The host system detects the press of a key and simulates an auto repeat inside the host system until the key release is detected. In this mode, when a key is held down, the key code is transmitted immediately and no other codes will be sent until the key is released. On the release of the key, the key release code transmitted will be a value equal to the key down code plus 20 hex.

Remembered Examples

Yes

When the key code associated with key 'P' (0x50) is pressed, the release code is 'p' (0x70). In RS-232 polled mode or via the I^2C , the "Key Down / Key Up" codes are used; however, the user should be careful of timing details. If the poll rate is slower than the simulated auto-repeat it is possible that polling for a key up code will be delayed long enough for an unwanted key repeat to be generated.

9.8 Auto Repeat Mode Off

Syntax Hexadecimal 0xFE 0x60

Decimal 254 96 ASCII 254 ""

Description This command turns auto repeat mode off. See Set Auto Repeat Mode.

Remembered No

9.9 Assign Keypad Codes

Syntax Hexadecimal 0xFE 0xD5 [KDown] [KUp]
Decimal 254 213 [KDown] [KUp]

Parameter	Length	Description
KDown	25	Key down codes
KUp	25	Key up codes
	KDown	KDown 25

This command will allow you to reassign the key codes that correspond to the key presses on the matrix style key pad. The first 25 bytes that are transmitted will be used for the key down codes and the next 25 bytes that are transmitted will be used for the key up codes.

	Key Down							Key	'Up		
	1	2	3	4	5		1	2	3	4	5
1	A	В	С	D	Е	1	a	b	С	d	e
2	F	G	Н	I	J	2	f	g	h	i	j
3	K	L	M	N	О	3	k	1	m	n	0
4	P	Q	R	S	T	4	p	q	r	S	t
5	U	V	W	X	Y	5	u	V	W	X	у

Remembered

Always

10 Display Functions

10.1 Introduction

The LK204-25 employs software controlled display settings, which allow for control over, clearing the screen, changing the brightness and contrast or setting timers for turning it on or off. The combination of these allow you complete software control over your display's appearance.

10.2 Display On

Syntax	Hexadecimal	0xFE 0x42 [mi	n]
	Decimal	254 66 [min]	
	ASCII	254 "B" [min]	
Parameters	Parameter	Length	Description
	min	1	Minutes before turning the display
			on (0 to 90).
Description	expired, with a the backlight sh	ninety minute ma ould turn on imm It while the remen	nt on after the [minutes] timer has eximum timer. A time of 0 specifies that nediately and stay on. When this mber function is on, the timer will reset
Remembered Default	Yes 0		

Display Off 10.3

Hexadecimal 0xFE 0x46 **Syntax**

Decimal 254 70 254 "F" **ASCII**

This command turns the backlight off immediately. The backlight will Description

remain off until a 'Display On' command has been received.

Remembered Yes

Set Brightness 10.4

Hexadecimal 0xFE 0x99 [brightness] Syntax

> Decimal 254 153 [brightness]

Parameters Parameter Length Description

> brightness Display brightness setting (0 to

> > 255).

Description This command sets the display [brightness]. If the remember function is

on, this command acts the same as 'Set and Save Brightness'.

Remembered Yes 255 Default

Set and Save Brightness 10.5

0xFE 0x98 [brightness] Syntax Hexadecimal

> Decimal 254 152 [brightness]

Length Parameter Description **Parameters**

> Backlight setting (0 to 255). brightness

Description This command sets and saves the display [brightness] as default.

Remembered Always

10.6 **Set Contrast**

0xFE 0x50 [contrast] **Syntax** Hexadecimal

> Decimal 254 80 [contrast] **ASCII** 254 "P" [contrast]

Parameters Parameter Length Description

Contrast value (0 to 255). contrast

This command sets the display's contrast to [contrast], where [contrast] is a value between 0x00 and 0xFF (between 0 to 255). Lower values cause 'on' elements in the display area to appear lighter, while higher values cause 'on' elements to appear darker. Lighting and temperature conditions will affect the actual value used for optimal viewing. Individual display modules will also differ slightly from each other in appearance. In addition, values for optimal viewing while the display backlight is on may differ from values used when backlight is off. This command does not save the [contrast] value, and is lost after power down; but this command has the option of remembering the settings when issued with the Remember function 'on'. When this is the case, this command is the same as the Set and Save Contrast command.

NOTE This command has only 32 levels for X-Board based displays, meaning eight contrast settings will have the same single effect. Efectively, values 0 through 7, 8 through 15, and so on will result in the same setting.

Remembered Default Yes 128

10.7 Set and Save Contrast

Syntax Hexadecimal 0xFE 0x91 [contrast]
Decimal 254 145 [contrast]

Parameters

Parameter Length Description

contrast 1 Contrast value (0 to 255).

Description

This command sets the display's contrast to [contrast], where [contrast] is a value between 0x00 and 0xFF (between 0 to 255). Lower values cause 'on' elements in the display area to appear lighter, while higher values cause 'on' elements to appear darker. Lighting conditions will affect the actual value used for optimal viewing. Individual display modules will also differ slightly from each other in appearance. In addition, values for optimal viewing while the display backlight is on may differ from values used when backlight is off.

NOTE This command saves the [contrast] value so that it is not lost after power down.

Remembered Default Yes 128

11 Data Security

11.1 Introduction

Ensuring that your LK204-25 display's exactly what you want it to can be the difference between a projects success and failure. This is why we incorporate features such as Data Lock into the LK204-25 With this new feature you now are in control over of how and when settings will be changed so there is no need to worry about the module acting exactly like you expected it to because all the settings may be locked and remembered for the next power up.

11.2 Set Remember

Syntax	Hexadecimal	0xFE 0x93 [switch]	
	Decimal	254 147 [exviteh]	

Parameters Parameter Length

Parameter Length Description
switch 1 0: Do not remember, 1: Remember

Description

This command allows you to switch the remember function on and off. To use the remember function, set remember to on, then set all of the settings that you wish to save, settings that are listed as 'Remember: Yes' support being saved into the non-volatile memory. After you have set all of the commands that you wish to save, you may then cycle the power and check the display settings to ensure that all the settings have been saved. If you wish to use remember again after cycling the power, you must set it to on again.

NOTES

- Writing to non-volatile memory is time consuming and slows down the operation of the display.
- Non-volatile memory has a 'write limit' and may only be changed approximately 100,000 times.

Remembered No
Default Do not remember

11.3 Data Lock

Syntax Hexadecimal 0xFE 0xCA 0xF5 0xA0 [level]
Decimal 254 202 245 160 [level]

Parameters Parameter Length Description

level 1 Sets the data lock level

Description

Paranoia allows you to lock the module from displaying information, as well as enables the protection of the filesystem and module settings.

Each bit corresponds corresponds to a different lock level, while sending a zero will unlock your display as the following tables explains:

Bit	Data Lock Level	Description
0-2	Reserved	Should be left 0
3	Communication	When this bit is set (1) the
	Speed Lock	Baud Rate and I ² C Slave
		address are locked
4	Setting Lock	When this bit is set (1)
		the display settings such
		as backlight, contrast and
		GPO settings are locked.
		(Internal EEPROM)
5	Reserved	Should be left 0
6	Command Lock	When this bit is set (1) all
		commands but commands
		202/203 are locked. (cmd
		lock)
7	Display Lock	When this bit is set (1) the
		module is locked from dis-
		playing any new informa-
		tion. (text lock)

NOTES

- Sending a new data lock level will override the previous data lock level.
- Data lock levels may be combined.

Remembered Default Examples Always

Hex		Dec	Binary	Description
0x0)	0	0	Unlock
0x50)	80	01010000	Setting and Command Lock

11.4 Set and Save Data Lock

Syntax Hexadecimal 0xFE 0xCB 0xF5 0xA0 [level]

Decimal 254 203 245 160 [level]

Parameters Parameter Length Description

level 1 Sets the data lock level

Description This command will set and save the data lock level. See the Data Lock

section for more information.

Remembered Always Default 0

11.5 Write Customer Data

Syntax Hexadecimal 0xFE 0x34 [data]

Decimal 254 52 [data] ASCII 254 "4" [data]

Parameters Parameter Length Description

data 16 Writes the customer data

Description Writes the customer Data. 16 Bytes of data can be saved in non-volatile

memory.

Remembered No

11.6 Read Customer Data

Syntax Hexadecimal 0xFE 0x35

Decimal 254 53 ASCII 254 "5"

Description Reads whatever was written by Write Customer Data.

Remembered No

12 Miscellaneous

12.1 Introduction

This chapter covers the 'Report Version Number' and 'Read Module Type' commands. These commands can be particularly useful to find out more information about the display module before contacting technical support.

12.2 Read Version Number

Syntax Hexadecimal 0xFE 0x36

Decimal 254 54 ASCII 254 "6"

Description This command will return a byte representing the version of the module,

see the following table as an example:

Hex Value	Version Number
0x19	Version 1.9
0x57	Version 5.7

Remembered No

12.3 Read Module Type

Syntax Hexadecimal 0xFE 0x37

Decimal 254 55 ASCII 254 "7"

This command will return a hex value corresponding to the model number of the module see the following table:

Hex	Product ID	Hex	Product ID
1	LCD0821	2	LCD2021
5	LCD2041	6	LCD4021
7	LCD4041	8	LK202-25
9	LK204-25	A	LK404-55
В	VFD2021	С	VFD2041
D	VFD4021	E	VK202-25
F	VK204-25	10	GLC12232
13	GLC24064	14	Unused
15	GLK24064-25	16	Unused
21	Unused	22	GLK12232-25
23	Unused	24	GLK12232-25-SM
25	GLK24064-16-1U-USB	26	GLK24064-16-1U
27	GLK19264-7T-1U-USB	28	GLK12232-16
29	GLK12232-16-SM	2A	GLK19264-7T-1U
2B	LK204-7T-1U	2C	LK204-7T-1U-USB
31	LK404-AT	32	MOS-AV-162A
33	LK402-12	34	LK162-12
35	LK204-25PC	36	LK202-24-USB
37	VK202-24-USB	38	LK204-24-USB
39	VK204-24-USB	3A	PK162-12
3B	VK162-12	3C	MOS-AP-162A
3D	PK202-25	3E	MOS-AL-162A
3F	MOS-AL-202A	40	MOS-AV-202A
41	MOS-AP-202A	42	PK202-24-USB
43	MOS-AL-082	44	MOS-AL-204
45	MOS-AV-204	46	MOS-AL-402
47	MOS-AV-402	48	LK082-12
49	VK402-12	4A	VK404-55
4B	LK402-25	4C	VK402-25
4D	PK204-25	4 E	Unused
4F	MOS	50	MOI
51	XBoard-S	52	XBoard-I
53	MOU	54	XBoard-U
55	LK202-25-USB	56	VK202-25-USB
57	LK204-25-USB	58	VK204-25-USB
5B	LK162-12-TC	5C	Unused
71	Unused	72	GLK240128-25
73	LK404-25	74	VK404-25
77	Unused	78	GLT320240
79	GLT480282	7A	GLT240128

Remembered

No

13 Command Summary

13.1 Communications

Description	Syntax		Page
Changing the I ² C Slave	Hexadecimal	0xFE 0x33 [adr]	17
Address	Decimal	254 51 [adr]	
	ASCII	254 "3" [adr]	
Changing the Baud Rate	Hexadecimal	0xFE 0x39 [speed]	17
	Decimal	254 57 [speed]	
	ASCII	254 "9" [speed]	
Setting a Non-Standard	Hexadecimal	0xFE 0xA4 [speed]	18
Baud Rate	Decimal	254 164 [speed]	

13.2 Text

Description	Syntax		Page
Auto Scroll On	Hexadecimal	0xFE 0x51	20
	Decimal	254 81	
	ASCII	254 "Q"	
Auto Scroll Off	Hexadecimal	0xFE 0x52	21
	Decimal	254 82	
	ASCII	254 "R"	
Clear Screen	Hexadecimal	0xFE 0x58	21
	Decimal	254 88	
	ASCII	254 "X"	
Changing the Startup	Hexadecimal	0xFE 0x40	21
Screen	Decimal	254 64	
	ASCII	254 "@"	
Set Auto Line Wrap On	Hexadecimal	0xFE 0x43	22
	Decimal	254 67	
	ASCII	254 "C"	
Set Auto Line Wrap Off	Hexadecimal	0xFE 0x44	22
	Decimal	254 68	
	ASCII	254 "D"	
Set Cursor Position	Hexadecimal	0xFE 0x47 [col] [row]	22
	Decimal	254 71 [col] [row]	
	ASCII	254 "G" [col] [row]	
Go Home	Hexadecimal	0xFE 0x48	23
	Decimal	254 72	
	ASCII	254 "H"	

Description	Syntax		Page
Move Cursor Back	Hexadecimal	0xFE 0x4C	23
	Decimal	254 76	
	ASCII	254 "L"	
Move Cursor Forward	Hexadecimal	0xFE 0x4D	23
	Decimal	254 77	
	ASCII	254 "M"	
Underline Cursor On	Hexadecimal	0xFE 0x4A	24
	Decimal	254 74	
	ASCII	254 "J"	
Underline Cursor Off	Hexadecimal	0xFE 0x4B	24
	Decimal	254 75	
	ASCII	254 "K"	
Blinking Block Cursor	Hexadecimal	0xFE 0x53	24
On	Decimal	254 83	
	ASCII	254 "S"	
Blinking Block Cursor	Hexadecimal	0xFE 0x54	24
Off	Decimal	254 84	
	ASCII	254 "T"	

13.3 Special Characters

Description	Syntax		Page
Creating a Custom	Hexadecimal	0xFE 0x4E [refID] [data]	25
Character	Decimal	254 78 [refID] [data]	
	ASCII	254 "N" [refID] [data]	
Saving Custom	Hexadecimal	0xFE 0xC1 [Bank] [ID] [Data]	26
Characters	Decimal	254 193 [Bank] [ID] [Data]	
Loading Custom	Hexadecimal	0xFE 0xC0 [Bank]	27
Characters	Decimal	254 192 [Bank]	
Save Startup Screen	Hexadecimal	0xFE 0xC2 [refID] [data]	27
Custom Characters	Decimal	254 194 [refID] [data]	
Initialize Medium	Hexadecimal	0xFE 0x6D	28
Number	Decimal	254 109	
	ASCII	254 "m"	
Place Medium Numbers	Hexadecimal	0xFE 0x6F [Row] [Col] [Digit]	28
	Decimal	254 111 [Row] [Col] [Digit]	
	ASCII	254 "o" [Row] [Col] [Digit]	
Initialize Large Numbers	Hexadecimal	0xFE 0x6E	29
	Decimal	254 110	
	ASCII	254 "n"	
Place Large Number	Hexadecimal	0xFE 0x23 [Col] [Digit]	29
-	Decimal	254 35 [Col] [Digit]	
	ASCII	254 "#" [Col] [Digit]	

Description	Syntax		Page
Initialize Horizontal Bar	Hexadecimal	0xFE 0x68	29
	Decimal	254 104	
	ASCII	254 "h"	
Place Horizontal Bar	Hexadecimal	0xFE 0x7C [Col] [Row] [Dir] [Length]	30
Graph	Decimal	254 124 [Col] [Row] [Dir] [Length]	
_	ASCII	254 " " [Col] [Row] [Dir] [Length]	
Initialize Narrow Vertical	Hexadecimal	0xFE 0x73	30
Bar	Decimal	254 115	
	ASCII	254 "s"	
Initialize Wide Vertical	Hexadecimal	0xFE 0x76	30
Bar	Decimal	254 118	
	ASCII	254 "v"	
Place Vertical Bar	Hexadecimal	0xFE 0x3D [Column] [Length]	31
	Decimal	254 61 [Column] [Length]	
	ASCII	254 "=" [Column] [Length]	

13.4 General Purpose Output

Description	Syntax		Page
General Purpose Output	Hexadecimal	0xFE 0x56 [Num]	32
Off	Decimal	254 86 [Num]	
	ASCII	254 "V" [Num]	
General Purpose Output	Hexadecimal	0xFE 0x57 [Num]	32
On	Decimal	254 87 [Num]	
	ASCII	254 "W" [Num]	
Set Startup GPO state	Hexadecimal	0xFE 0xC3 [Num] [state]	32
_	Decimal	254 195 [Num] [state]	

13.5 Dallas 1-Wire

Description	Syntax	Page
Search for a 1-Wire	Hexadecimal	0xFE 0xC8 0x2 33
Device	Decimal	254 200 2
Dallas 1-Wire	Hexadecimal	0xFE 0xC8 0x1 [flags] [SndBits] [RevBits] [Data]
Transaction	Decimal	254 200 1 [flags] [SndBits] [RcvBits] [Data]

13.6 Keypad

Description	Syntax		Page
Auto Transmit Key	Hexadecimal	0xFE 0x41	36
Presses On	Decimal	254 65	
	ASCII	254 "A"	
Auto Transmit Key	Hexadecimal	0xFE 0x4F	36
Presses Off	Decimal	254 79	
	ASCII	254 "O"	
Poll Key Press	Hexadecimal	0xFE 0x26	37
	Decimal	254 38	
	ASCII	254 "&"	
Clear Key Buffer	Hexadecimal	0xFE 0x45	37
	Decimal	254 69	
	ASCII	254 "E"	
Set Debounce Time	Hexadecimal	0xFE 0x55 [time]	38
	Decimal	254 85 [time]	
	ASCII	254 "U" [time]	
Set Auto Repeat Mode	Hexadecimal	0xFE 0x7E [mode]	38
	Decimal	254 126 [mode]	
	ASCII	254 "~" [mode]	
Auto Repeat Mode Off	Hexadecimal	0xFE 0x60	39
	Decimal	254 96	
	ASCII	254 "'"	
Assign Keypad Codes	Hexadecimal	0xFE 0xD5 [KDown] [KUp]	39
	Decimal	254 213 [KDown] [KUp]	

13.7 Display Functions

Description	Syntax		Page
Display On	Hexadecimal	0xFE 0x42 [min]	40
	Decimal	254 66 [min]	
	ASCII	254 "B" [min]	
Display Off	Hexadecimal	0xFE 0x46	41
	Decimal	254 70	
	ASCII	254 "F"	
Set Brightness	Hexadecimal	0xFE 0x99 [brightness]	41
_	Decimal	254 153 [brightness]	
Set and Save Brightness	Hexadecimal	0xFE 0x98 [brightness]	41
	Decimal	254 152 [brightness]	
Set Contrast	Hexadecimal	0xFE 0x50 [contrast]	41
	Decimal	254 80 [contrast]	
	ASCII	254 "P" [contrast]	
Set and Save Contrast	Hexadecimal	0xFE 0x91 [contrast]	42
	Decimal	254 145 [contrast]	

13.8 Data Security

Description	Syntax		Page
Set Remember	Hexadecimal	0xFE 0x93 [switch]	43
	Decimal	254 147 [switch]	
Data Lock	Hexadecimal	0xFE 0xCA 0xF5 0xA0 [level]	44
	Decimal	254 202 245 160 [level]	
Set and Save Data Lock	Hexadecimal	0xFE 0xCB 0xF5 0xA0 [level]	45
	Decimal	254 203 245 160 [level]	
Write Customer Data	Hexadecimal	0xFE 0x34 [data]	45
	Decimal	254 52 [data]	
	ASCII	254 "4" [data]	
Read Customer Data	Hexadecimal	0xFE 0x35	45
	Decimal	254 53	
	ASCII	254 "5"	

13.9 Miscellaneous

Description	Syntax		Page
Read Version Number	Hexadecimal	0xFE 0x36	46
	Decimal	254 54	
	ASCII	254 "6"	
Read Module Type	Hexadecimal	0xFE 0x37	46
71	Decimal	254 55	
	ASCII	254 "7"	

13.10 Command By Number

Command	Descrip	tion Page		
Hex	Dec	ASCII		
0x23	35	"#"	Place Large Number	29
0x26	38	"&"	Poll Key Press	37
0x33	51	"3"	Changing the I ² C Slave Address	17
0x34	52	"4"	Write Customer Data	45
0x35	53	"5"	Read Customer Data	45
0x36	54	"6"	Read Version Number	46
0x37	55	"7"	Read Module Type	46
0x39	57	"9"	Changing the Baud Rate	17
0x3D	61	"="	Place Vertical Bar	31
0x40	64	"@"	Changing the Startup Screen	21
0x41	65	"A"	Auto Transmit Key Presses On	36
0x42	66	"B"	Display On	40

Command	Description	on Page		
Hex	Dec	ASCII		
0x43	67	"C"	Set Auto Line Wrap On	22
0x44	68	"D"	Set Auto Line Wrap Off	22
0x45	69	"E"	Clear Key Buffer	37
0x46	70	"F"	Display Off	41
0x47	71	"G"	Set Cursor Position	22
0x48	72	"H"	Go Home	23
0x4A	74	"J"	Underline Cursor On	24
0x4B	75	"K"	Underline Cursor Off	24
0x4C	76	"L"	Move Cursor Back	23
0x4D	77	"M"	Move Cursor Forward	23
0x4E	78	"N"	Creating a Custom Character	25
0x4F	79	"O"	Auto Transmit Key Presses Off	36
0x50	80	"P"	Set Contrast	41
0x51	81	"Q"	Auto Scroll On	20
0x52	82	"R"	Auto Scroll Off	21
0x53	83	"S"	Blinking Block Cursor On	24
0x54	84	"T"	Blinking Block Cursor Off	24
0x55	85	"U"	Set Debounce Time	38
0x56	86	"V"	General Purpose Output Off	32
0x57	87	"W"	General Purpose Output On	32
0x58	88	"X"	Clear Screen	21
0x60	96	""	Auto Repeat Mode Off	39
0x68	104	"h"	Initialize Horizontal Bar	29
0x6D	109	"m"	Initialize Medium Number	28
0x6E	110	"n"	Initialize Large Numbers	29
0x6F	111	"o"	Place Medium Numbers	28
0x73	115	"s"	Initialize Narrow Vertical Bar	30
0x76	118	"v"	Initialize Wide Vertical Bar	30
0x7C	124	"["	Place Horizontal Bar Graph	30
0x7E	126	"~"	Set Auto Repeat Mode	38
0x91	145		Set and Save Contrast	42
0x93	147		Set Remember	43
0x98	152		Set and Save Brightness	41
0x99	153		Set Brightness	41
0xA4	164		Setting a Non-Standard Baud Rate	18
0xC0	192		Loading Custom Characters	27
0xC1	193		Saving Custom Characters	26
0xC2	194		Save Startup Screen Custom	27
			Characters	
0xC3	195		Set Startup GPO state	32
0xC8	200		Dallas 1-Wire Transaction	34
0xCA	202		Data Lock	44

14 Appendix

14.1 Specifications

14.1.1 Environmental

Table 69: Environmental Specifications

	Standard Temperature	Extended Temperature	
Operating Temperature	0° C to $+50^{\circ}$ C	-20°C to +70°C	
Storage Temperature	-20° C to $+70^{\circ}$ C	-30°C to +80°C	
Operating Relative Humidity	90% max non-condensing		
Vibration (Operating)	4.9 m/s ² XYZ directions		
Vibration (Non-Operating)	19.6 m/s ² XYZ directions		
Shock (Operating)	29.4 m/s ² XYZ directions		
Shock (Non-Operating)	490 m/s ² XYZ directions		

14.1.2 Electrical

Table 70: Electrical Specifications

	Standard	Wide Voltage (V)	S	
			Switching Power Supply (VPT)	
Supply Voltage	+5Vdc ±0.25V	+9V to +15V	+9V to +35V	
Minimum Current	40 mA typical			
Backlight On (YG & IY)	add 135mA (175mA) typical			
Backlight On (R)	add 150mA (190mA) typical			
Backlight On (GW & WB)	add 70mA (110mA) typical			

14.2 Optical Characteristics

Table 71: Optical Characteristics

Character x Lines	20 columns x 2 rows
Module Size	98.00 mm x 60.00 mm x 30.63 mm
Character Size	3.20 mm x 5.55 mm
Display Size	76.30 mm x 25.00 mm
LED Backlight Half-Life (YG & IY)	50, 000 hours typical
LED Backlight Half-Life (R)	20,000 hours typical
LED Backlight Half-Life (GW & WB)	10, 000 hours typical

NOTE To prolong life, it is recommended that the backlight be turned off when the display is not in use.

14.3 Physical Layout

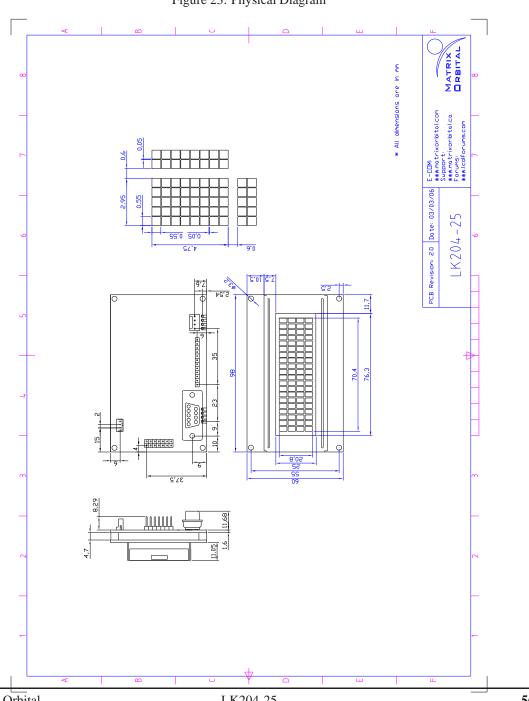


Figure 23: Physical Diagram

LK204-25 56 Matrix Orbital

14.4 Ordering Information

L	K	20	4	-25	-GW	-VPT	-E
1	2	3	4	5	6	7	8

Table 72: Part Numbering Scheme

#	Description	Options	
1	Screen Type	L: Liquid Crystal Display*	
2	Input Type	K: External Keypad	
3	Width	20: Twenty Character Columns	
4	Height	4: Four Character Rows	
5	Keypad Buttons	-25: Twenty-Five Key Input Maximum	
		NP: Standard Grey/Yellow-Green	
		GW: Grey/White	
6	Color (Text/Background)	WB: White/Blue	
		R: Red/Black	
		IY: Yellow/Black	
		NP: Standard (4.75-5.25V)	
7	Input Voltage	-V: Extended Voltage(9.00-15.0V)	
		-VPT: Extended Voltage with ESPS (9.00-35.0V)	
8	Tomporatura	NP: Standard (0°C to +50°C)	
0	Temperature	-E: Extended Temperature (-20°C to +70°C)	

Table 73: Part Options

NOTE * Also available with a Vacuum Florescent Display in the VK204-25 model

14.5 Definitions

 ${f E}\;$ Extended Temperature (-20C to 70C)

VPT Wide Voltage with Efficient Switching Power Supply (+9 to +35Vdc)

V Wide Voltage (+9 to +15Vdc)

GW Grey Text / White Background

WB White Text / Blue Background

R Inverse Red

IY Inverse Yellow

14.6 Contacting Matrix Orbital

Telephone

Sales: 1(403)229-2737 Support: 1(403)204-3750

On The Web

Sales: http://www.MatrixOrbital.com Support: http://www.MatrixOrbital.ca Forums: http://www.lcdforums.com

14.7 Revision History

Table 74: Revision History

Revision	Description	Author
2.0	Initial Manual	Matrix Orbital
2.1	Updated Backlight Life	Clark

Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

Matrix Orbital:

LK204-25-E LK204-25-VPT LK204-25-GW-V LK204-25-GW-VPT LK204-25-IY-E LK204-25-IY-V LK204-25-IY-VPT LK204-25-R-E LK204-25-R-V LK204-25-R-VPT LK204-25-WB-E LK204-25-WB-V LK204-25-WB-VPT LK204-25-V-E LK204-25-VPT-E LK204-25-WB-VPT-E LK204-25-GW-V-E LK204-25-GW-VPT-E LK204-25-R-V-E LK204-25-R-V-E LK204-25-FA LK204-25-FW LK204-25-FG LK204-25-GW-E LK204-25-FB